

TURN Reference Guide RhinoCAM-TURN 2025

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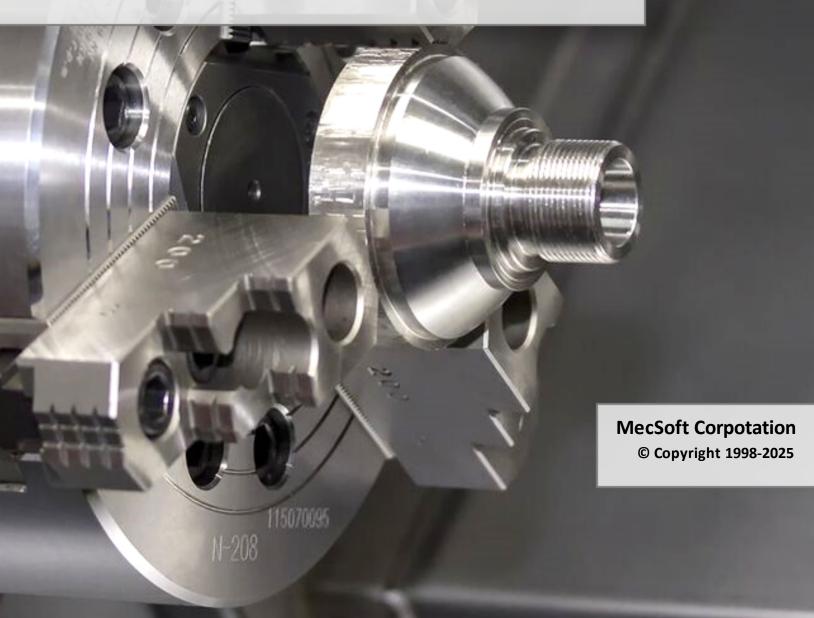


Table of Contents

weicom	ne to I URN	1
1	1 Features of the TURN module	7
:	2 Understanding the TURN Module	8
;	3 Programming Work-flow	10
	4 Post-Processing	12
Quick S	Start	13
Resour	ce Guide	15
Key Co	ncepts	16
	1 Turning Coordinate System	16
	2 TURN Module Default View	16
;	3 Part Geometry	17
	Orient Part Geometry	19
	How to Define Part Geometry	25
User Int	terface	28
1	1 RhinoCAM Menu Item	28
:	2 TURN Browsers	29
;	3 Machining Browser (Mops)	29
	Browser Toggle Tabs	
	Program tab Simulate tab	
,	4 Machining Objects (Mobs) Browser	
	Tools tab	
	K-Bases tab	
;	5 Right-Click Commands	41
	6 Docking Browsers	44
•	7 CAM Preferences	45
	Geometry	46
	Stock	
	Cutting Tools	
	Feeds & Speeds	
	Machining Toolpath	
	Simulation	
	User Interface	
	Post Processor	62
	Licensing	65

Overviev	v of Machining Methods	68
1	Turning Operations	68
	Roughing	69
	Finishing	70
	Groove Roughing	71
	Groove Finishing	72
	Follow Curve	73
	Threading	74
	Parting Off	
2	Drilling (Hole Making) Operations	76
Creating	Machining Operations	80
1	Lathe	80
	Coordinate System	80
	Machine Setup	83
2	Geometry	85
	Part Geometry	85
	Part Geometry Types	
	Orient Part	
	Stock Geometry	93
	Cylinder Stock	93
	Part Cylinder Stock	
	Offset Stock	97
	Revolve Stock	
	Stock from Selection	
	Export Stock as STL	
	Delete Stock	
•	Remove Simulations	
3	· · · ·	
4	Align Part and Stock Models	
5	Material	108
6	Work Zero	110
7	Machining Features	116
	Avoid Sections	
8	Tool	118
	Create/Select Tools	118
	Load Tool Library	135
	Add Tool to Library	
	Select Tools from Library	
	Save Tool Library	
	List Tools	
•	Cutter Compensation	
9		
	Load from File	
10	Clearance Plane	
11	Knowledge Base	155
	Create Knowledge Base	
	Load Knowledge Base	157

	Apply a Knowledge Base	158
12	Create Miscellaneous Operations	161
	Mop Set	162
	Machine Control	163
13	Tools and Utilities	166
	Save As Defaults	167
	Post Process Generator	170
	Export to VCP	171
Creating	Turning Operations	173
1	Roughing	173
	Global Parameters	175
	Turn Roughing Options	180
	Entry/Exit	182
	Tool	
	Feeds & Speeds	
•	Clearance	
2	Finishing	
	Global Parameters	
	Finishing Parameters	
	Entry/Exit	
	Tool Feeds & Speeds	
	Clearance	
3		
J		
	Global Parameters Roughing Parameters	
	Entry/Exit	
	Tool	
	Feeds & Speeds	
	Clearance	
4	Groove Finishing	227
	Global Parameters	228
	Finishing Parameters	
	Entry/Exit	234
	Tool	235
	Feeds & Speeds	237
	Clearance	
5	Follow Curve	243
	Global Parameters	244
	Follow Curve Parameters	
	Entry/Exit	
	Tool	
	Feeds & Speeds	
e	Threading	
0	•	
	Thread Cut Parameters	
	Thread Cut Parameters	
	Feeds & Speeds	
	Clearance	

7	Parting Off	274
	Part Off Parameters	276
	Entry/Exit	
	Tool Feeds & Speeds	
	Clearance	
Creating	Hole Making Operations	288
•	Drilling	
1	· ·	
	Tool Feeds & Speeds	
	Clearance	
	Cut Parameters	298
2	Tapping	301
	Tool	
	Feeds & Speeds	
	Clearance Cut Parameters	
3	Boring	
_	Tool	
	Feeds & Speeds	
	Clearance	322
_	Cut Parameters	
4	Reverse Boring	
	Tool	
	Feeds & Speeds Clearance	
	Cut Parameters	
Editing N	lachining Operations	340
_	Editing Operations Associatively	340
2	Toolpath Viewer	
3	Copy & Paste Operations	
	Clone Operation	
5	Delete Operations	
6	Rename Operations	
7	Suppress Operations	354
8	Delete Dirty Mops	355
9	Suppress Dirty Mops	357
10	Unsuppress Dirty Mops	359
11	Machining Information	360
12	Shop Documentation	361
13	Machining Operation Properties	364
Simulatir	ng Machining Operations	368
	Tool Animation	372

2	2 Cut Material Simulation	375
3	3 Material Texture in Simulation	377
4	4 Part/Stock Compare	379
Post Pro	ocessing Machining Operations	382
1	1 Set Post Options	387
	Welcome	389
	Quick Start	390
	Resource Guide	392
	Good Things to Know	393
	Use Legacy Post	405
	Dialogs	406
	Post Processor File Browser	406
	PPG Editor	407
	Variable List Dialog	409
	PPG Editor	410
	General	410
	StartEnd	414
	Tool Change	415
	Setup	418
	Spindle	419
	Feed Rate	421
	Motion	424
	Circle	426
	Helical/Spiral	
	Multi Axis Motion	
	Cutter Compensation	
	Cut Motion Start/End	
	Cycles	
	Miscellaneous	
	Variables	
	Macros	
	Macros	
	How to edit Macros	
	Use Programmable Post	
	Selecting a Programmable Post	
	Writing Scrips Post Events	
	Post Event List	
	Post Variables List.	
	Example Script	
	Find More Resources	
Archivin	ng Machining Operations	476
Find Mo	ore Resources	477
	Index	478

Welcome to TURN



MILL Module 2025

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The RhinoCAM-TURN Module is a unique turning product that is used for offline programming of 2 Axis CNC Lathes. This product is a module of RhinoCAM, which is completely integrated inside of Rhino. This integration allows for the seamless generation of toolpaths and cut material simulation/verifications inside of Rhino for programming turning machines.

For purposes of brevity, RhinoCAM will be referred to as TURN in all subsequent references. Also, Rhino refers to both Rhinoceros 7 or Rhino 8.

The RhinoCAM-TURN module also comes with numerous post-processors to output the programmed G-code to some of the most popular CNC machine controllers on the market today. Additionally, the RhinoCAM-TURN module also includes a post-processor generator that has the capability to configure entirely new post-processors. These features make programming CNC Turning easy and affordable.

The RhinoCAM-TURN module supports turning and hole making operations such as Turn Roughing, Turn Finishing, Groove Roughing, Groove Finishing, Threading, Parting and Hole making operations such as Drilling, Tapping, Boring, Reverse Boring and Threading.

1.1 Features of the TURN module

The list below summarizes the toolpath generation features found in the TURN module.

Data Import:
Supports file formats that can be imported in Rhinoceros
Turn Machining Methods:
Roughing, Finishing, Groove Roughing, Groove Finishing, Follow Curve, Threading and Parting.
Hole Machining Methods:
Drilling, Tapping, Boring, Reverse Boring

Tool Types: Turning Inserts - Diamond, Triangular, Circular, Trigon, Parallelogram, Groove. Hole Making Tools - Drill, CenterDrill, Reamer, Tap, Bore, ReverseBore. User customizable tool library: Create and save tools to library. Saves feeds and speeds to tool library. Feeds and Speeds: Customizable feeds and speeds table, Feeds and Speeds calculator Cut Material Simulation: Fast and fully integrated Material Cutting Simulation. Create true 3D in-process stock model. Advanced cut material simulation includes tool holder collision and part stock comparison. Post-Processors: Standard set of post-processors bundled with the product. Choose from our large set of standard post processors. Post-Processor Generator: Customize your Post Processor or create your own Post Processor from scratch. This

1.2 Understanding the TURN Module

post processor generator supports 3 axis posts.

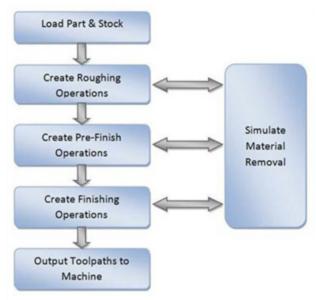
The manufacturing process aims to successively reduce material from the stock model until it reaches the final shape of the designed part model. To accomplish this, the machinist or programmer utilizes a 3-part machining strategy.

3-Part Machining Strategy

- 1. A typical machining strategy employed in the manufacturing industry is to use larger cutters to perform bulk removal of material early on in the manufacturing process. These operations are called roughing operations.
- 2. This is then followed by operations employing successively smaller cutters removing proportionately smaller amounts of material from the stock model. This is done until the part has a uniform amount of stock left. These operations are called pre-finishing operations.
- 3. This is then followed by finish operations. Here the uniform stock remaining on the part is removed by using a small cutter removing a constant amount

of material with every motion to produce the net shape. The standard work flow of TURN Module mimics this process and can be represented by the flow chart shown below.

Basic TURN Module Work Flow Chart



TURN Module Work Flow Chart

Basic TURN Module Work Flow Steps

- Part geometry is imported into TURN Module via the various data interfaces provided in Rhino. A stock model representing the raw stock from which the part needs to be manufactured can then either be created using the various tools provided in TURN Module or imported.
- 2. You then determine the machining strategy to be used in manufacturing the part. This can be done by loading a previously saved manufacturing operation sequence or by creating a new one. This manufacturing strategy is represented by a sequence of machining operations in Turning.
 - To create a new machining strategy, simply selects the tools and the machining operations in sequence and generates toolpaths. The system automatically records this sequence. This record can be archived as an operation list that can be retrieved for later use.
- 3. You can also simulate material removal to visualize how the stock model will look at any time during the process. This provides valuable feedback that can help you choose the most appropriate machining strategy.
- 4. To create a new machining operation, select a tool followed by the type of toolpath to be created. You then selects the parameters to use for machining and then generates the toolpath.

- 5. Rough machining can be done by Roughing operations, using a turning tool with a relatively large nose radius. These rough operations can be followed by subsequent roughing operations, either using the same tool or a smaller tool.
- 6. Final finishing of the part can then be performed by using one or more Finishing operations. Finishing operations typically use tools with smaller nose radius so as to obtain a better surface finish and tighter tolerance levels.
- 7. Depending on the geometry of the part and/or machining operations desired, Groove Roughing, Groove Finishing, Follow Curve, Threading and the Hole-Making operations can be considered. After completing all the machining operations, the final part is cut off from the rest of the bar stock by using the Part-Off operation.
- 8. Once all of the operations are completed you can then go back and review the operation sequence, re-order operations if desired and output the toolpath for post-processing. The "Machining Operations Browser" can be used to manage these operations.

1.3 **Programming Work-flow**

Once the part is loaded, the typical work flow is reflected in the layout of the tabs of the Machining Browser window. The work flow is designed to allow you to work starting from the left most tab and ending at the right most tab. As each tab is accessed, a ribbon toolbar with functions specific to the tab chosen will be displayed just below the tab. The functions in each of the toolbars corresponding to each tab are also best accessed in order from left to right.

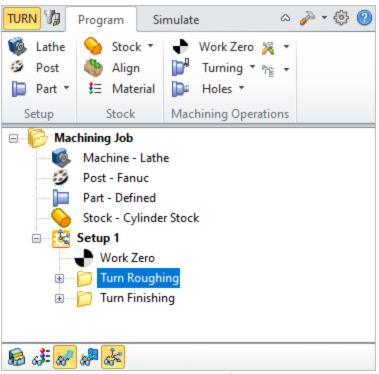
Thus you typically would start with the Program tab and access each of the buttons, optionally, in the toolbar that appears when this tab is selected in sequence from left to right. Once the setup functions are completed, you will then proceed to the Machining Operations group to commence programming the part. Once machining operations are completed you can simulate the operations by selecting the Simulate tab before finally sending the operation codes to the machine tool.



Step 1: Program Tab

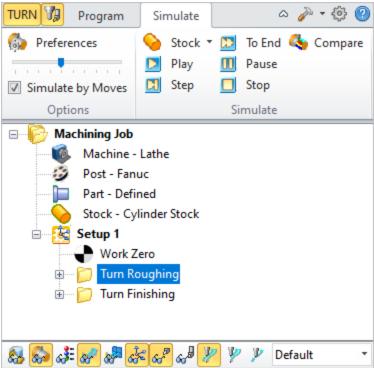
Define Machine Setup and Stock before programming

Create Machining Operations



Step 1: Program Tab

Step 2: Simulate machining operations



Step 2: Simulate machining operations

1.4 Post-Processing

Once the machining operations have been created and verified, they can be post processed to create G-code files. These G-code files can then be sent to the controller of the machine tool to drive the actual machine tool.

Quick Start

Quick Start Guides for each RhinoCAM module are available in both PDF and Video format. Refer to the following information to access these guides:

What's New!

What's New in RhinoCAM 2025

The Complete Quick Start Video Play List

Here is a link to the complete 2025 Video Play List

How to Access the Quick Start Guide Documents

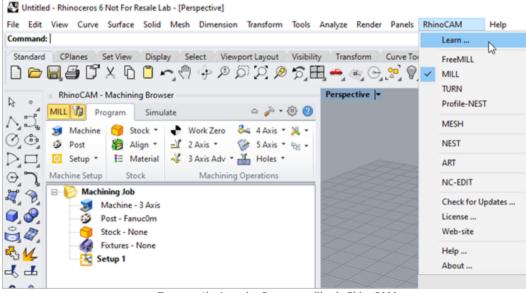
To help you quickly get started in working with each module, select one of the Help buttons located on the RhinoCAM Learning Resources dialog.

You will find:

- Quick Start Guides
- What's New documents
- Online Help links

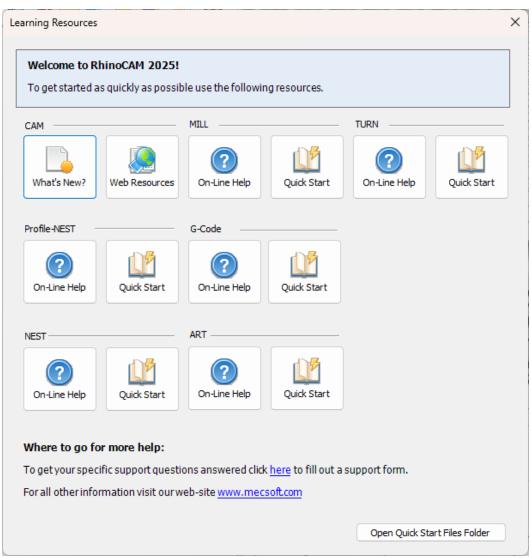
The Quick Start Guides will help you step through an example tutorial which will illustrate how to use the module. To access the Learning Resources dialog:

1. From the Rhino Main Menu, drop down the Main menu and select Learn ...



To access the Learning Resources dilog in RhinoCAM

- 2. Select a document from the Learning Resources dialog to get started using the module of your choice.
 - You can also select the Open Quick Start Files Folder button located at the bottom of the dialog to open the Quick Start folder where the source files (start and completed versions) are located.

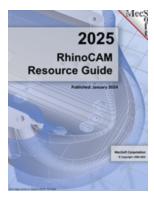


Learning Resources Dialog

Resource Guide

Download this PDF Guide for a list of the available RhinoCAM Resources.

2025 RhinoCAM Resource Guide



The 2025 RhinoCAM Resource Guide!

18 Pages

Lists PDF downloads and Online resources including Quick Start Guides, Reference Guides, Exercise Guides, Tutorials and More.

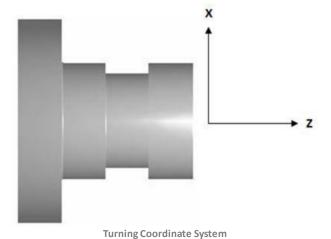
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Key Concepts

Before attempting to use the TURN Module there are a few key concepts that need to be understood. Some of these concepts will be familiar to lathe programmers and are explained here because they are essential for the proper use of TURN Module.

4.1 Turning Coordinate System

CNC turning centers use the Cartesian coordinate system for programmed coordinates but they are typically different from that used in milling. Turning centers follow the convention that axis of rotation that is aligned with the spindle is designated as the Z axis. Secondly the axis perpendicular to this axis along which the tool travels to cut into the stock is designated the X axis. Thus the part is rotated about the Z-axis of the lathe machine. Moving the tool along the Z-axis provides the direction of feed and moving it along the X-axis provides the depth of cut. This is shown below.



4.2 TURN Module Default View

TURN Module uses the Top view as the default view. The coordinate system of this top view is setup to be aligned with the turning coordinate system. That is the origin of the screen is located at the center of the screen and the Z axis goes from left to right and the X axis goes from bottom to top. This display setup is not typical in design systems where the Top view is aligned with the XY axes of the world coordinate system.

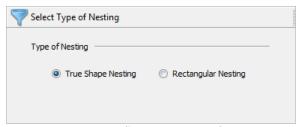
This view setup is used in TURN Module to allow the turning center programmer to work in turning center coordinates rather than in the XY coordinates of the design system. The world coordinate system in Rhino is in XY coordinates. All part modeling would still be done in XY coordinates. Loading the turn browser sets the turn coordinate system.

It should be noted that this convention might sometimes be disorienting for users who are used to visualizing their design parts in the normal XY aligned display rather than the ZX aligned display.

TURN Module's Top view is by default aligned with the ZX turning center coordinate system.

TURN Coordinate System Example

The picture below shows the turn coordinate system with the work zero set the right face of the part and the world coordinates at the origin. The **Red** arrow in the coordinate system represents X coordinate axis, **Blue** represents Z coordinate axis and **Green** represents Y coordinate axis. The WCS (World Coordinate System) is displayed the same way as MCS (Machine Coordinate System) with the length of the lines and arrows being smaller when compared to MCS.



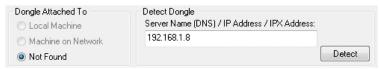
TURN Coordinate System Example

4.3 Part Geometry

TURN Module requires Solid, Surfaces, Polygon Meshes, Regions/Curves that defines the part geometry. Since all parts that can be created in a 2-Axis turning machine are solids of revolutions, it is enough to describe the profile that needs to be revolved to create this shape. The profile can be created in Rhino as a region or curve. TURN Module automatically creates the 2D silhouette of this part region when 3D Solid or Surface geometry is selected as TURN part geometry.

The First Quadrant, XY Plane Restriction

Furthermore, TURN Module places a further restriction that these part geometry need to be constrained to lie *only* in the first quadrant of the ZX plane in turn coordinate system. This would essentially be XY plane (Top view) in world coordinate system in Rhino.



The First Quadrant, XY Plane Restriction

If Geometry Falls Outside the First Quadrant of the XY Plane

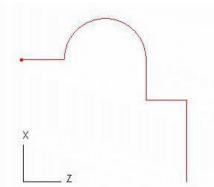
TURN Module will be unable to process a part region that fall outside the first quadrant. If the selected part region is outside the first quadrant, TURN Module will

trim this to the first quadrant.

If Geometry Falls Outside the First Quadrant of the XY Plane

Example of Curves Correctly Positioned

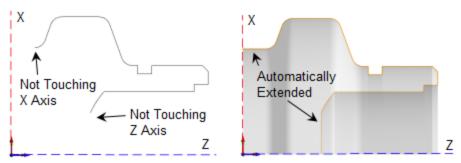
Example below shows curve region correctly positioned in the first ZX quadrant of the turn coordinate system touching both the X and Z axis. This would essentially be XY plane (Top view) in world coordinate system in Rhino.



Example of Curves Correctly Positioned

Example of Curves NOT Touching the X or Y Axis

Example below shows region not touching the X axis and/or Z axis



Part Profiles are Automatically Extended to the X and Z axis

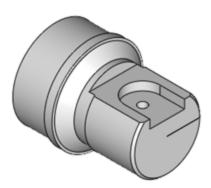
In such cases, TURN Module automatically extends the part regions to the X and Z axis when the regions do not touch the X axis and/or Z axis.

Part regions need to be constrained to the first quadrant of the ZX coordinate system.

Parts can be imported or can be created within VisualCAD using the Geometry creation and editing tools found under the CAD ribbon bar.

TURN Geometry with MILL features

You can select 3D geometry (surfaces, solids or meshes) for defining the TURN part that contains milling features. Such milling features are ignored while the turn part profile is being defined.

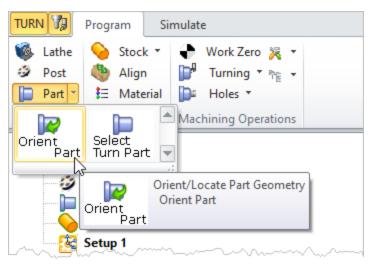


4.3.1 Orient Part Geometry



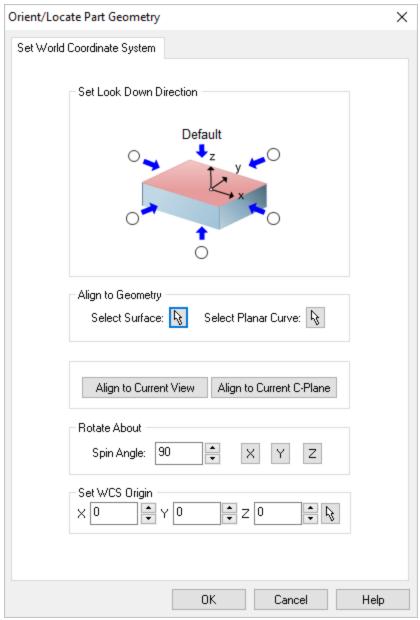
Once part geometry is loaded, you can use this command to change the orientation for turning. It can be invoked by selecting Part and Orient Part from Program tab under the Machining Browser. **Note**: This command changes the WCS orientation of your part. To change the MCS orientation use the Setup command.

Machining Browser: Part, Orient Part



Machining Browser: Part, Orient Part

Dialog Box: Orient/Locate Part Geometry



Dialog Box: Orient Geometry

Set Look Down Direction

Select the radio button representing the orthographic view of your part that you wish to machine. For example, select the right side radio button (on the positive X side in the dialog image) will rotate your part so that the positive X direction becomes the positive Z direction.

Align to

If your part is not aligned orthographically, you can use these options to align your part to selected geometry or active display element. Select from one of the options

that will orient the part that you wish to machine:

Select Surface

Choose the Pick button and then select a surface of your part to orient to. The part will be aligned such that the surface normal direction is aligned with the -Z axis.

Select Planar Curve

Choose the Pick button and then select a Planar Curve of your part to orient to. The part will be aligned such that the curve will be parallel to the XY plane (i.e., normal to the Z axis).

Align to Current View

Pick this button to align the part such as the Current View direction is aligned with the Z axis (i.e., you are looking in the -Z direction).

Align to Current C-Plane

Pick this button to align the part so that the Current C-Plane becomes parallel with the XY plane.

Rotate About

Use this option to Rotate About one of the principal XY or Z axis. Enter an angle and then select the button representing the axis you wish to Rotate About.

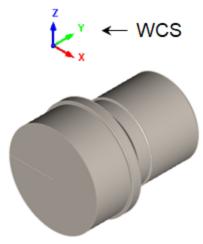
Set WCS Origin

You can also independently set the coordinate location for the WCS. So for example, you can orient the part normal to a surface and then also choose a point on the surface to become the new WCS origin. In this case the part would be oriented to the surface while the point on the surface remains at the WCS.

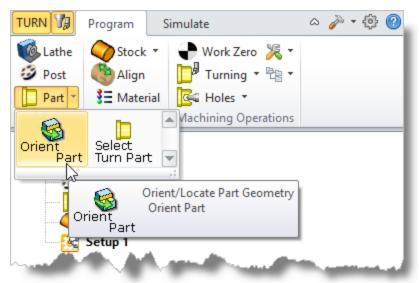
Example: Steps to orient your part for Turning

In TURN, the default rotational axis is along the X Axis of the World Coordinate System or WCS. Note: Once you select a direction and pick OK from the dialog, all of the geometry will be moved and/or rotated. In the example part shown below we want to orient the part so that the rotation axis is along the X Axis of the WCS. We also want the WCS origin to be located at the center of the back face of the part. Look at the steps below to see how it's done.

1. From the Program tab select Part and then Orient Part.



Incorrect Orientation

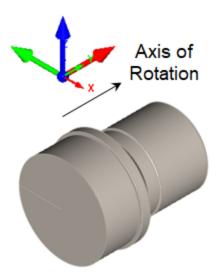


Machining Browser: Part, Orient Part

The dialog is displayed and the WCS is also displayed on the screen.

2. Under Rotate About, set the Spin Angle to 90 and then pick the Z button to rotate the WCS displayed on the screen. We want the X Axis of the WCS to point along the rotational axis of the part.

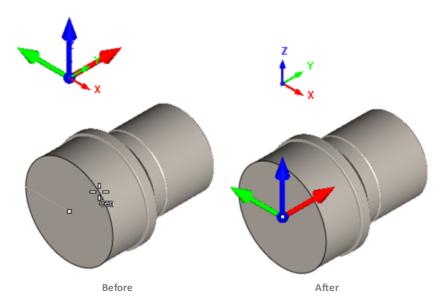




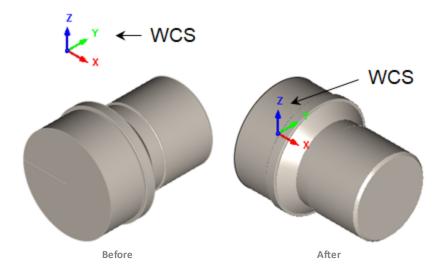
3. Now, let's locate the WCS origin. In the dialog under Set WCS Origin, select the Pick button.



4. Select the center point of the circular face of the back of the part. This is the face that will be mounted on the spindle of the lathe. When you select the point, the WCS triad is move to that point.



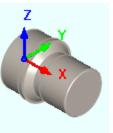
5. Now pick OK from the dialog and the part is oriented as desired.



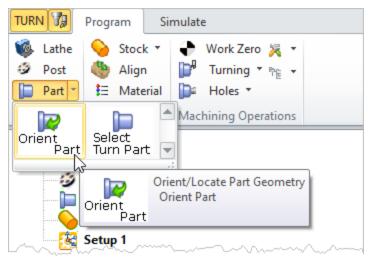
4.3.2 How to Define Part Geometry

Here are the basic steps to define part geometry:

BEFORE selecting part geometry for Turning, make sure it is oriented correctly. The image shows the correct orientation. The turning axis of the part is along the X Axis of the Word Coordinate System (WCS). Also, the WCS is located on the back rearmost face of the part. Orient Part can help you do this.

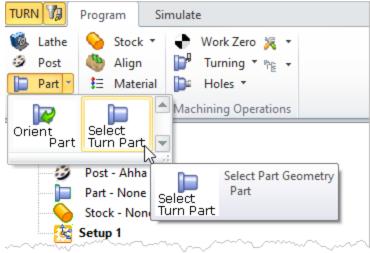


Orient your Part if needed.



Machining Browser: Part, Orient Part

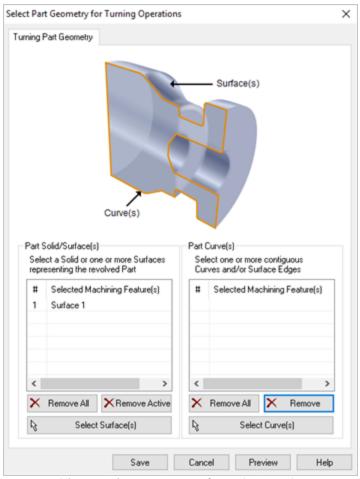
2. Select Turn Part in Machining Browser.



Select Part (Select Part Geometry) under Program tab in Machining Browser

3. Dialog Box: Select Part Geometry for Turning Operations

You can select surfaces or curves to define TURN part geometry.



Dialog Box: Select Part Geometry for Turning Operations

4. Define Part Geometry

There are two lists on this dialog. Use one or the other to define the Turn Part (not both).

If you have 3D geometry, pick the Select Surfaces button. You will be prompted to select part objects. Select the objects to define the part geometry and right-click or press Enter. If you only have a curve profile, make sure it is located in the positive XZ plane. See Part Geometry Types for more information.

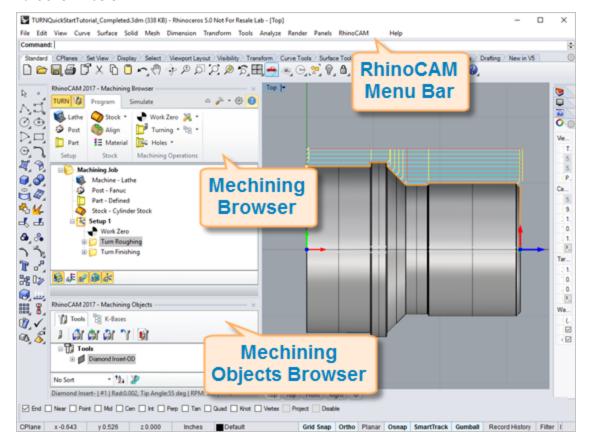
The selected geometry is listed under Selected Machining Feature(s) list.

5. Select Save

When the part is previewed, selecting Save defines the turn part geometry and displays Part-Defined under the machining browser.

User Interface

The RhinoCAM TURN Module adheres to the Windows standard for user interface design and integrated into the Rhino screen seamlessly. A screen shot of TURN Module running inside of Rhino is shown below:

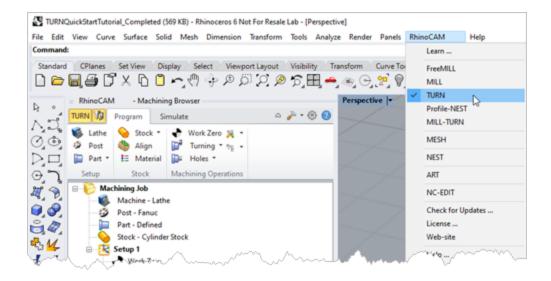


There are 3 main interface objects created when The RhinoCAM TURN Module is loaded.

- 1. RhinoCAM menu bar entry under Rhino menu bar.
- 2. Machining Browser window.
- 3. Machining Objects Browser window.

5.1 RhinoCAM Menu Item

When RhinoCAM is loaded it will add a menu bar item, titled RhinoCAM 2025 to the main Rhino menu bar. Selecting this menu bar item will create a drop down menu as shown below. To run TURN Module, select TURN from the RhinoCAM drop down menu. Selecting TURN toggles the display of the Turning Browser window from the Rhino user interface. If the FreeMILL, MILL, NEST or ART Browser is currently open selecting this will switch to the TURN Browser.

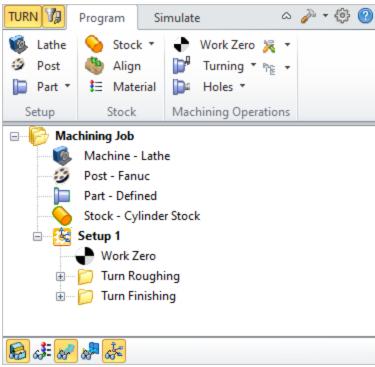


5.2 TURN Browsers

The Browser is a dock-able window that allows management of various entities or objects that can be created in TURN Module. There are 2 browsers in RhinoCAM – Machining Browser (Mops) and Machining Objects (Mobs).

5.3 Machining Browser (Mops)

The Machining Browser (Mops) has two main modes of operation represented by tabs at the top of the window. These are Program and Simulate. Each tabbed view also incorporates a ribbon toolbar at the top. These toolbars group all of the functions associated with the type of object in the tab.

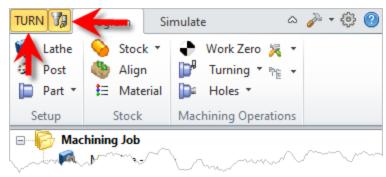


Machining Operations Browser

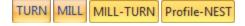
5.3.1 Browser Toggle Tabs

The tabs available on the Machining Browser allow you to toggle the display of both the Machining Browser and the Machining Objects Browser.

Browser Toggle Tabs



Locating the Browser Toggle Tabs



Selecting this tab toggles between the MILL, TURN, MILL-TURN and Profile-NEST Machining Browser.

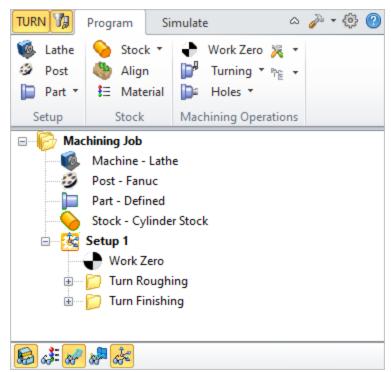


Select this tab to toggle the display of the Machining Objects Browser.

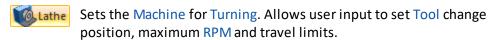
5.3.2 Program tab

Selecting the Program tab in the Mops Browser shows 3 groups of menus that provide access for specifying Machine, Stock and defining Machining Operations.

Machining Browser, Program Tab



Machine Setup Group





Part Provides access to commands that allow you to Orient and Define your Part geometry for TURN programming. See Orient Part Geometry and Part Geometry

Machining Stock Group



Allows you to create Stock geometry. User can also delete a Stock geometry by selecting Delete Stock.



Aligns stock model to part. This function is especially useful when the part model and the stock model are created without regard to their respective positional locations.



Allows you to select a material from the material list.

Machining Operations Group

This section allows user to create machining operations. TURN Module allows you to create multiple machining operations in a part file. This is a powerful feature that allows you to create an entire sequence of machining operations that is necessary to create the part model from the stock model. This set of operations can additionally be archived with the part file and retrieved at a later time with no loss of information.



Allows you to set the Work Coordinate zero (Origin) for the part being programmed.



Provides access to Turn Roughing & Finishing, Groove Roughing & Finishing, Threading and Parting Off machining methods



Provides access to Drilling, Tapping Boring and Reverse Boring Machining Methods



Allows you to create Machining operation sets, Machine Control Cycles.



Allows saving and loading of Machining operations to and from a knowledge base.



Provides access to G Code Editor and Post process generator.



Provides access to specify Color, User Interface, Machining, Simulation and Feeds Speeds Preferences.



Minimizes the Ribbon Bar.



Maximizes the Ribbon Bar.



Open On-line Help document.



The Status bar on the Program tab

The toolbar above status bar on the Program tab has the following controls



Turn on/off Stock Model



Turn on/off material Texture Visibility



Turn on/off toolpath display



Hidden Toolpath Visibility: Turn the hidden portions of toolpaths on/off.



Turns on/off of World Coordinate System display.



Turns on/off of Machine Coordinate System display.

The status bar displays the currently selected tool, spindle speed and cut feedrate.

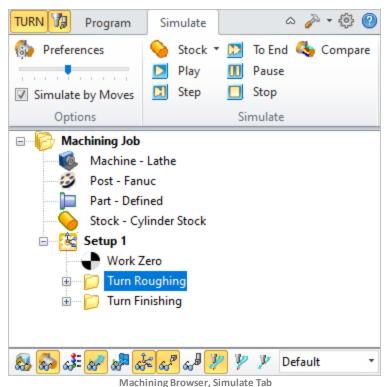
Turn Roughing | Diamond Insert1 | #1 | RPM: 500 | F: 20

5.3.3 Simulate tab

Selecting the Simulate tab allows you to run the material simulation and toolpath animation. This tab also provides controls to vary simulation speed and set simulation preferences.

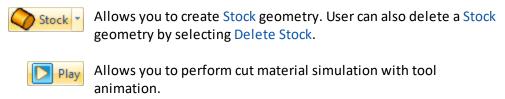


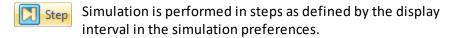
Show me the Machining Browser, Simulate Tab

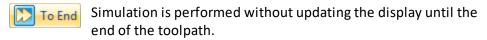


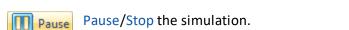
The following controls are available on the Simulate tab.

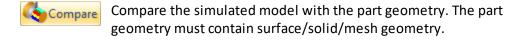
Simulate Tab Functions











Exits Simulation Mode. Pause simulation before exiting simulation mode.



Varies simulation speed.



Provides access to simulation preferences.



Switches from Simulate by Distance to Simulate by Motions. The toolbar above status bar on the stock tab had the following controls in addition to the controls listed under the Program tab.



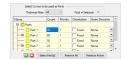
Turn on/off part model display during simulation.



Stock Model Visibility: Turn on/off stock model.

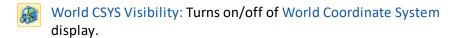


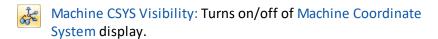
Material Texture Visibility: Turn on/off material texture visibility.

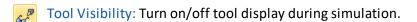


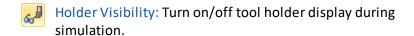
Toolpath Visibility: Turn on/off toolpath display.

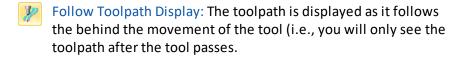


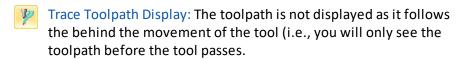














Segment Toolpath Display: The toolpath is only displayed for the segment that the tool is currently on.



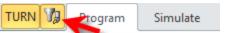
Simulation Display State: Use this to select the display state for the simulation. Select from Default, Tool, Mop or Texture. See Machining Operation Properties for setting unique simulation colors for each Mop (Machining Operation) in your Machining Job.

The Status bar displays the progress of the operation currently being simulated and number of GOTO motions.



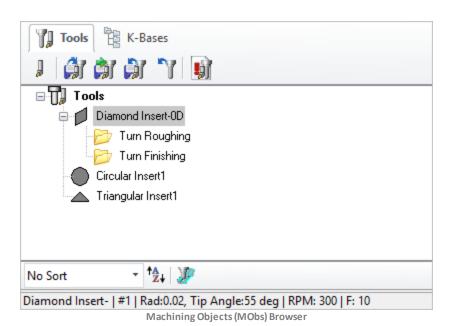
5.4 Machining Objects (Mobs) Browser

Machining Objects (Mobs) browser has two main modes of operation represented by tabs at the top of the window. These are Tools and K-Bases. Each tabbed view also incorporates a toolbar at the top. These toolbars group all of the functions associated with the type of object in the tab.



To toggle the display the Machining Objects Browser select Tools, Machining Objects Browser button located on the

Machining Browser just to the left of the Program tab.

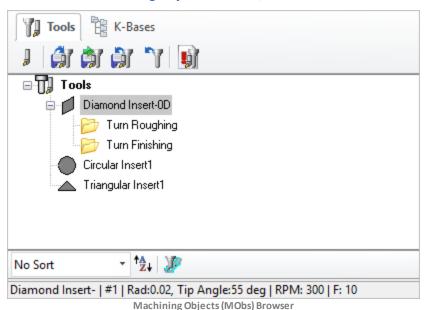


5.4.1 Tools tab

Selecting the Tools tab under the Machining Objects Browser brings up the tool manager. The tool manager lists all of the tools currently defined as well as the tools that are in use in machining operations. Users can edit a tool by double clicking the tool button in the browser. A tool can be

deleted by selecting the tool from the Tools browser, right click cut or use the delete key from the keyboard.

Show me the Machining Objects Browser, Tools Tab



RhinoCAM supports 2 types of tool library file format *.vkb and *.csv.

- *.vkb format saves and loads tools with the feeds and speeds assigned for each tool.
- *.csv format saves and loads tools without the feeds/speeds assigned for each tool.

Tools Tab Functions



Create/Edit Tools

This button brings up the tool dialog that enables the creation and saving of the desired tool. All turning inserts and drilling tools can be created here. Refer to the Tool section for a detailed description on creating tools and defining tool parameters.



Load Tool Library

The load tool library button enables the loading of a previously saved tool library. Refer to the following section for additional information - Load Tool Library



Select Tools from Library

The select tool library button enables users to select tools from a

previously saved tool library. Refer to the following section for additional information - Select Tools from Library



Save Tool Library

This button enables the created tools to be saved in a tool library file. The file can be saved in the desired directory and read in when required. Refer to the following section for additional information -Save Tool Library



Unload Tool Library

This button will unload the current Tool Library. Refer to the following section for additional information - Load Tool Library

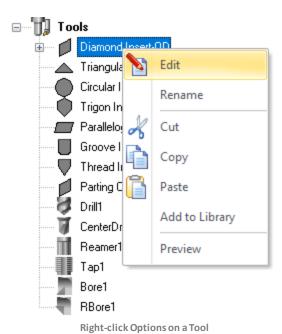


List Tools

The button brings up all the tool properties associated with the tools currently recorded in the current TURN Module session. Refer to the following section for additional information - List Tools

Right-click Options on Tools

You can right-click on a Tool listed in the Mobs Browser to perform various functions. These are listed below:





Edit

Displays the Create/Edit Tool dialog allowing you to edit the Tool parameters.

Rename

Allows you to Rename the selected tool.



Cut / Copy / Paste



These options allow you to Cut or Copy the selected Tool to the Windows Clipboard and then Paste it back to the Tools list to create a new tool using the previous tool as a template.

Add to Library

This allows you to Add the selected Tool to an exiting Tool Library *.csv data file.

Preview

This will display a Preview of the selected Tool in the Graphics Window similar to how the Tool displays during <u>Simulation</u>.

Tools Toolbar Functions



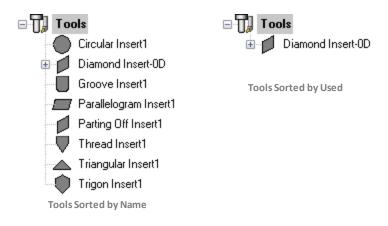
Sorting Selector: This allows you to sort the tool list. You can select No Sort or you can sort by Name, Number, Type and Diameter.



Sort in Ascending/Descending Order: This icon acts like a toggle to switch between Ascending and Descending sort order.

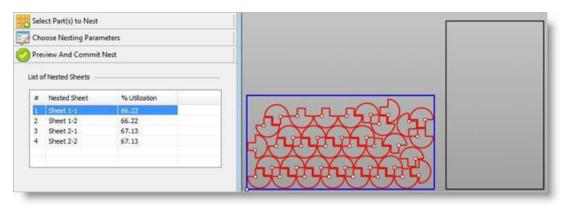


List on the Tool used in Machining Operations: Toggle this icon to list ONLY the tools currently assigned to an operation. **Note**: You must Generate an operation for the assigned tool to be listed.





The status bar displays the currently selected tool, tool tip radius & angle, spindle speed and cut feedrate.

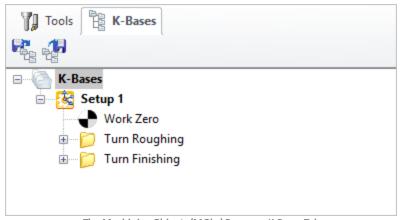


Right mouse button click on Tool in Tools tab provides the following options Edit, Rename, Cut, Copy, Paste and Preview tool.

5.4.2 K-Bases tab

Selecting the K-Bases tab under the Machining Objects Browser displays the Knowledge Base manager.

The Machining Objects (Mobs) Browser, K-Bases Tab



The Machining Objects (MObs) Browser, K-Bases Tab

K-Bases Tab Functions



Load Knowledge Base: Allows you to select a machining operations knowledge base to load.



Save Knowledge Base: Allows saving of knowledge bases which can be archived and used across other files.

Refer to the following sections for a detailed description on Knowledge base

Knowledge Base

5.5 Right-Click Commands

You can perform a variety of commands by right-clicking on items within the Machining Browser and Machining Job. The tables below lists each of the available commands.

from the Machining Operations (MOps) Browser

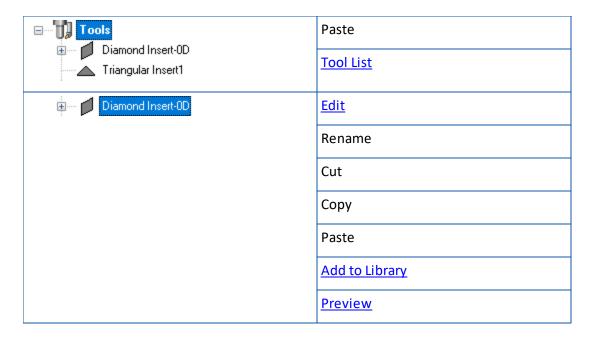
RhinoCAM Right-Click Commands - MILL Module				
Action Item	Right-Click Commands			
Machining Job	Regenerate All			
Machining Job Machine - Lathe	Post All			
Post - Fanuc	Simulate All			
Part - Defined Stock - Part Cylinder Stock Setup 1 Work Zero Turn Roughing Turn Finishing	Save to Knowledge Base			
	Information			
	Shop Documentation			
	Delete All			
Machine - Lathe	Machine Coordinate System			
Post - Fanuc	Set Post Options Dialog			
Stock - Part Cylinder Stock	Cylinder Stock Dialog			
	Part Cylinder Stock			
	Offset Stock			
	Revolve Stock			
	Stock from Selection			
	Export Stock to STL			
	<u>Delete Stock</u>			

	Remove Simulations	
⊟ <mark>∰</mark> Setup 1	Regenerate	
	<u>Post</u>	
	<u>Simulate</u>	
	Information	
	Shop Documentation	
	Rename	
	<u>Suppress</u>	
	Cut	
	Сору	
	<u>Paste</u>	
	Save to Knowledge Base	
Work Zero	Regenerate	
	Post	
	<u>Simulate</u>	
	Simulate Until	
	Simulate To End	
	<u>Information</u>	
	Edit	
	<u>Rename</u>	
	<u>Suppress</u>	
	Cut	
	Сору	
	<u>Paste</u>	
	Clone	

	Save to Knowledge Base
	Save As Defaults
	<u>Properties</u>
Turn Roughing	Regenerate
	Post
	Simulate
	Simulate Until
	Simulate to End
	<u>Information</u>
	Edit
	<u>Rename</u>
	Suppress
	Cut
	Copy
	<u>Paste</u>
	Clone
	Save to Knowledge Base
	Save As Defaults
	<u>Properties</u>

from the Tools tab of the Machining Objects (MObs) Browser

RhinoCAM Right-Click Commands - MILL Module				
Action Item	Right-Click Commands			
Machining Objects Browser / Tools Tab Tools K-Bases	Cut			



5.6 Docking Browsers

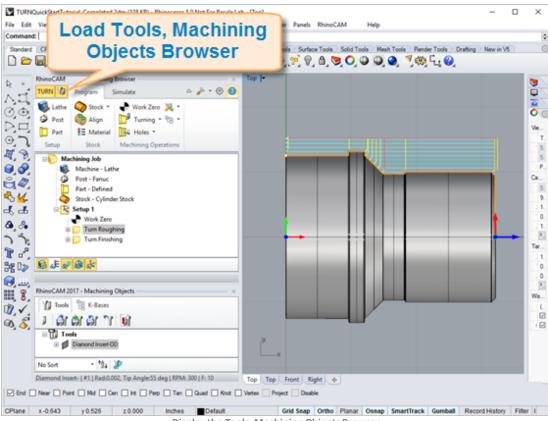
Both Machining Operations Browser and Objects Browser windows are dockable windows. This means these windows can be docked in any position in Rhino. This section describes the procedure to be used to dock both of these windows such that they are stacked vertically.

Step 1: Launch the TURN Browser

Select RhinoCAM from the menu bar and click TURN Browser. This displays the machining operations browser and by default is docked to the left half of the application window next to the view bar.

Step 2: Display the Tools, Machining Objects Browser

Select Tools, Machining Objects Browser button located on the Machining Operations Browser just to the left of the Program tab. This displays the Machining Objects Browser next to the operations browser.



Display the Tools, Machining Objects Browser

Step 3: Drag & Drop the Browser

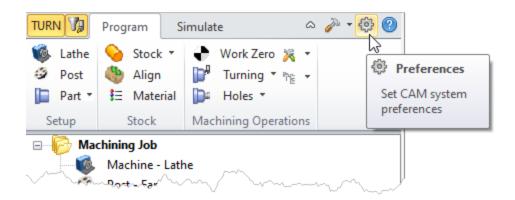
Selecting the title bar and holding the left mouse button down and dragging the browser window allows you to dock the browser to desired location. You can dock a browser inside of another browser or have them docked side by side.

5.7 CAM Preferences

You can set various CAM Preferences that will be saved even after you exit the program.

Select the Preferences icon from the Machining Browser. When you install a new RhinoCAM update you are choose to import your CAM Preferences from one version to the next.

The CAM Preferences Icon



The available Preferences include:

User Interface

Includes General, Stock Information and Ribbon Style preferences. Show the dialog

Geometry

Includes color preferences for Regions and Surfaces. <u>preference</u>.

Stock

These include stock colors, stock edge display and stock transparency. Show the dialog.

Cutting Tools

Includes Tool colors, Tool display states and the default Tool Library preferences. <u>Show the dialog</u>.

Feeds & Speeds

Includes Feeds & Speed preferences such as default values and other options. Show the dialog.

Machining

Includes Arc Output, Drill Cycle Output, Toolpath Resolution and the default machining Knowledge Base preferences. Show the dialog

Toolpath

Includes Toolpath Colors and Toolpath Display preferences. Show the dialog

Simulation

Includes Simulation Type, Mode, Accuracy, Transparency and other preferences. <u>Show</u> the dialog

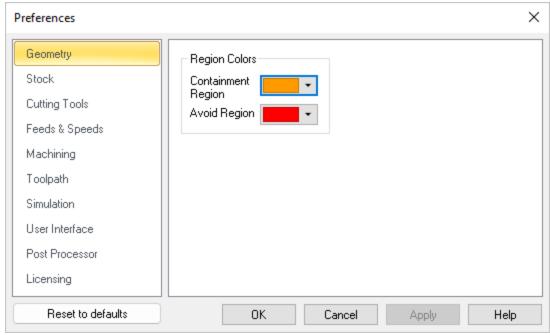
Licensing

Includes network licensing preferences. Show the dialog

5.7.1 Geometry

You can set the colors to display various objects using this dialog. To change each of the color settings in this dialog select the colored button next to the item of interest. This will bring up the color selection dialog, which can be used to choose the color needed. Once a color has been selected the button will change its color to the selected one. You can use the Reset to defaults button if you want to revert to the default factory install settings.

CAM Preferences > Geometry Dialog



CAM Preferences > Geometry

Region Colors

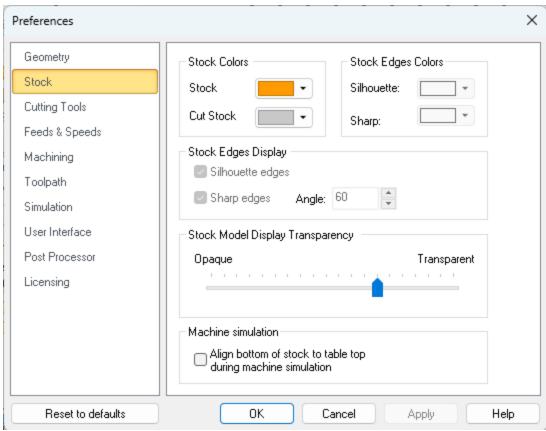
Sets the region highlight color for selection of containment and avoid regions.

5.7.2 Stock

You can set the simulation preferences using this dialog. **Note**: Some options are not available in XPR (Xpress) configuration. You can use the Reset to defaults button if you want to revert to the default factory install settings.

Dialog Box: CAM Preferences > Stock

Users can set the simulation preferences using this dialog:



CAM Preferences > Stock

Stock Colors / Stock Edge Colors

Here you can set the Stock and Stock Edge colors. You can differentiate between cut and non-cut areas by specifying different colors for them here.

Note: If the <u>Simulation Display State</u> is set to <u>Mop</u> then the Color assigned using the <u>Machining Operation Properties</u> is used to display the cut stock. Right-click on an operation in the <u>Machining Job tree</u> and select <u>Properties</u> to set this color.

Stock Edges Display

This section allows you to control the Stock Edges Display states. For example, you can check the boxes to display Silhouette Edges and Sharp Edges as well as the Angle to display for stock edges. Silhouette Edges and Sharp Edge colors are set using the Colors section of this dialog. Experimentation is advised until you are comfortable with the way your stock display.

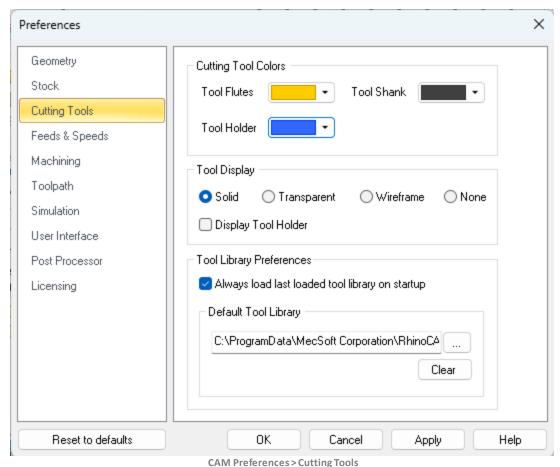
Stock Model Transparency

Use this slider to adjust the Stock Model Transparency when the Program tab is selected (i.e., when you are not simulating).

5.7.3 Cutting Tools

You can set the Tool Library to load on startup and also specify the location of your Tool Library files. You can use the Reset to defaults button if you want to revert to the default factory install settings.

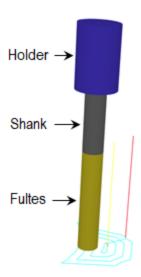
CAM Preferences > Cutting Tools



Note: Menu selections on the left may change depending on module and configuration

Cutting Tool Colors

Use the color selectors to set the default display colors for the cutting tool. The Tool Flutes, Tool Shank and Tool Holder can each be assigned a different.



Tool Display

The cutting tool can be displayed as either Solid, Transparent, Wireframe or None by selecting the desired option. You can also toggle the display of the Tool Holder by checking or un checking the box provided.

Tool Library Preferences

This defines your Tool Library preferences:

Always load last loaded tool library on startup

If you check this box, every time RhinoCAM loads, the last loaded Tool Library will be loaded automatically.

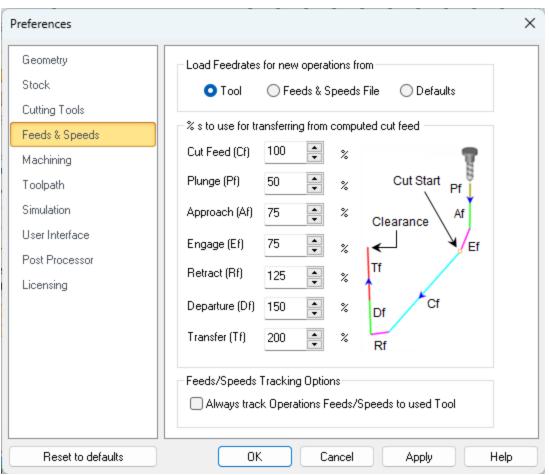
Default tool library path

Optionally you can specify the file path for your default tool library files. **Note**: It is recommended that you save your custom tool library files to a location outside of the RhinoCAM install path. This will keep them from being overwritten when you install new updates of RhinoCAM.

5.7.4 Feeds & Speeds

You can set the Feeds & Speeds preferences using this dialog. You can use the Reset to defaults button if you want to revert to the default factory install settings.

CAM Preferences > Feeds & Speeds



CAM Preferences > Feeds & Speeds

Load Feedrates for operations from

This allows you to select a preference option for loading Feeds/Speeds from table or from tool or use defaults when creating a new operation.

Tool

Selecting this option loads the feeds/speeds saved with the tool when creating a new operation.

Table

Selecting this option loads the feeds/speeds based on the material selected when creating a new operation.

Defaults

Selecting this option loads the feeds/speeds from the default knowledge base when creating a new operation. If default knowledge base is set to undefined, the system defaults would be used for loading feeds and speeds.

% s to use for transfer from computed cut feed

These % values apply when using the Load from File option (i.e., commonly referred to as the Feeds & Speeds Calculator) from either the Create/Edit Tools dialog of from the Feeds & Speeds tab of any of the toolpath operation dialogs. 100% of the Cut Feed specified in this dialog is applied and a percentage of the Cut Feed is used to populate the remaining feedrates for Plunge, Approach, Engage, Retract, Departure and Transfer. You can set the % values to use here.

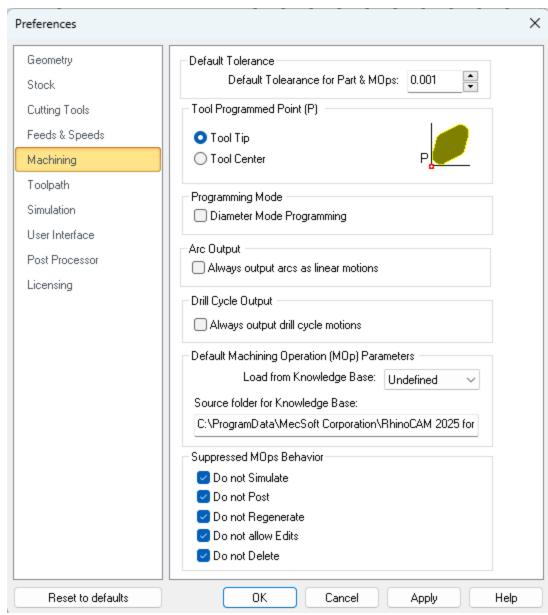
Feeds/Speeds Tracking Options

When you select the Load from Tool option from any of the toolpath operation dialogs, the Feeds & Speeds specified for the active tool are populated into the Feeds & Speeds tab of the operation's dialog. You can check this box to perform this automatically when new toolpath operations are created.

5.7.5 Machining

Users can set the machining preferences using this dialog. You can use the Reset to defaults button if you want to revert to the default factory install settings.

Dialog Box: Set Machining Preferences



Dialog Box: Set Machining Preferences

Default Tolerance

Default Tolerance for Part & Mops

Enter the default tolerance to use for the TURN Part definition as well as for new machining operations. You can edit this parameter manually from the Cut Parameters tab of each machining operation (Mop) dialog.

Tool Programmed Point (P)

The toolpath can be output as the tool tip or the tool center. If the output is set to be the tool center, the toolpath will be offset by the difference in the height of the tool tip and

tool center. The default value is the tool tip.

Programming Mode

Check the box to program in Diameter Mode for Turning. With this box checked, your posted g-code will output diameter values for the X axis. Make sure your Turn Machine Controller is set to the appropriate mode.

Arc Output

Some of the controllers do not handle arc outputs (for example G2, G3). For such type of controllers, the arcs that are generated in the TURN module toolpath can be output as linear segments using this option.

Drill Cycle Output

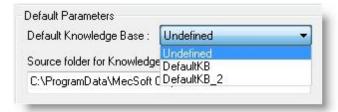
Check this box to always output drill cycles as linear motions. Left unchecked and the output is a canned drill cycle. Example g-code for the Fanuc post is shown below:

Checked Unchecked

% % (Standard Drill) (Standard Drill) G54 G54 G50 S300 G50 S300 G97 S300 M03 G97 S300 M03 M08 M08 G00 X0. Z0.25 G00 X0. Z0.25 X0. Z0.1 G81 X0. Z-0.5 R0.1 F10. G01 X0. Z-0.5 G70 F10. G00 X0. Z0.25 X0. Z0.1 G00G28W0. G00 X0. Z0.25 G00G28U0. G00G28W0. M09 G00G28U0. M05 M09 M30 M05 % M30 %

Default Machining Operation (Mop) Parameters

Allows you to select a Default Knowledge Base to load for creating machining operations. Selecting a knowledge base as Default loads the operation parameters when creating new operations. If no Default Knowledge Base is specified, the system defaults are used for machining operation parameters.



Default Knowledge Base

Refer to the following section for creating Default Knowledge Base

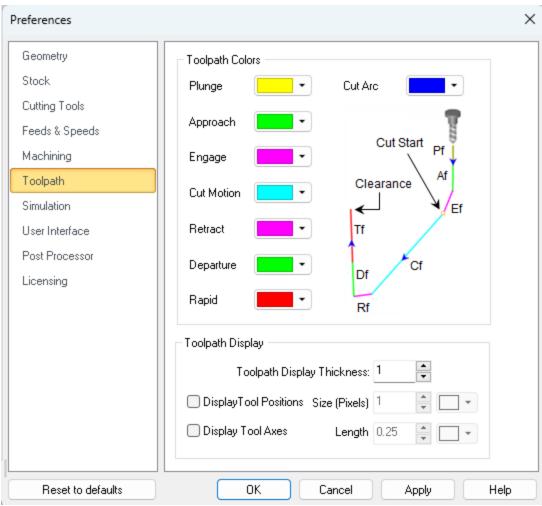
Suppressed Mops Behavior

When you Suppress Machining Operations (Mops) you can apply one or more of these conditions. Check each box to enable that condition and then pick OK to close this dialog.

5.7.6 Toolpath

These preferences relate to the graphical display of toolpath cut motions. You can use the Reset to defaults button if you want to revert to the default factory install settings.

CAM Preferences > Toolpath



CAM Preferences > Toolpath

Toolpath Colors

Use the color selectors to define the display color for each motion in the toolpath. The following can be set: Cut Motion, Plunge, Approach, Engage, Retract, Departure, Rapid and Cut Arc.

Toolpath Display

These preferences control the display of the toolpath in the graphics window.

Toolpath Display

This refers to the graphical display of toolpaths. Enter a value to effect the size of the toolpath during display.

Display Tool Positions Size (Pixels)

Check this box to display tool position locators. Each coordinate represents one tool position. Then enter the pixel size for the locator point as well as the color of the position points. You can also use the color selector to assign a color to these markers.

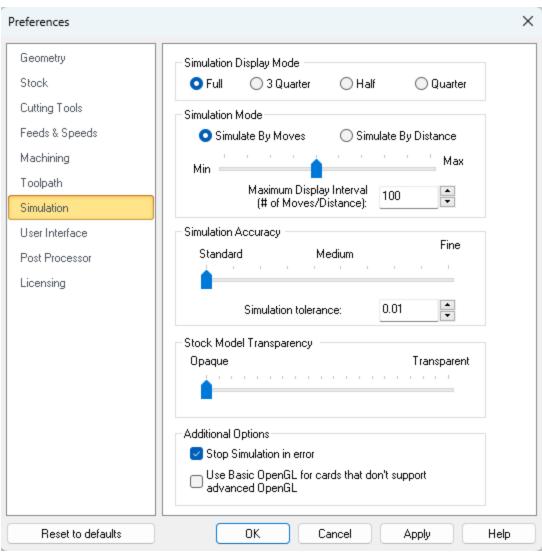
Display Tool Axis

Check this box to display the Tool Axis line. You can then enter a Length for the axis line and use the Color selector to assign it a color.

5.7.7 Simulation

Users can set the simulation preferences using this dialog. You can use the Reset to defaults button if you want to revert to the default factory install settings.

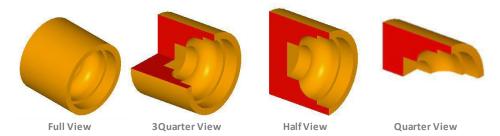
Dialog Box: Set Simulation Preferences



Dialog Box: Set Simulation Preferences

Simulation Display Mode

This parameter allows you to display the model in either Full, 3 Quarter, Half and Quarter. Simulations hidden inside the stock (Internal Boring, Drilling etc.), can be visualized better using the 3 Quarter or Half View.



Simulation Mode

User can set the simulation mode to Distance or by Motion. Simulate by Motion simulates the toolpath based on the number of go to motions in the generated toolpath. Simulate by Distance uses a distance based approach.

Simulation Speed

User can control the speed of the simulation using the slider bar and the Maximum display interval. When using Simulate by distance mode, the speed is determined as # of Motions / Distance.

Simulation Accuracy

This setting is used to control the accuracy of display of the simulated model. You can control the accuracy of the stock model by selecting from Standard, Medium or Fine. The finer the stock model accuracy results in slower performance and increases the simulation time.

Stock Model Transparency

User can control the stock model transparency under standard mode and under simulation mode.

Stock Edges Display

This section allows you to control the Stock Edges Display states. For example, you can check the boxes to display Silhouette Edges and Sharp Edges as well as the Angle to display for stock edges. Silhouette Edges and Sharp Edge colors are set using the Colors section of this dialog. Experimentation is advised until you are comfortable with the way your stock display.

Tool holder Display

User can turn on /off the display of tool holder during simulation.

Tool Display

The cutting tool can be displayed either as a sold, Transparent, wireframe or can be turned off during simulation.

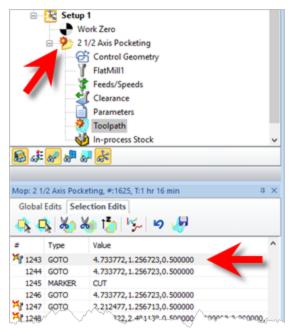
Additional Options

Use Basic OpenGL

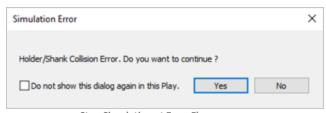
Check this box only if you have an older graphics card adapter that does not support advanced OpenGL (i.e., OpenGL 2). Some older cards may only support OpenGL 1 for example. If you experience graphics instability checking this box may help resolve the issue.

Stop Simulation in Error

Check this box to pause the Simulation at each error flag. If enabled, a message will display asking if you wish to continue with the simulation. Selecting Play will simulate to the next error flag and then pause. etc.



Stop Simulation at Error Flag

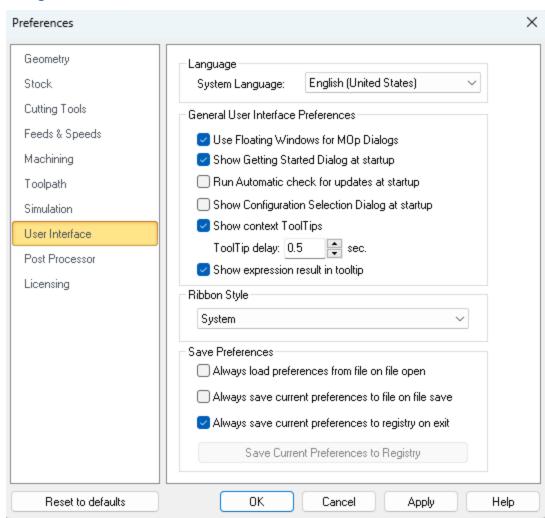


Stop Simulation at Error Flag message

5.7.8 User Interface

Users can set the various user interface options. You can use the Reset to defaults button if you want to revert to the default factory install settings.

Dialog Box: Set User Interface Preferences



Dialog Box: Set User Interface Preferences

User Floating Windows for Mop Dialogs

Selecting this option displays machining operation dialogs as a floating window where the dialog appears on top of the Machining Browser. If the above option is unchecked the machining operation dialog is docked and is displayed over the Machining Browser window.

Show Getting Started Guide at startup

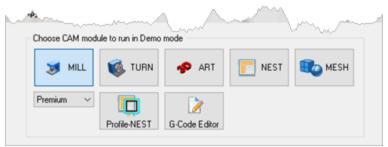
This displays Getting Started dialog at program startup every time the program is loaded. This dialog provides quick access to resources on MecSoft's website.

Run Automatic check for updates at startup

Selecting this option automatically checks for product updates when RhinoCAM is loaded. This requires access to internet on the computer running RhinoCAM.

Show Configuration Selection Dialog at startup

Selecting this option displays the product configuration dialog to run when the program is loaded. User can select from the following MILL modules - Standard, Expert, Professional and Premium.

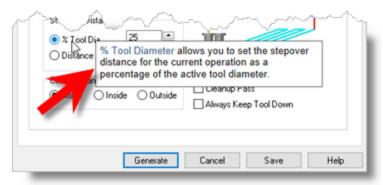


Configuration Selection Dialog at startup

This dialog appears at startup when RhinoCAM is running in demo mode.
Selecting a configuration loads RhinoCAM and provides the features available in the selected configuration.

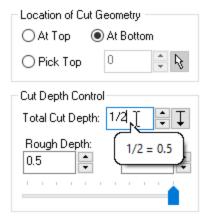
Show context ToolTips

Check this box to display Context ToolTips when the mouse moves over a parameter in a dialog. A definition of the parameter will pop-up automatically. **Note** that Context ToolTips may not be available for ALL dialogs. You can also set the ToolTip Delay in seconds. This is the amount of time it takes to display the Context ToolTip when the mouse activate it.



Show Expression Results in Tooltip

You can enter expressions in any dialog field that expects a numerical value and the value will be computed and entered automatically. Check this box to pop-up the results of any expressions in a ToolTip balloon. An example is shown below.



Show Expressions in ToolTip

Save Preferences

Always load preferences from file when opening a new file

Check this box if you wish to always load CAM Preferences from the file you are opening. Remember, however, that your current settings including your selected post is subject to be being changed.

Always save current preferences to file on file save

Check this box if you wish to always save the current CAM preferences to the file on file save. Remember, however, that your current settings including your currently selected post will replace those preferences that were in the current file originally.

Always save settings to registry on exit

Check this box if you wish to always save the current CAM preferences to the Windows registry when you exit your MecSoft CAM plugin. This will ensure that your current CAM settings will always be used when starting a new file.

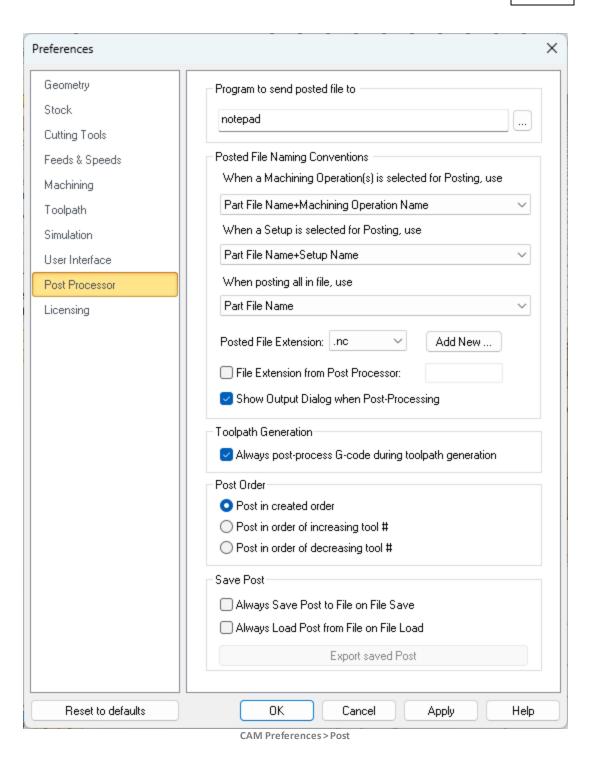
Save Current Preferences to Registry

If you have your preferences set the way you want them and do not want them top change, select this button to save the current preferences to your Windows registry. Doing this will force them to be loaded when you create new files.

5.7.9 Post Processor

These preferences relate to posting toolpath operations to gcode files. You can use the Reset to defaults button if you want to revert to the default factory install settings.

CAM Preferences > Toolpath



Program to send the Posted file to

This feature allows you to specify a program to display the posted file. This could be a NC editor or a text editor like Notepad.

You could also have this point to your control software's executable file and RhinoCAM will automatically launch this application when the machining operations are post processed.

Posted File Naming Conventions

This allows you to set rules for posted file name when post processing machining operations.

When a machining operation is selected for posting you can set the output file name from one of the following options.

- Part File Name + Machining Operation Name
- Part File Name + Setup Name + Machining Operation Name
- Setup Name + Machining Operation Name
- Machining Operation Name

When a setup is selected for posting you can set the output file name from one of the following options.

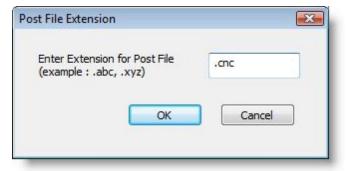
- Part File Name + Setup Name
- Setup Name

When Machining Job is selected to Post All, you can set the output file name from one of the following options.

- Part File Name
- Part File Name + First Setup Name
- First Setup Name

Posted File extension

You can select a posted file extension from the list or add an extension to the list by selecting Add new button. This displays the Post File Extension dialog shown below where you can specify a new file extension and click OK.



Dialog Box: Post File Extension

The new file extension is now set as your posted file extension automatically.

By default RhinoCAM performs interactive post-processing. That is, when you select a toolpath for post-processing, RhinoCAM launches the post-processor and waits for it to complete. You can also turn off the display of the output dialog (post and save dialog).

During interactive post-processing, RhinoCAM launches the NC editor to view the output file. You can specify a different NC editor to use. See Program to send the Posted file to above for doing this.

File Extension from Post Processor

Check this box to "pull" the posted g-code file extension from the Legacy Post-Processor (*.spm) file. This ensures that whichever post that you use, your posted g-code file will match the file extension defined in the active post. **Note**: You must edit your legacy post and set the Output File Extension value from the General tab in the Post-Processor Generator.

Show Output Dialog When Post Processing

Check this box to always display the Post & Save As file dialog when you select Post from an operation (Mop), Setup or Machining Job.

Toolpath Generation

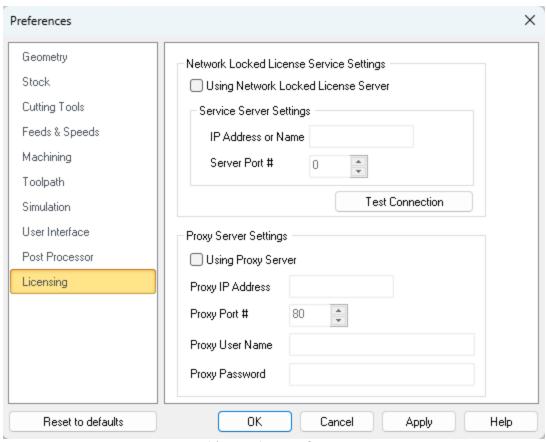
Always post-process G-code during toolpath generation

Your G-code is stored with your CAM file so that the latest G-code is always available to you when you open a file. Uncheck this box if you do not want new G-code generated every time you generate a toolpath operation.

5.7.10 Licensing

This dialog allows you to set Licensing Preferences for using a Proxy Server and/or a LAN Daemon (for Network Licenses). This information would be provided by your network administrator. You can use the Reset to defaults button if you want to revert to the default factory install settings.

Dialog	Box:	License	Preferences



Dialog Box: License Preferences

Network Locked License Service Settings

Network Locked License is a security process required when a computer on a network tries to connect to the server in order to use its resources. This license type is locked to the specified license server and cannot operate without a secure connection to the specified license server. If the user's client machine has access to the license server and a license is available, the license will activate. A valid server IP Address and Server Port # are required.

Using Network Locked License Server

Check this box to enable Network Locked License Server. Then complete the Service Server Settings provided here.

Server IP Address

For Network Authentication, enter the Service Server's IP Address here.

Server Port

For Network Authentication, enter the Service Server's Port # here.

Proxy Server Settings

Proxy Server Settings need to be set if your computer or network is behind a proxy. A proxy server is a computer that acts as an intermediary between the user's computer and

the Internet. It allows client computers to make indirect network connections to other network services.

Using Proxy Server

Check this box to enable Proxy Server Settings and complete ALL of the following fields accurately. This information would be provided by your network administrator.

Proxy IP

This is the IP Address for your Proxy Server. This information would be provided by your network administrator.

Proxy Port

Enter the Port Number for your Proxy Server. This information would be provided by your network administrator.

Proxy User

Enter the Proxy Server user name. This information would be provided by your network administrator.

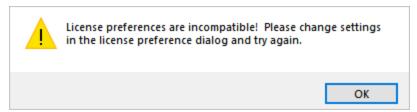
Proxy

Enter your Proxy Server password. This information would be provided by your network administrator.

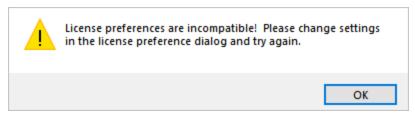
Troubleshooting and Messages

Here are some troubleshooting messages that you may encounter.

If you have node locked license activated and you select Using Lan Daemon, this will display the following message and release your node locked license.



If Using Lan Daemon is checked and you are entering a valid node locked activation code in the license dialog, the following message is displayed. Make sure Using Lan Daemon is unchecked before activating a node-locked license.



Overview of Machining Methods

There are two major classes of machining operations that can be created in the RhinoCAM TURN Module - Turning and Drilling. Turning operations are used to mill material to form shapes. Drilling operations are used to create holes. Both classes are essential in any manufacturing industry.

Turning operations can be categorized as Roughing, Finishing, Grooving, Threading and Parting Off. The various hole machining operations that can be used for hole making are Drilling, Tapping, Boring and Reverse Boring.

Turning

Provides access to Roughing, Finishing, Grooving, Threading and Parting Off operation. The tool moves in X and Z axis. Material is removed in successive passes in Roughing operation.

Holes

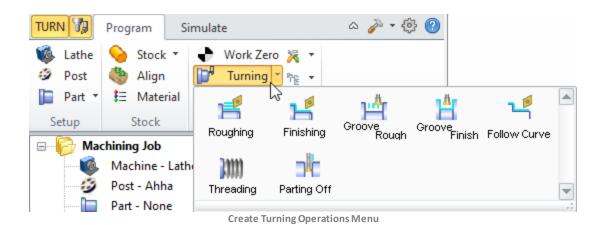
These operations are used to create holes in the part, including drill holes, counter sunk holes and through holes. Tapped and bored holes can also be created The tool is oriented along the Z axis and is at the center of the rotational axis.

These categories, and the available operations, within them are described in the sections to follow.

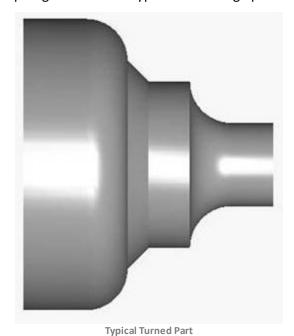
6.1 Turning Operations

The RhinoCAM TURN Module allows you to choose from a variety of rough, semifinish and finish machining operations to satisfy various machining conditions and requirements. A list of the available types with a short description for each type is given below. The drop down menu in the icon can be used to access Turning operations and Hole machining operations. The Turning operations under the Turning menu that can be used in TURN Module are Roughing, Finishing, Grooving, Follow Curve, Threading and Parting Off.

Create Turning Operations Menu



Using this class of machining, you can machine parts that are defined by 2D curves or 3D part geometries. A typical machining operation would involve roughing then finishing.



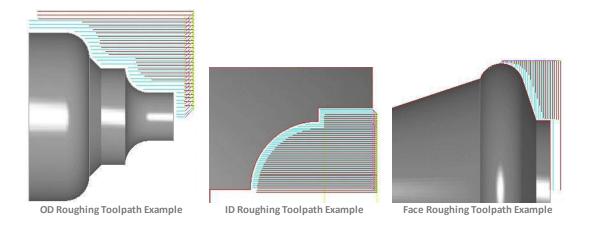
6.1.1 Roughing



This is the RhinoCAM TURN Module's principal method of roughing, in which the material is roughed out in multiple cuts. This type of machining is very efficient for removing large volumes of material, and is typically performed with a large radius tool. Roughing is typically followed by finishing toolpaths.

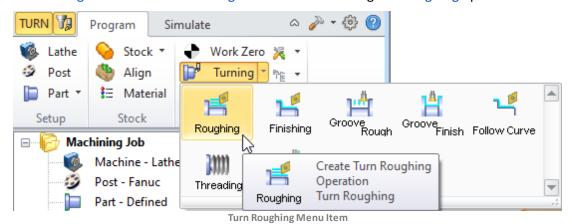
Both part and stock geometry are used to determine the regions that can be safely machined. Roughing can be of 3 types: OD Roughing, ID Roughing, and Front Facing (Face Roughing). See <u>Turn Roughing</u> for cut parameters.

Turn Roughing Examples



Turn Roughing Menu Item

The Turn Roughing toolpath method is invoked by selecting the Program tab, clicking on the Turning button in the Machining Browser and selecting the Roughing operation.



6.1.2 Finishing

Finishing

This is one of the most commonly used machining processes. The part is rotated while a single point cutting tool is moved parallel to the axis of rotation following the contour of the geometry. Finishing can be done on the external surface of the part (OD, Face) as well as internally (boring). You can define offsets so that the tool

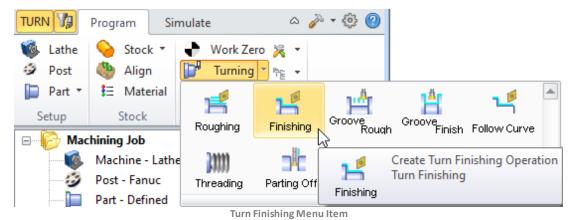
makes multiple passes relative to the regions. Finishing is typically done after a Roughing operation, or it can be used alone. See <u>Turn Finishing</u> for cut parameters.

Turn Finishing Examples



Turn Finishing Menu Item

The Turn Finishing toolpath method is invoked by selecting the Program tab, clicking on the Turning button in the Machining Browser and selecting the Finishing operation.



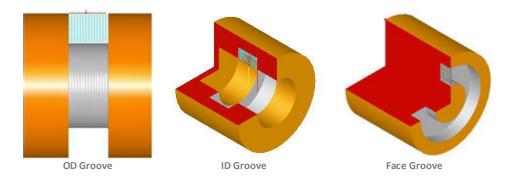
6.1.3 Groove Roughing



This operation is performed to machine grooves in multiple cuts on the part. This roughing operation provides user the control to set the step down and step over and choose the cut direction.

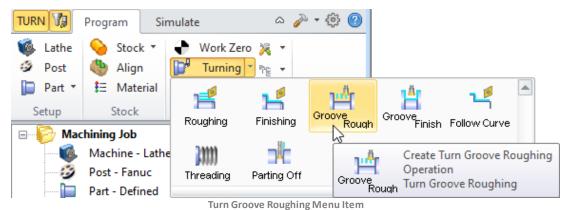
Both part and stock geometry are used to determine the regions that can be safely machined. Groove Roughing can be of 3 types: OD Groove Roughing, ID Groove Roughing, and Face Groove Roughing. The grooves are typically used to slide/fit one part into another to obtain the required assembly. See Turn Groove Roughing for cut parameters.

Turn Groove Roughing Examples



Turn Groove Roughing Menu Item

The Groove Roughing toolpath method is invoked by selecting the Program tab, clicking on the **Turning** button in the Machining Browser and selecting the Groove Roughing operation.



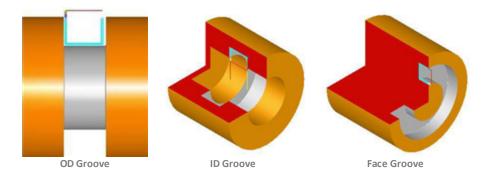
6.1.4 Groove Finishing



This operation is used to finish the grooves. This operation is performed after the Groove Roughing operation. Groove Finishing can be of 3 types: OD, ID, and Front Facing. See <u>Turn Groove Finishing</u> for cut parameters.

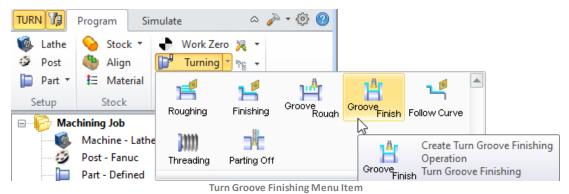
Turning Operations

Turn Groove Finishing Examples



Turn Groove Finishing Menu Item

The Groove Finishing toolpath method is invoked by selecting the Program tab, clicking on the Turning button in the Machining Browser and selecting the Groove Finishing operation.



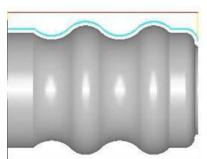
6.1.5 Follow Curve



This operation is performed after the roughing operation. This is similar to finishing operation where the toolpath follows the selected curve to obtain better surface finish and is characterized by smaller depth of cut to obtain tighter tolerances and better surface finish. This method is similar to engraving in milling where the tool

nose radius compensation is not applied to the toolpath. Follow curve can be used in OD, ID, and Front Facing operations. See <u>Turn Follow Curve</u> for cut parameters.

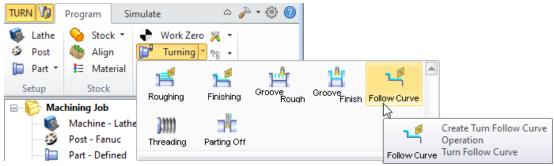
Turn Follow Curve Example



Follow Curve Operation Toolpath Example

Turn Follow Curve Menu Item

The Follow Curve toolpath method is invoked by selecting the Program tab, clicking on the Turning button in the Machining Browser and selecting the Follow Curve operation.



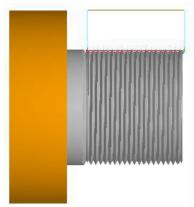
Flow Curve Menu Item

6.1.6 Threading



This operation is performed to machine threads on the part. Threads are used as fasteners for assembly purposes. OD and ID threads can be programmed using this method. See <u>Turn Threading</u> for cut parameters.

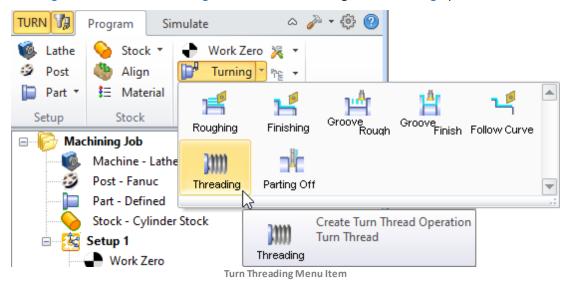
Turn Threading Example



Threading Operation Toolpath Example

Turn Threading Menu Item

The Threading toolpath method is invoked by selecting the Program tab, clicking on the Turning button in the Machining Browser and selecting the Threading operation.

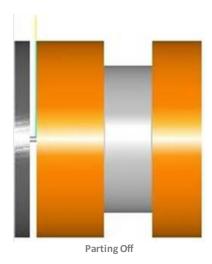


6.1.7 Parting Off



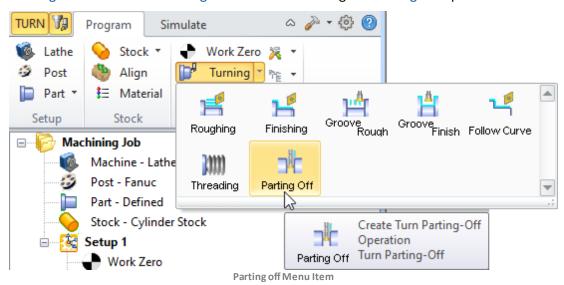
This operation is performed to cut off the finished part from the rest of the bar stock which is typically done as the last operation in OD. See <u>Turn Roughing</u> for cut parameters. See <u>Turn Parting Off</u> for cut parameters.

Turn Parting Off Example



Turn Parting Off Menu Item

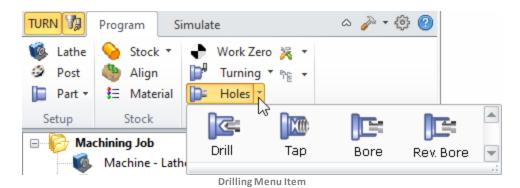
The Parting Off toolpath method is invoked by selecting the Program tab, clicking on the Turning button in the Machining Browser and selecting the Parting Off operation.



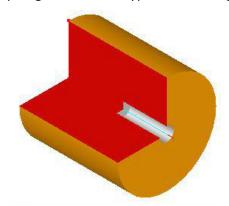
6.2 Drilling (Hole Making) Operations

These operations are used to create holes in the part, including drill holes, counter sunk holes and through holes. Tapped and bored holes can also be created. The tool is oriented along the Z axis and is at the center of the rotational axis. The following drilling operations are available:

Turn Drilling (Hole Making) Operations Menu



Using this class of machining, you can machine parts that are defined by 2D curves or 3D part geometries. A typical machining operation would involve roughing then finishing.

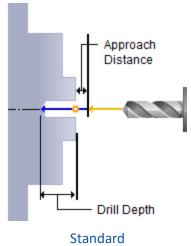


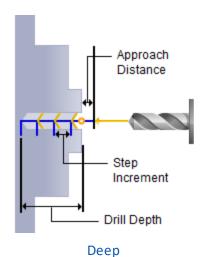
Typical Turned Hole Operation

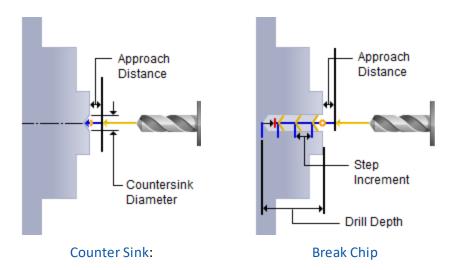
Turn Drill Operation



The following drill cycles are available:







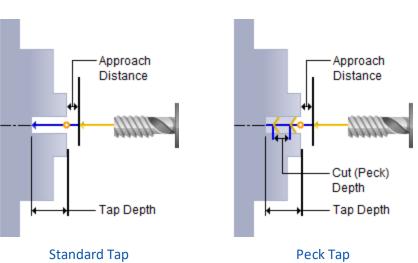
User Defined Drill1 / User Defined Drill2

These are user defined drill types.

Turn Tap Operation



The following tap cycles are available:



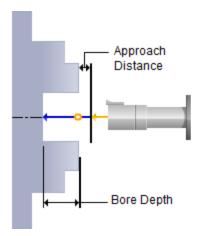
User Defined Drill1 / User Defined Drill2

These are user defined drill types.

Turn Bore Operation



The following bore cycles are available:



Drag Bore, No Drag Bore, Manual Bore

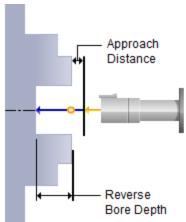
User Defined Drill1 / User Defined Drill2

These are user defined drill types.

Turn Reverse Bore Operation



The following reverse bore cycles are available:



Reverse Bore

User Defined RBore1 / User Defined RBore2

User defined Reverse Bore types.

Creating Machining Operations

Creating machining operations in the RhinoCAM TURN Module is a very simple process. You load the part, select the part geometry for turning, create stock geometry if necessary, select a tool and then specify the feeds and speeds to be used in the machining operation.

You then pick the type of machining operation required and set the parameters for the operation and then generate the toolpath. You can also specify cut containment to restrict areas to be machined. Generation of the toolpath begins once you click on the "Generate" button in the machining operation parameter dialog. Once the toolpath generation is complete the machining operation will be created and displayed in the Machining Browser (Mops). The following sections describe each of the necessary and optional items that need to be selected or set before creating a machining operation.

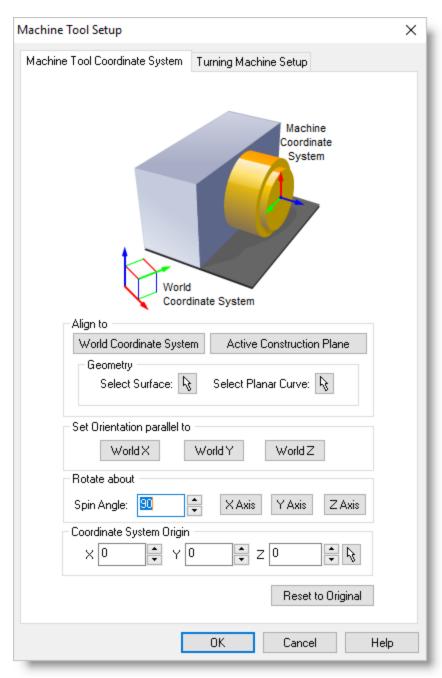
7.1 Lathe

7.1.1 Coordinate System

Once part geometry is loaded, user can set the cutting direction. This orients the Machine Coordinate System for Turning to have the part aligned in the same way as it would be fixtured on the machine tool for cutting. The stock geometry and machine tool definition will be defined based on the orientation of the machine tool coordinate system.

This dialog offers a convenient way of aligning the Machine Coordinate System (MCS).





Dialog Box: Machine Tool Setup, Machine Tool Coordinate System tab

The Machine Coordinate System (MCS)

The Machine Coordinate System (MCS) is displayed as a triad with **Blue** line representing the Z-axis, **Red** representing X-axis and **Green** representing the Y-axis. The WCS is displayed the same way as MCS and is located at the origin. The lengths of the WCS arrows are shorter when compared to MCS.





(WCS)

Align to

This aligns the MCS orientation. Select from the following:

World Coordinate System

Setting the MCS to the WCS. In this case MCS and WCS would have the same coordinate location.

Active View Construction Plane

Setting the MCS to the orientation of the active viewport of the construction Plane.

Geometry:

Part Surface

User can select a point on a surface determine the alignment of MCS.

Geometry:

Planar Curve

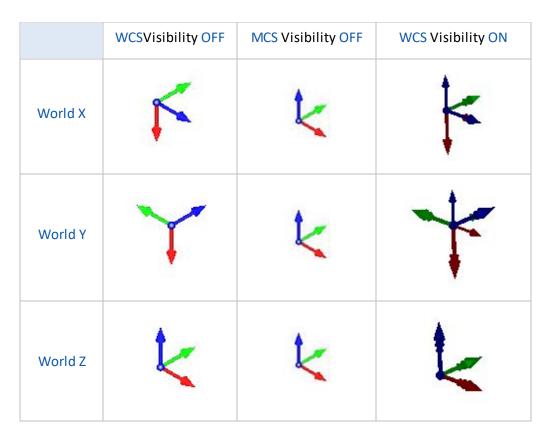
User can select a planar curve (2D sketch) to determine the alignment of MCS.

Set Orientation Parallel to

Allows you to set the Machine Coordinate System parallel to the World X Y or Z coordinate axis.

- World X
 Orients the Z axis of MCS parallel to World X axis.
- World Y
 Orients the Z axis of MCS parallel to World Y axis.
- World Z
 Orients the Z axis of MCS parallel to World Z axis.

Orientation Parallel to	Triad Display		
	MCS Visibility ON	WCS Visibility ON	MCS Visibility ON



Rotate about

Allows you to rotate the Machine Coordinate System in X Y Z coordinate axis by any angle specified under Spin Angle.

Specify Spin Angle and click the axis to rotate about. Clicking the same coordinate axis button multiple times rotates by the specified angle incrementally. For example if you set the Spin Angle = 90 and click X Axis button 2 times, the MCS is rotated about X coordinate axis by 180 degrees.

Coordinate System Origin

This translates the MCS origin to the desired location. This can be set to any location on the part geometry.

Reset to Original

Resets MCS orientation to current MCS orientation.

7.1.2 Machine Setup

This dialog allows you to setup your Machine Tool Definition. Refer to each section below for more information.

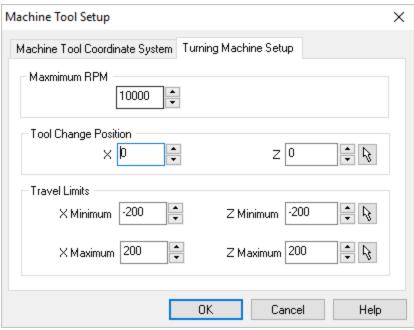
Turning Machine Setup

In the TURN Module, this dialog sets up the machine for 2 axis turning operations. This is done by selecting Lathe (Turning Machine Tool Setup) under Program tab in Machining Browser. This will bring up the following dialog.

Machine Tool Setup, Machine Tool Coordinate System tab

See: Machine Tool Setup, Machine Tool Coordinate System tab

Machine Tool Setup, Turing Machine Setup tab



Dialog Box: Machine Tool Setup, Turing Machine Setup tab

Maximum RPM

Allows you to specify the maximum spindle RPM that can be set for the machine tool.

Tool Change Position

User can specify a coordinate location in X and Z axis. TURN Module will take this coordinate values and output it for every tool change. The tool change variables must be configured in the post processor.

Travel Limits

Allows you to specify the minimum and maximum travel limits for X and Z Coordinate axis of your machine. **Note**: These parameters are not applied and reserved for future use.

7.2 Geometry

This refers to the types of geometry that can be defined and used in TURN Module.

7.2.1 Part Geometry

Part Geometry constitutes the end product of the manufacturing operation. This is also the design model. Design models in various data formats can be imported into Rhino. These design models can either be solid models or surface models or even faceted triangle models.

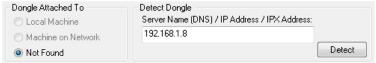
Refer to the following section for information on defining part geometry for Turning - Part Geometry

7.2.1.1 Part Geometry Types

TURN Module requires Solid, Surfaces, Polygon Meshes, Regions/Curves that defines the part geometry. Since all parts that can be created in a 2-Axis turning machine are solids of revolutions, it is enough to describe the profile that needs to be revolved to create this shape. The profile can be created in Rhino as a region or curve. TURN Module automatically creates the 2D silhouette of this part region when 3D Solid or Surface geometry is selected as TURN part geometry.

The First Quadrant, XY Plane Restriction

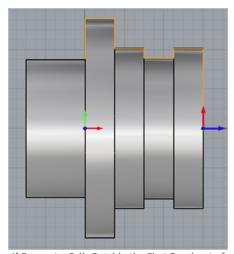
Furthermore, TURN Module places a further restriction that these part geometry need to be constrained to lie *only* in the first quadrant of the ZX plane in turn coordinate system. This would essentially be XY plane (Top view) in world coordinate system in Rhino.



The First Quadrant, XY Plane Restriction

If Geometry Falls Outside the First Quadrant of the XY Plane

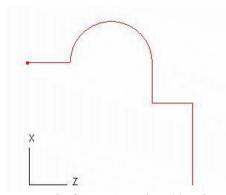
TURN Module will be unable to process a part region that fall outside the first quadrant. If the selected part region is outside the first quadrant, TURN Module will trim this to the first quadrant.



If Geometry Falls Outside the First Quadrant of the XY Plane

Example of Curves Correctly Positioned

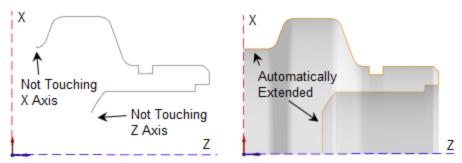
Example below shows curve region correctly positioned in the first ZX quadrant of the turn coordinate system touching both the X and Z axis. This would essentially be XY plane (Top view) in world coordinate system in Rhino.



Example of Curves Correctly Positioned

Example of Curves NOT Touching the X or Y Axis

Example below shows region not touching the X axis and/or Z axis



Part Profiles are Automatically Extended to the X and Z axis

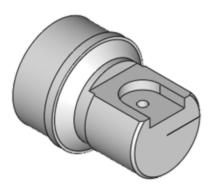
In such cases, TURN Module automatically extends the part regions to the X and Z axis when the regions do not touch the X axis and/or Z axis.

Part regions need to be constrained to the first quadrant of the ZX coordinate system.

Parts can be imported or can be created within VisualCAD using the Geometry creation and editing tools found under the CAD ribbon bar.

TURN Geometry with MILL features

You can select 3D geometry (surfaces, solids or meshes) for defining the TURN part that contains milling features. Such milling features are ignored while the turn part profile is being defined.



7.2.1.2 Orient Part

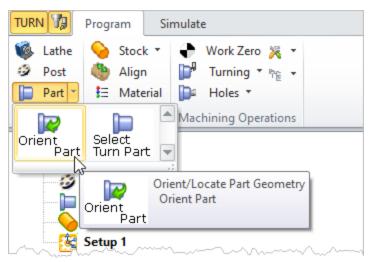


Once part geometry is loaded, you can set the cutting direction. This allows you to orient the part to have it aligned properly for machining. This dialog can be invoked by selecting Setup and Orient Part from Program tab under the Machining Browser. This dialog has some very powerful options to help you quickly position your part for

machining. refer to the dialog and options listed below.

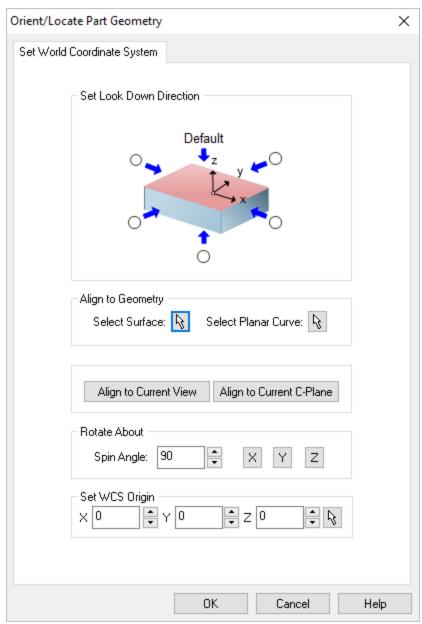
Orient Part icon

Locate the Orient Part Icon



Machining Browser: Setup, Orient Part

☐ Dialog Box: Orient/Locate Part Geometry



Dialog Box: Orient Geometry

Set Look Down Direction

Select the radio button representing the orthographic view of your part that you wish to machine. For example, select the right side radio button (on the positive X side in the dialog image) will rotate your part so that the positive X direction becomes the positive Z direction.

Align to

If your part is not aligned orthographically, you can use these options to align your part to selected geometry or active display element. Select from one of

the options that will orient the part that you wish to machine:

Select Surface

Choose the Pick button and then select a surface of your part to orient to.
The part will be aligned such that the surface normal direction is aligned with the -Z axis.

Select Planar Curve

Choose the Pick button and then select a Planar Curve of your part to orient to. The part will be aligned such that the curve will be parallel to the XY plane (i.e., normal to the Z axis).

Align to Current View

Pick this button to align the part such as the Current View direction is aligned with the Z axis (i.e., you are looking in the -Z direction).

Align to Current C-Plane

Pick this button to align the part so that the Current C-Plane becomes parallel with the XY plane.

Rotate About

Use this option to Rotate About one of the principal XY or Z axis. Enter an angle and then select the button representing the axis you wish to Rotate About.

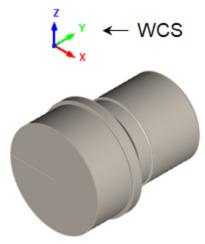
Set WCS Origin

You can also independently set the coordinate location for the WCS. So for example, you can orient the part normal to a surface and then also choose a point on the surface to become the new WCS origin. In this case the part would be oriented to the surface while the point on the surface remains at the WCS.

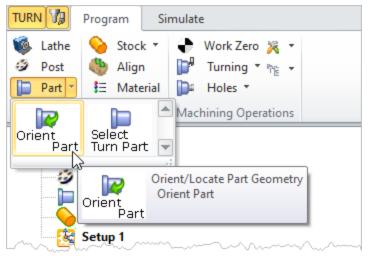
Example: Steps to orient your part for Turning

In TURN, the default rotational axis is along the X Axis of the World Coordinate System or WCS. **Note:** Once you select a direction and pick OK from the dialog, all of the geometry will be moved and/or rotated. In the example part shown below we want to orient the part so that the rotation axis is along the X Axis of the WCS. We also want the WCS origin to be located at the center of the back face of the part. Look at the steps below to see how it's done.

1. From the Program tab select Part and then Orient Part.



Incorrect Orientation

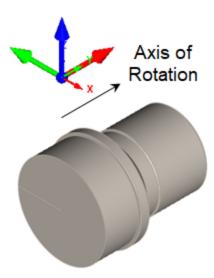


Machining Browser: Setup, Orient Part

The dialog is displayed and the WCS is also displayed on the screen.

2. Under Rotate About, set the Spin Angle to 90 and then pick the Z button to rotate the WCS displayed on the screen. We want the X Axis of the WCS to point along the rotational axis of the part.

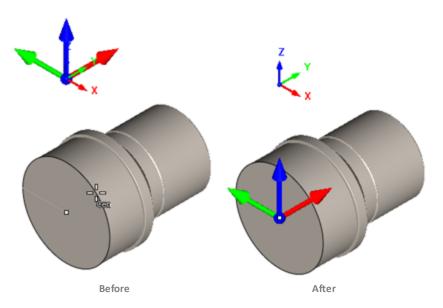




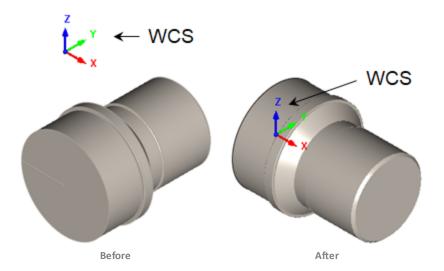
3. Now, let's locate the WCS origin. In the dialog under Set WCS Origin, select the Pick button.



4. Select the center point of the circular face of the back of the part. This is the face that will be mounted on the spindle of the lathe. When you select the point, the WCS triad is move to that point.



5. Now pick OK from the dialog and the part is oriented as desired.



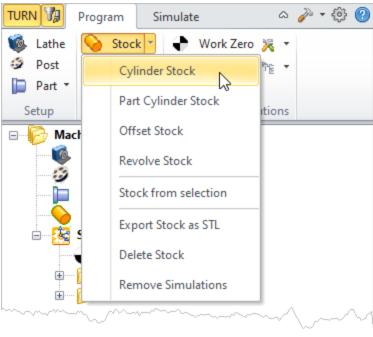
7.2.2 Stock Geometry



Stock Geometry represents the raw stock from which the designed part needs to be manufactured. TURN module allows the definition of various kinds of stock models.

7.2.2.1 Cylinder Stock

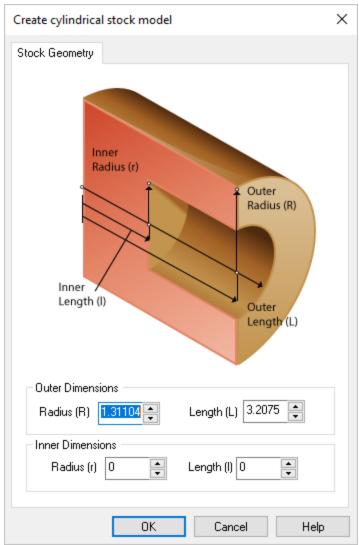
You can define the raw stock model as a simple cylinder by selecting the Cylinder Stock option from Create Turn Stock Model under the Program tab in Machining Browser.



Cylinder Stock Menu Item

Dialog Box: Create cylindrical stock model

When you select this option, the following dialog will be invoked.

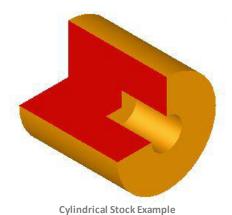


Dialog Box: Create cylindrical stock model

Inner/Outer Radius Dimensions

In this type of Stock model user can specify the Radius (Outer and Inner) and Length (Major and Minor) for the stock. By default TURN Module displays with outer Radius (R) and Major Length (L) values based on the defined part geometry.

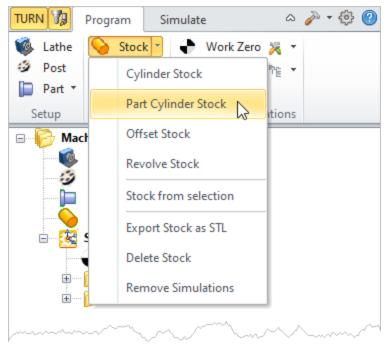
The stock is displayed as a cylinder positioned at the reference point of the lathe machine. Its color can be set in the Color Preferences under CAM Preferences.



7.2.2.2 Part Cylinder Stock

You can define the raw stock model as a part bounding cylinder by selecting the Part Cylinder Stock option from Create Turn Stock Model under the Program tab in Machining Browser.

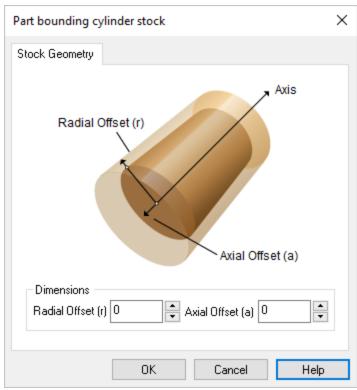
Stock Menu Selection



Part Cylinder Stock Menu Item

Dialog Box: Create cylindrical stock model

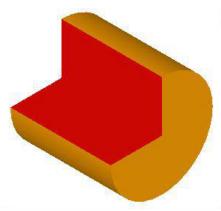
When you select this option, the following dialog will be invoked.



Dialog Box: Part bounding cylinder stock

Radial/Axial Offset Dimensions

You can define the cylinder by simply specifying the Radial (r) and the Axial (a) offset distances. The bounding cylinder will be calculated based on the defined part geometry and these offset values will be used to expand the cylinder in both the radial and axial direction.

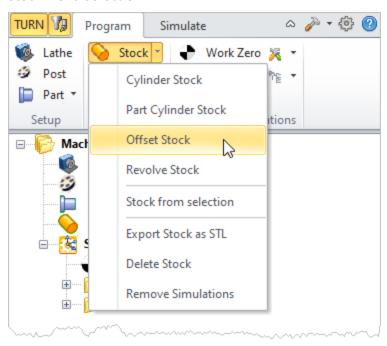


Create cylindrical stock model example

7.2.2.3 Offset Stock

You can define the raw stock model as a uniformly offset part model by selecting the Part Offset option from Create Turn Stock Model under the Program tab in Machining Browser.

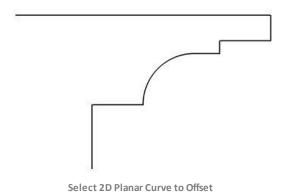
Stock Menu Selection



Offset Stock Menu Item

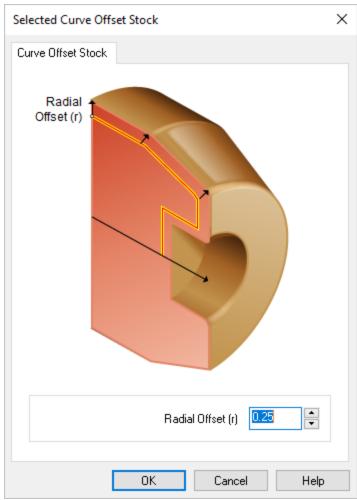
Select 2D Planar Curve to Offset

First, you need to select a 2D planar curve on the XZ axis before creating a Curve Offset Stock. User can then specify offset value to create the stock model.



Dialog Box: Selected Curve Offset Stock

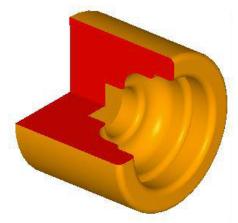
The following dialog will be invoked.



Dialog Box: Selected Curve Offset Stock

Radial Offset (r)

When you click on the OK button, a stock model based on the specified Radial Offset (r) is created. You can switch to the Simulate tab of the browser window to display the stock model that was created.

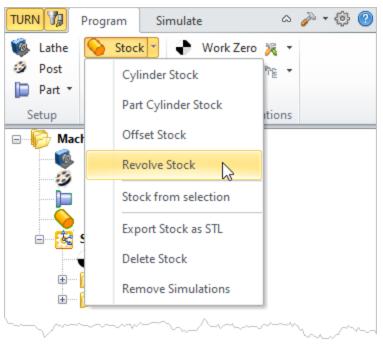


Selected Curve Offset Stock Example

7.2.2.4 Revolve Stock

You can define the raw stock model by revolving selected 2D curve profile as Revolve Stock from Create Turn Stock Model under the Program tab in Machining Browser.

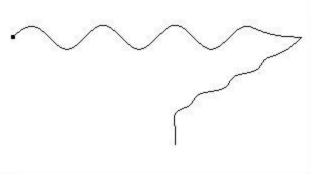
Stock Menu Selection



Revolve Stock Menu Item

Select 2D Planar Curve to Revolve

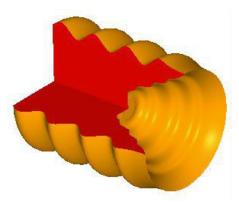
First select a 2D planar curve on the XZ axis before creating Revolve Stock.



Select 2D Planar Curve to Revolve

Revolve Stock Example

The system creates a stock model by revolving the 2D profile curve about the Z axis. You can switch to the Simulate tab of the browser window to display the stock model that was created.

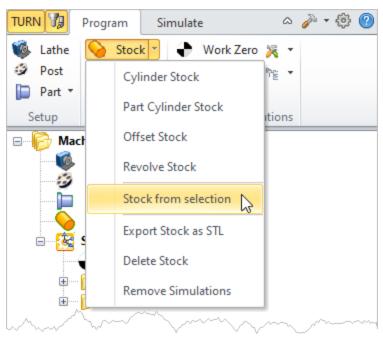


Revolve Stock Example

7.2.2.5 Stock from Selection

You can define the raw stock model from the currently active selected 3-D geometry. You can select 3D surfaces and/or meshes and then selects Stock from Selection option from Create Turn Stock Model under the Program tab in Machining Browser.

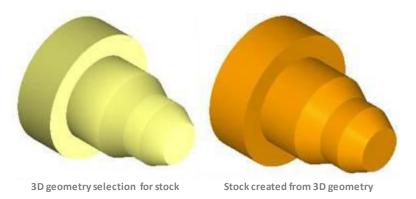
No dialog will be invoked but the system will use the selected geometry and create a triangulated stock model. You can switch to the Stock tab of the browser window to display the stock model that was created.



Stock from Selection Menu Item

Stock from Selection Example

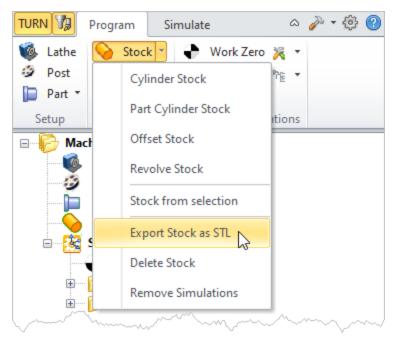
You can switch to the Simulate tab of the browser window to display the stock model that was created.



Stock from selection will fail to create stock if the selected 3-D geometry is not a watertight model.

7.2.2.6 Export Stock as STL

User can export the stock geometry by selecting Export Stock as STL from Create Turn Stock Model under the Program tab in Machining Browser.

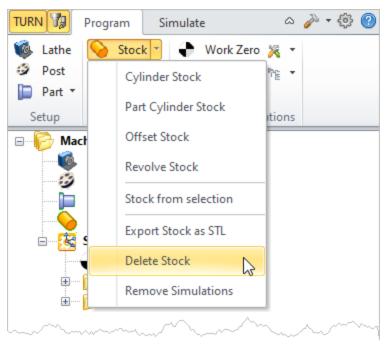


Export Stock as STL Menu Item

A Save As dialog appears that allows you to save the stock model as STL. The stock model can also be exported by selecting the stock entry under Machining Job, right mouse button click and select Export Stock as STL.

7.2.2.7 Delete Stock

User can delete the stock geometry by selecting Delete Stock from Create Turn Stock Model under the Program tab in Machining Browser.



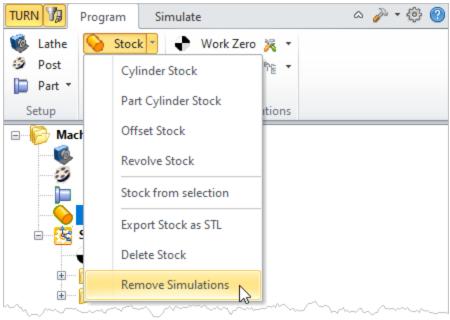
Delete Stock Menu Item

The stock model can also be deleted by selecting the stock entry under Machining Job, right mouse button click and select Delete Stock.

7.2.2.8 Remove Simulations

You can remove the in-process stock model by selecting Remove Simulations from Stock menu under the Program tab in Machining Browser. This is different than the <u>Delete Stock</u> command. The stock is not deleted, only the current simulations are removed.

Machining Browser: Remove Simulations



Machining Browser: Remove Simulations stock menu

7.3 Setup

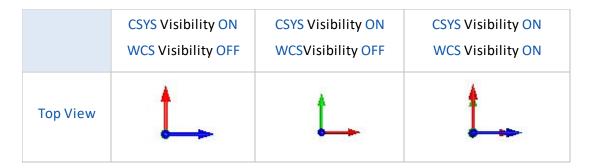
Setup defines the Turn coordinate system. CNC turning centers use the Cartesian coordinate system for programmed coordinates but they are typically different from that used in milling. Turning centers follow the convention that axis of rotation that is aligned with the spindle is designated as the Z axis. Secondly the axis perpendicular to this axis along which the tool travels to cut into the stock is designated the X axis. Thus the part is rotated about the Z-axis of the lathe machine. Moving the tool along the Z-axis provides the direction of feed and moving it along the X-axis provides the depth of cut.

Triad Display States

The Turn Machine Coordinate System (CSYS) is displayed as a triad with **Blue** line representing the Z-axis, **Red** representing X-axis and **Green** representing the Y-axis. The WCS is displayed the same way as MCS with the length of the lines and arrows being smaller when compared to MCS.

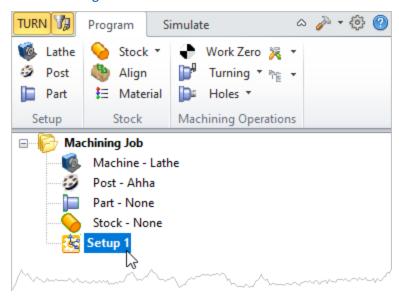


0	Triad Display Chatas
Orientation	Triad Display States
Parallel to	



Setup 1 in the Machining Browser

By default Setup 1 is created when a new part is loaded. The Setup cannot be edited in the Machining Browser.

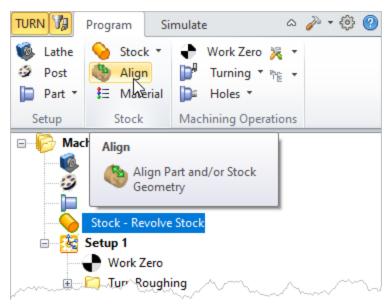


Setup1 in the Machining Browser

7.4 Align Part and Stock Models

It is typical for users to need the ability to position stock geometry in some geometric relationship with the part geometry. This dialog offers a convenient method of relative positioning the stock along the Z axis based on defined part geometry. This dialog can be invoked by selecting Align Part Stock from Program tab under the Machining Browser.

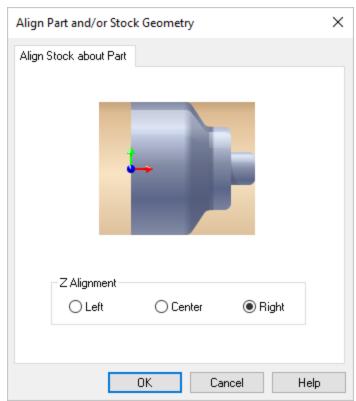
Align (Menu Selection)



Align Part and Stock Models Menu Item

Dialog Box: Align Part and Stock Geometry

The Align Part and Stock Geometry dialog appears as shown below.



Dialog Box: Align Part and Stock Geometry

Z Alignment

Turn part geometry needs to be defined before aligning stock to part. For information on defining part geometry, refer to Part Geometry.

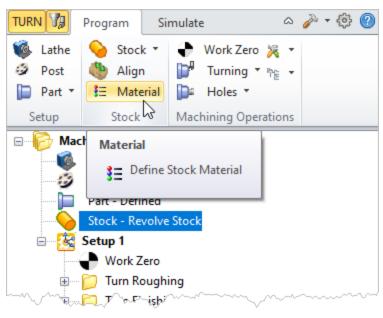
Once both part and stock geometry are defined in TURN Module, use this dialog to perform the relative positioning. Select the necessary Z alignment options using the appropriate radio buttons in this dialog.

7.5 Material

This allows selection of material for Stock geometry. User can select a material from the available list of materials. Selecting a material displays the texture for the material. This texture is applied to stock geometry and can be displayed during simulation.

Machining Browser: Material menu item

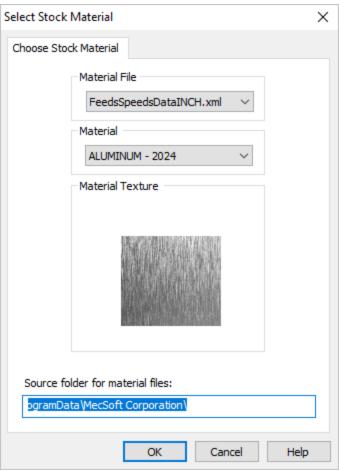
This dialog can be invoked by selecting Material from Program tab under the Machining Browser.



Material Menu Item

Dialog Box: Select Stock Material

Choose Stock Material dialog appears as shown below.



Dialog Box: Select Stock Material

Material File

This points to file where all materials are defined.

This xml contains the list of materials, texture, feeds and speeds. The file is located under Materials folder in RhinoCAM. (C:\ProgramData\MecSoft Corporation\RhinoCAM 20xx for Rhino x.x\Materials).

The Materials folder contains the following files

- FeedsSpeedsDataINCH.xml
- FeedsSpeedsDataMM.xml

If part unit is set to Inches, RhinoCAM automatically loads FeedsSpeedsDataINCH.xml and when part unit is set to MM, FeedsSpeedsDataMM.xml is loaded.

The material file is an .xml file format, which can be edited using any text editor to add newer materials.

See Feeds and Speeds for information on the format of the material file and adding new materials.

Material

This lists all materials available in the selected Material File. Selecting a Material from the list displays the material name and material texture.

Material Texture

A preview of the Material Texture is displayed for reference.

Material Texture Visibility

Click OK. Once you have defined a Stock geometry, click Material Texture Visibility icon under Program or Simulate tab in Machining Browser to display the texture applied to stock model.

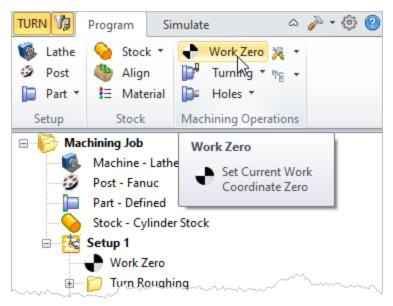


Material Texture (TURN)

7.6 Work Zero

Work Zero defines the work coordinate (part or stock) origin. This is also known as the program zero. Work Zero translates the turn machine coordinate system origin (CSYS) to the desired location on the Z axis. Typically this is set to the face of the part or stock geometry. This dialog can be invoked by selecting Work Zero from Program tab under the Machining Browser.

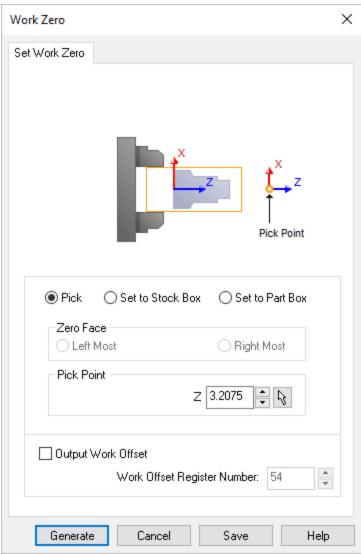
Work Zero (Menu Selection)



Work Zero Menu Item

Dialog Box: Work Zero

Set Work Zero dialog appears as shown below. You can set the origin by explicitly picking a point on the Z axis or can set it with respect to the Part or Stock geometry bounding boxes.



Dialog Box: Work Zero

Pick

If you select the Pick option, the button with the pick cursor will be activated. You can then click on this button to graphically select a point to set Work Zero.



You can use object snaps located in Rhino's status bar to snap to part geometry.

Set to Stock Box

Selecting this item will activate the Zero Face section of the dialog. You can then select the zero face to the Left Most or to the Right Most face of the stock by choosing the appropriate selections in the dialog.

Set to Part Box

Similar to the previous selection, selecting this item will activate the Zero Face section of the dialog. You can then select the zero face to the Left Most or to the Right Most face of the part by choosing the appropriate selections in the dialog.

Output Work Offset

This allows you to specify a Work Coordinate Offset number which is then output in the posted code. This is set under Work Offset Register Number. Work offsets are used to set work piece origin(s) on CNC machines that are assigned to a register number G54, G55 etc... Entering a positive number will make incremental offsets positive (i.e., G54, G55, etc.) Entering a negative number will make decremental offsets (i.e., G54, G53, etc.).

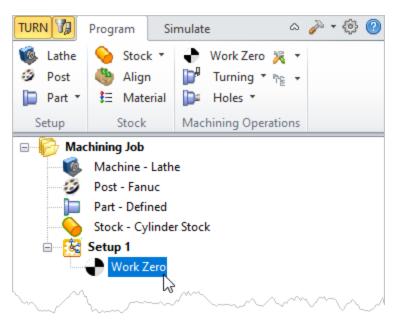


For example:

- To output G54, G55, etc., set the Work Offset Register number to 54. To output G54, G53, etc., set the Work Offset Register number to -54 (negative).
- The Work Offset Prefix "G" is set in the post-processor generator.

☐ Generate

Click Generate and Work Zero is now listed under Setup in Machining Browser. The Machine CSYS origin is now translated to the specified location.

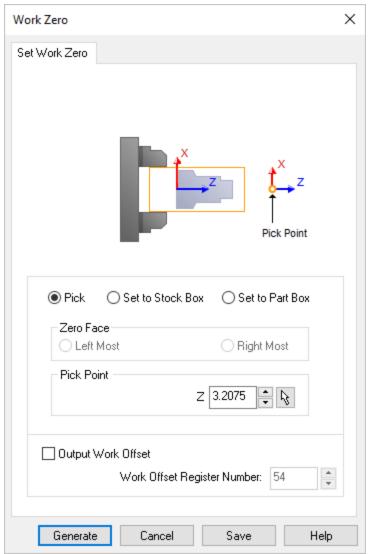


Work Zero displayed in the Machining Browser

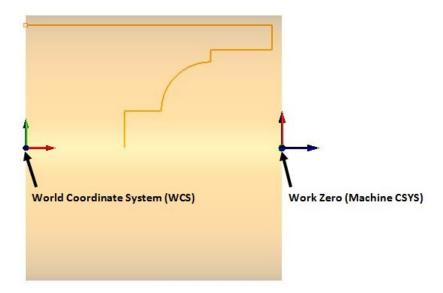
Work Zero Example

In the example shown below Work Zero is set to:

- Set to Stock Box
- Zero Face Right Most



Dialog Box: Work Zero



7.7 **Machining Features**

Refer to the following section for additional information - Part Geometry

It should be noted that regions can be created and be present in a part file but if they are not selected in defining turn part geometry they will be ignored during toolpath computation. So creating a region does not make it active; you select it as turn part geometry before creating the toolpath.

7.7.1 **Avoid Sections**

This allows user to select areas to be excluded from the turn part geometry for toolpath computation. This is done by selecting 2 points on the part geometry. A line is inserted between the 2 selected points as avoid region and this now becomes part of your turn part geometry. One or more avoid areas can be selected.



Defining Avoid Sections

To select an area to avoid:

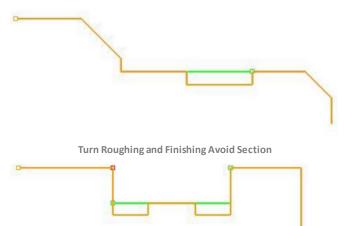
From the Global Parameters tab in the Turn Operations dialog box, click Select Section under Avoid Sections and pick 2 points on the part geometry. The selection is now displayed under avoid selection.

Selecting an Avoid Region from the list highlights it on the part geometry.

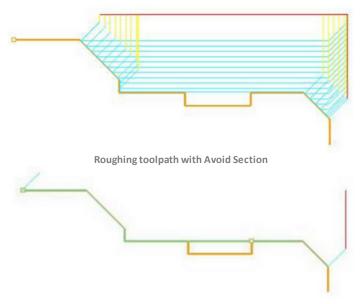


Avoid Sections, Global Parameters tab of Turn Operations dialog box

Examples for various Turn Operations



Groove Roughing and Finishing Avoid Section



Finishing toolpath with Avoid Section

7.8 Tool

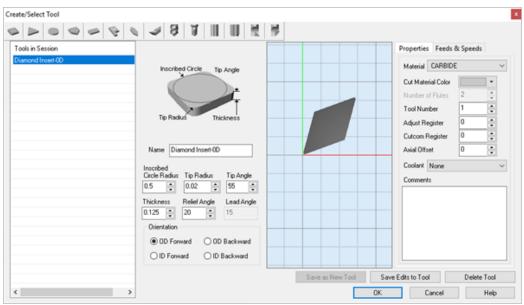
TURN Module allows you to define, use and archive various types of turning inserts and drilling tools. The tool types that are currently supported are Diamond, Triangular, Circular, Trigon, Parallelogram, Groove, Threading, Parting off, Drill, Center Drill, Reamer, Tap, Bore and Reverse Bore.

For each tool you can specify standard APT parameters: Tip radius, Relief angle, thickness, width, length, nose angle. All defined tools can be viewed in the Tools tab of the Machining Objects Browser. You can also save a set of tools to a library that can be loaded in other files.

7.8.1 Create/Select Tools

To create a tool, you either selects the Create/Edit Tool option under the Tools tab in Machining Objects Browser or alternatively by selecting the Create/Edit/Select Tool button under the Tool tab in the machining operation. This brings up the following dialog box that you can utilize to create and edit tool definitions.

- Create/Select Tools
 - Dialog Box: Create/Select Tools



Dialog Box: Create/Select Tools

Create Tools Toolbar

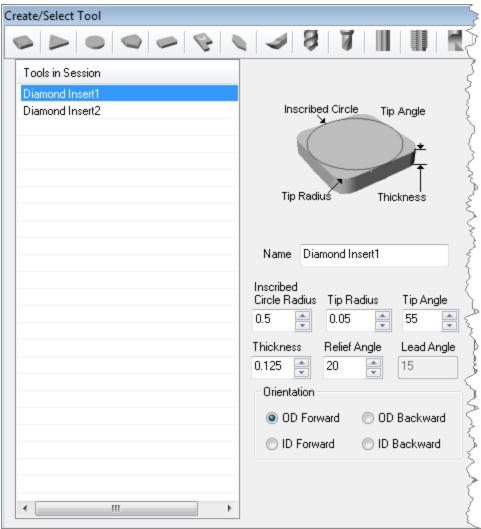
The tool toolbar on the top of the dialog displays all various types of tools available in TURN Module. Different tool types can be defined by selecting the desired icon the dialog box.



Create Tools Toolbar

Tools in Session

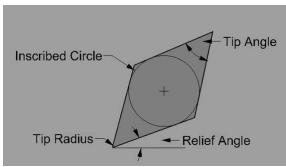
The dialog box shows the tool name of the current selection if there is one selected in the list-box under Tools in Session. If there is no selection then the tool name will be the name used for a new tool definition. The list box itself lists all of the tools of the corresponding type.



Tools in Session

Standard APT Parameters for Tool Definition

The geometry definition of the tool contains edit boxes for the Tip Radius, Relief Angle, Thickness, Width, Length and Nose Angle. These definitions are standard APT parameters for the tool definition. The parameters would be different depending on tool insert type.



Diamond Tool Insert

Save/Edit/Delete Tool

- Save As New Tool saves a new tool and lists under Tools in Session. If a tool of the same name already exist under Tools in Session, the Save as New Tool button will be grayed out.
- Save Edits to Tool saves edits or changes made to tool parameters
- Delete Tool deletes the selected tool. A tool will not be deleted a tool if is being used in a machining operation.

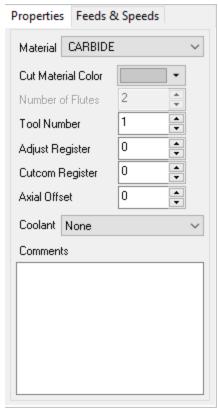
Tool Preview



1001116416

The Properties tab

The Properties tab to the right side of the tool preview allows you to set the Tool Material, Cut Material Color, Tool Number, Adjust Register, Cutter Compensation Register, Axial Offset and Coolant Type. The Tool Number and Adjust Register are used when post processing toolpaths.



The Properties tab

Adjust Register

This is used to set the Tool Offset register (an integer). Generally this is set the same as Tool Number. In turning applications, this is typically output along with the tool number. The posted code would output this number that corresponds to the offset value in the controller's tool table. Note the post processor needs to be configured to output the Adjust Register and 2 digit format for Tool numbers and registers.

For example

N20 T0101 M6

Where first set of 01 is the tool number and the next set of 01 points to the offset location in controllers tool table.

Cutcom Register

This is used to set the Tool Diameter Offset (an integer) for cutter compensation / tool wear compensation at the controller. Generally this is set the same as Tool Number. The posted code would output D<#> and the # corresponds to the offset value in the controller's tool table.

For example

N30 G41 X 2.0 Y 1.0 D1

Where D1 points to the controllers tool table for diameter compensation.

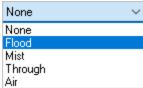
Note the post processor needs to be configured to output the Cutter Compensation. Refer to Cutter Compensation for detailed description.

Axial Offset

This parameter offsets the Z value in the posted g-code by the specified value. This can be set to a positive or negative value and can be an integer or decimal.

Coolant

Here you can override the Coolant that is specified by the Tool. Coolant can be set to Flood, Mist, Through or Air. Coolant codes are defined in the post processor generator under Misc tab. Coolant Off is also supported as a variable that can be added where needed using the post-processor generator.



Coolant selections available

Comments

Outputs specified comments in the posted g-code before a tool change.



Adding \$ as prefix would skip the comment start and end characters in the posted output file.



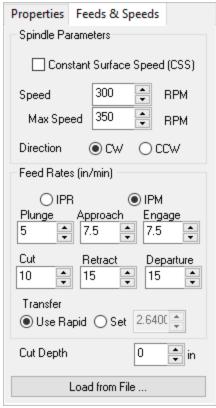
The posted code would include the comments in the output as shown below.

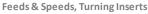
(DIAMOND INSERT 1) M01

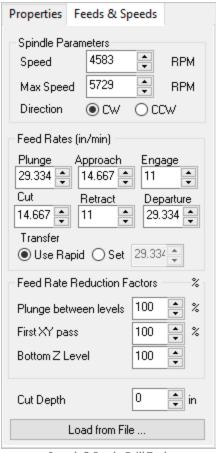
Make sure comments to output is selected in your post processor.

The Feeds & Speeds tab

The Feeds & Speeds tab located next to Properties tab allows you to set feeds and speeds for each tool. Feeds & Speeds parameters for Dill, CenterDrill, Tap, Bore and ReverseBore are slightly different from Turning inserts. Also note that there is Max Speed value for Drill tools in the TURN module.







Speeds & Feeds, Drill Tools

Cut Depth

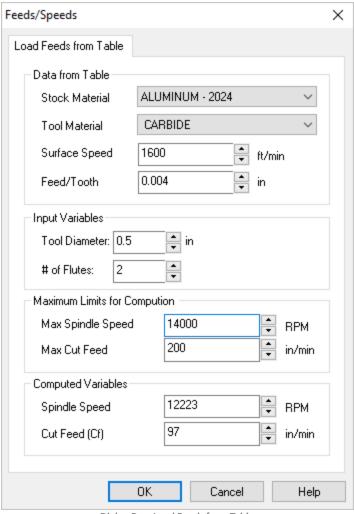
You can set the Cut Depth specific for each tool you create. If you set this value here, you will see a Depth From Tool icon next to the Rough Depth/Cut parameter in the Cut Levels tab of each operation where it applies. Selecting the icon will use this value for Rough Depth/Cut. If Cut Depth is left at 0 in this dialog, the icon will not appear in the Cut Levels tab.

Load from File

This loads the Feeds & Speeds values from the Feeds & Speeds Table file. This will display the Load Feeds from Table dialog box to make your selections.

Dialog Box: Load Feeds from Table

Selecting OK from this dialog transfers the spindle speed and cut feedrate to the Feeds & Speeds tab. The plunge, approach, engage, retract and departure feeds are determined using a percent of the cut feed. The percent to use for transferring the computed cut feed can be set under Feeds & Speeds Preferences.



Dialog Box: Load Feeds from Table

Data from Table

Stock Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Tool Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Surface Speed

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Feed/Tooth

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Input Variables

The input variables - Work Diameter is automatically loaded from the Stock Radius. Based on this parameter and the Variables Limits parameters, the program computes Spindle Speed and Cut Feedrate (Cf). measured in Unites/Revolution. Changing the spindle speed modifies the cut feedrate.

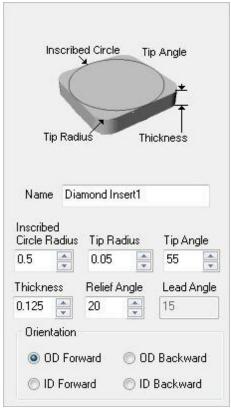
Maximum Limits for Computation

Here you can set the Max Spindle Speed and Max Cut Feed (Cf) values. Once these two values are set, the Spindle Speed and Cut Feed calculated by this dialog will not exceed these values even if you attempt to enter higher values into the Computed Variables fields. To exceed these values, change them here or you must edit the operation or tool parameters manually.

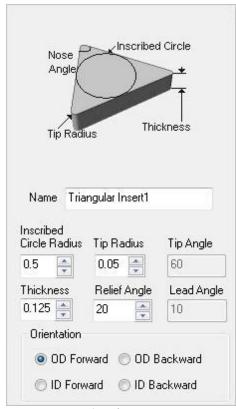
Computed Variables

The variables for Spindle Speed and Cut Feed (Cf) are computed for you based on the selections made in this dialog but will not exceed the values set in the Maximum Limits for Computation section of the dialog. These values are then assigned to the active toolpath operation or tool. You can override either of these variables and the other will update automatically. Since this dialog is a Feeds & Speeds Calculator, you cannot override both values. To do so, you must edit the operation or tool parameters manually.

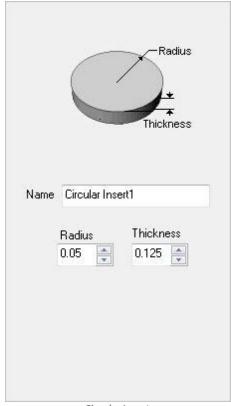
Turning insert types available

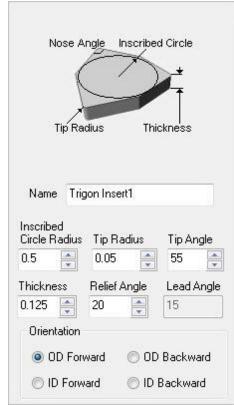






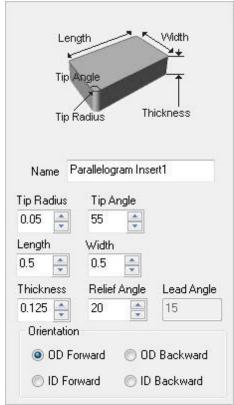
Triangular Insert

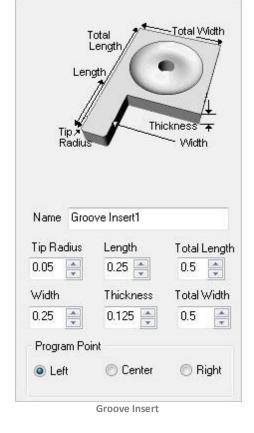




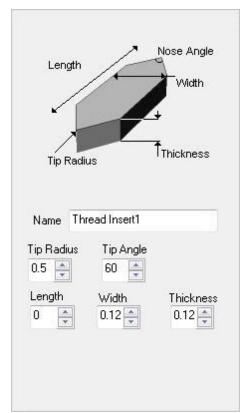
Circular Insert

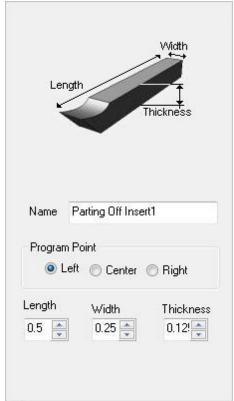
Trigon Insert





Parallelogram Insert

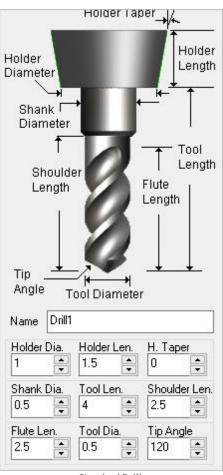


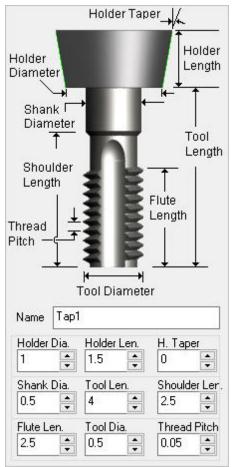


Thread Insert

Parting off Insert

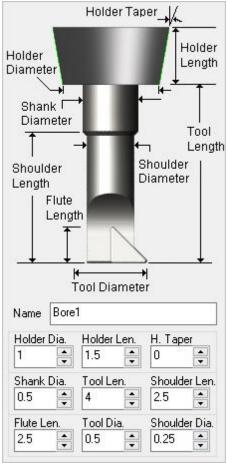
Drilling Tools available in TURN Module

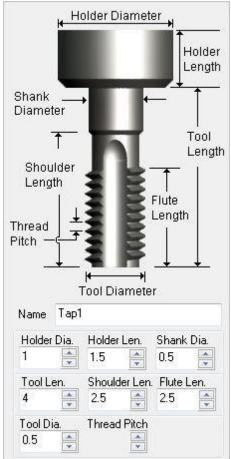




Standard Drill

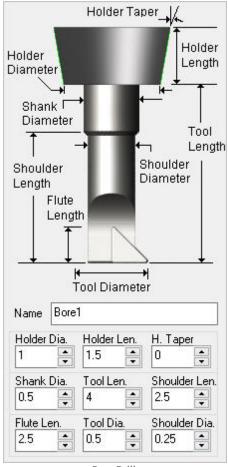
Center Drill

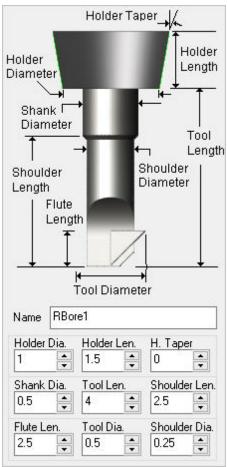




Reamer Drill

Tap Drill





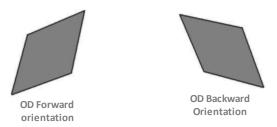
Bore Drill

Reverse Bore Drill

Orientation

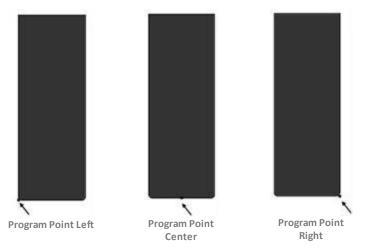
Orientation is set for Diamond, Triangular, Trigon, Parallelogram inserts to set the orientation of the tool inserts for OD, ID programming.

- OD Forward is commonly used for both OD and Front Facing operations.
- OD Backward is used for a Back Facing insert. This is used for programming a back relief on a part.
- ID Forward is used for programming ID operations.



Program Point

Program Point is set for Grooving and Parting off inserts. This can be set to left, center or right in the insert definition.



7.8.2 Load Tool Library



Select the Load Tool Library button from the Tools tab of the Machining Objects Browser. This enables the loading of a previously saved tool library.

Locating the Load Tool Library button



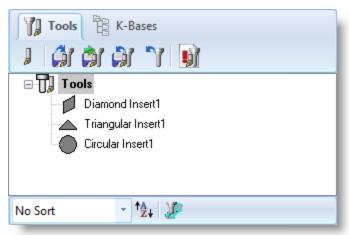
Locating the Load Tool Library button

Select the Tool Library File

Browse to the folder; double click on the desired file (*.vkb or *.csv) to load it into TURN Module.

To load a Tool Library from TURN 1.0 module

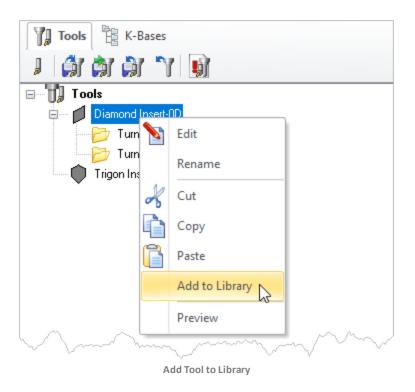
To load a Tool Library from TURN 1.0 module, select Version 1.0 Tool Library Files (*.vtl) under file type. The loaded tool list will be seen under the tool button in the browser. To perform the Edit, Rename, Cut, Copy or Paste operations on any of these tools, hit the right mouse button while highlighting the desired tool.



The loaded tool list will be seen under the tool button in the browser

7.8.3 Add Tool to Library

You can right-click on a Tool listed in the Mobs Browser to Add the Tool to an exiting Tool Library *.csv data file.



7.8.4 Select Tools from Library

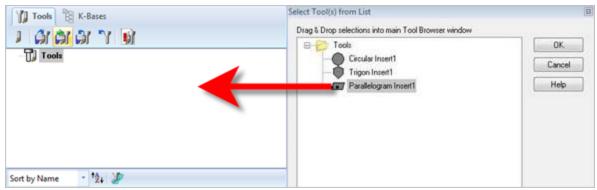


The Select Tools from Library button enables users to select tools from a previously saved Tool Library.

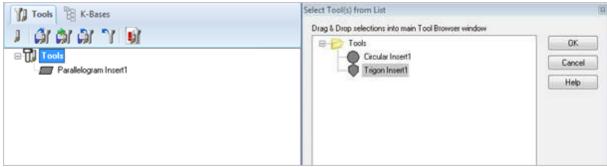


Locating the Load Tool Library button

The list of tools will now be displayed under Select Tools(s) from list dialog and you can drag and drop the tools from the selection list to the cutting tools browser.



Dialog Box: Select Tools(s) from list (Drag & Drop)



Dialog Box: Select Tools(s) from list (Drag & Drop)

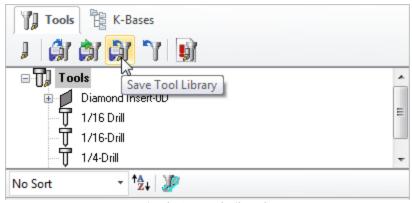
To Edit, Rename, Cut, Copy or Paste on any of these tools, use right mouse button click after selecting the tool under Tools tab.

7.8.5 Save Tool Library



This button enables the created tools to be saved in a Tool Library file. The file can be saved in the desired directory and read in when required.

Locating the Save Tool Library button



Locating the Save Tools Library button

Dialog Box: Save As

Specify a file name and click Save.

File Types Supported

TURN Module supports 2 types of tool library file format *.vkb and *.csv. Both formats save and loads tools with the feeds and speeds assigned for each tool.

7.8.6 List Tools

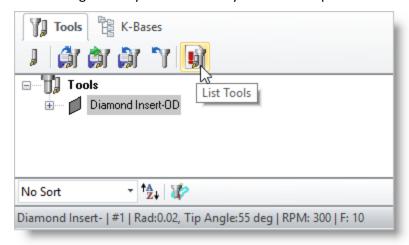


This allows you to List and Print your tools.

List Tools (in the TURN Module)

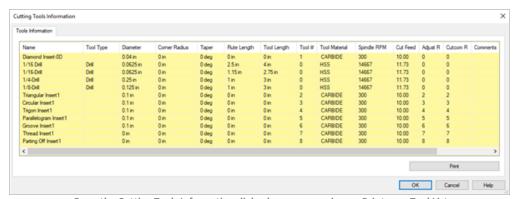
1. From the Tools tab of the Machining Objects Browser, select the List Tools button

Note: The actual icons you see in this dialog will depend on what module and what configuration you are currently licensed to operate



Locating the List Tools button

2. The button brings up all the tool properties associated with the tools currently recorded in the current session. From the Cutting Tools Information dialog box, you can view or Print your Tool List.



From the Cutting Tools Information dialog box, you can view or Print your Tool List

3. Pick OK to close the dialog.

7.8.7 Cutter Compensation

Cutter compensation is used typically to compensate for the difference in the dimensions of the actual cutter used in machining and the cutter used for programming in TURN Module. For example, if the cutter used in programming in TURN Module has a tool nose radius of 0.02 inches and due to tool wear the actual tool nose radius is only 0.01 inches in size, you can compensate for this in the controller rather than having to re-program the operation in TURN Module again.

Enable Cutter Compensation

To enable Cutter Compensation in your toolpaths:

- 1. On the Global Parameters tab of the Turn operation, set Compensation to Auto/ON.
- 2. Set Adjust Register and Cutcom Register from the Parameters tab of the Create/Edit Tools dialog box.
- 3. Enable Cutter Compensation in your Post Processor (see below).

In the Post Processor

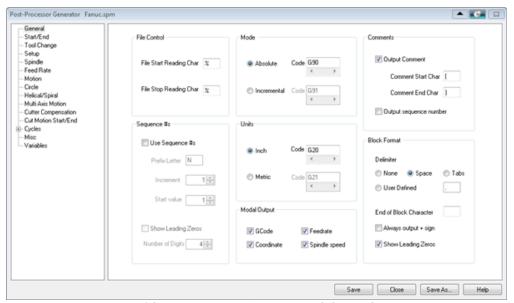
Specify the Cutter Compensation value and the Compensation Register in the controller (the controller needs to be capable of doing this).

1. From the Program tab of the Machining Browser, select



- 2. From the Set Post-Processor dialog box, select the Edit ... button located to the right of the Current Post Processor.
- 3. Enable Cutter Compensation from the Tool Change tab of the Post processor Generator dialog box.

- 1. From the Machining Browser, select and then select Post processor Generator...
- 4. Select the Post Processor and then pick Edit.
- Enable Cutter Compensation from the Tool Change tab of the Post processor Generator dialog box.



Dialog Box: Post-Process Generator, Tool Change tab

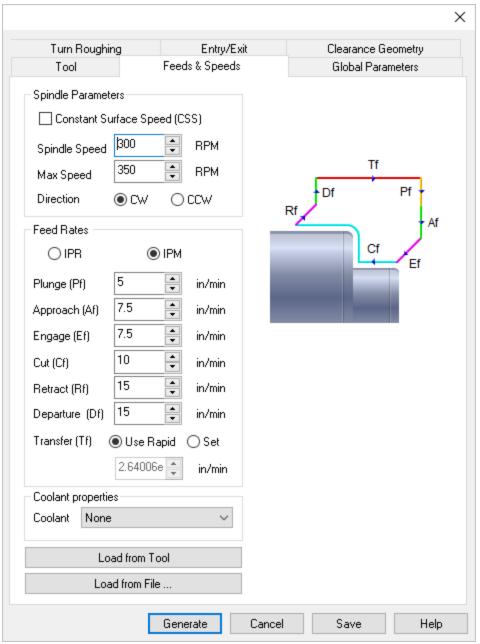
A few things to watch out for:

- ! Cutter Compensation makes sense only in finishing operations. If you are using multiple passes in finishing, the compensation will be turned on only in the final pass.
- Make sure you are not using Zig-Zag cut traversal in the finishing methods that you want to turn compensation on.
- I Make sure you have a linear motion for the controller to turn on the compensation value on. Thus, in turn finishing, make sure there is a linear entry motion for the controller to be able to turn Compensation on.

7.9 Feeds & Speeds

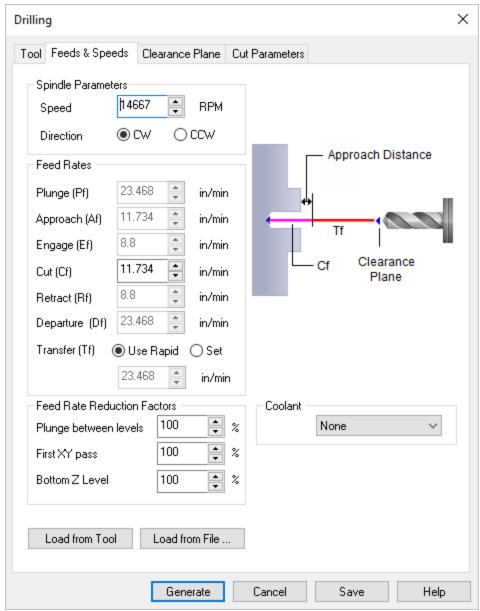
TURN Module allows setting of feeds and speeds to be used in the toolpaths via the Feeds/Speeds dialog. This dialog gives you the ability to set the following parameters:

Dialog Box: Feeds & Speeds for Turning operations



Dialog Box: Feeds & Speeds for Turning operations

Dialog Box: Feeds & Speeds for Hole Machining operations



Dialog Box: Feeds & Speeds for Hole Machining operations

Spindle Parameters

Constant Surface Speed (CSS)

This is the Spindle Speed Mode. If this box is checked, the mode is set to Constant Surface Speed (CSS). If unchecked, the mode is set to Constant Rotational Speed (CRS).

If the Constant Surface Speed is checked, the controller would automatically calculate and adjust the spindle speed based on the current diameter of the work-piece. If this calculated spindle speed is greater than the maximum spindle speed specified in your post, the spindle speed would be reduced to the maximum speed. Refer to the Spindle section of the Post-Processor Generator to ensure your Spindle Mode is set

correctly.

Spindle Speed

his is the rotational speed of the spindle expressed in RPM.

Surface Speed

Surface speed is set in units/min when Constant Surface Speed is selected. This is only applicable for turning inserts.

Max Speed

The maximum rotational speed of the spindle, in RPM. This is only applicable for turning inserts.

Direction

This determines the direction of spindle rotation and can be set to Clockwise or Counter Clockwise.

Feed Rates

Feedrate can be set in Units/Min or Units/Revolution for Turning Inserts.

Plunge (Pf)

This rate is the feed before the tool starts to engage in material. This is always vertical.

Approach (Af)

This is the feedrate used that prepares the cutter just before it starts engaging into material as it starts cutting. The approach motions are dependent on the method of machining.

Engage (Ef)

This is the feedrate used when the tool is performing an engage move. TURN Module sets this value to be 75% of the cutting speed.

Cut (Cf)

This is the feedrate used when the tool is cutting material

Retract (Rf)

The feedrate used when the tool is performing a retract move away from material. TURN Module sets this also to also be 75% of the cutting speed.

Departure (Df)

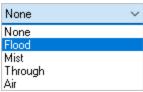
The feedrate used to retract the tool from the material.

Transfer (Tf)

This is the feedrate (in Units/Min), used for Transfer motions. Select Use Rapid to set this to the Transfer Feed value defined in the Feeds & Speeds section of the CAM Preferences dialog.



Here you can override the Coolant that is specified by the Tool. Coolant can be set to Flood, Mist, Through or Air. Coolant codes are defined in the post processor generator under Misc tab. Coolant Off is also supported as a variable that can be added where needed using the post-processor generator.



Coolant selections available

Feed Rates Reduction Factors (Hole Operations Only)

This sets Feed Rate Reduction Factors for Plunge Between Levels and the First XY pass.

Load from Tool

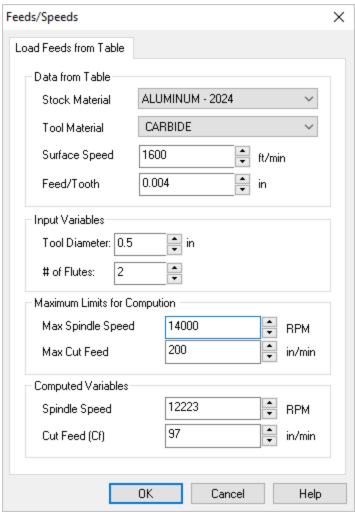
Feeds & Speeds are defined when a tool is created using Create/Edit Tools from the Machining Objects Browser. Selecting this button loads the Feeds & Speeds from the tool that is selected for the current machining operation.

Load from File

This loads the Feeds & Speeds values from the Feeds & Speeds Table file. This will display the Load Feeds from Table dialog box to make your selections.

Dialog Box: Load Feeds from Table

Selecting OK from this dialog transfers the spindle speed and cut feedrate to the Feeds & Speeds tab. The plunge, approach, engage, retract and departure feeds are determined using a percent of the cut feed. The percent to use for transferring the computed cut feed can be set under Feeds & Speeds Preferences.



Dialog Box: Load Feeds from Table

Data from Table

Stock Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Tool Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Surface Speed

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Feed/Tooth

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Input Variables

The input variables - Work Diameter is automatically loaded from the Stock Radius. Based on this parameter and the Variables Limits parameters, the program computes Spindle Speed and Cut Feedrate (Cf). measured in Unites/Revolution. Changing the spindle speed modifies the cut feedrate.

Maximum Limits for Computation

Here you can set the Max Spindle Speed and Max Cut Feed (Cf) values. Once these two values are set, the Spindle Speed and Cut Feed calculated by this dialog will not exceed these values even if you attempt to enter higher values into the Computed Variables fields. To exceed these values, change them here or you must edit the operation or tool parameters manually.

Computed Variables

The variables for Spindle Speed and Cut Feed (Cf) are computed for you based on the selections made in this dialog but will not exceed the values set in the Maximum Limits for Computation section of the dialog. These values are then assigned to the active toolpath operation or tool. You can override either of these variables and the other will update automatically. Since this dialog is a Feeds & Speeds Calculator, you cannot override both values. To do so, you must edit the operation or tool parameters manually.

Customizing Feeds & Speeds

TURN Module allows you to customize the feeds and speeds based on the stock material being machined, the material of the cutter employed and also the operation type. This is done by archiving your desired feeds and speeds settings in an external data file.

A default implementation of this table has been included with the RhinoCAM product and can be found in a folder called "Materials" under the product installation directory.

This xml contains the list of materials, texture, feeds and speeds. The file is located under Materials folder in RhinoCAM. (C:\ProgramData\MecSoft Corporation\RhinoCAM 20xx for Rhino x.x\Materials).

The Materials folder contains the following files

- FeedsSpeedsDataINCH.xml
- FeedsSpeedsDataMM.xml

The Feeds and speeds file is an .xml file format, which can be edited using any text editor to add newer materials.

These values can then be recalled at any time to compute the feeds/speeds to be used in the current program. The format for this file is shown below.

The format for this file is shown below:

```
<Units>Imperial</Units>
<FeedsSpeeds>
<Material>

<Name>Stock Material</Name>

<TextureFile>Texture Bitmap</TextureFile>

<FeedsSpeedsRecord>Operation type, Tool Material, Surface Speed, Feed per Tooth</FeedsSpeedsRecord>

</Material>

</FeedsSpeeds>
```

An example entry is shown below:

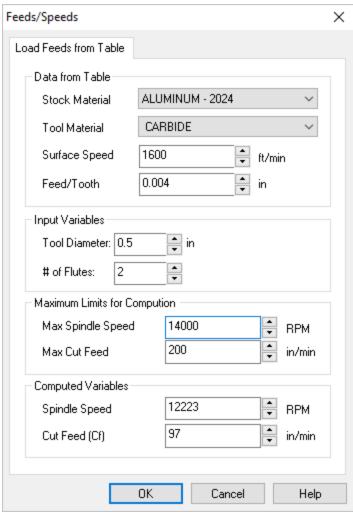
If part unit is set to Inches, TURN Module automatically loads FeedsSpeedsDataINCH.xml and when part unit is set to MM, FeedsSpeedsDataMM.xml is loaded.

7.9.1 Load from File

This loads the Feeds & Speeds values from the Feeds & Speeds Table file. This will display the Load Feeds from Table dialog box to make your selections.



Selecting OK from this dialog transfers the spindle speed and cut feedrate to the Feeds & Speeds tab. The plunge, approach, engage, retract and departure feeds are determined using a percent of the cut feed. The percent to use for transferring the computed cut feed can be set under Feeds & Speeds Preferences.



Dialog Box: Load Feeds from Table

Data from Table

Stock Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Tool Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Surface Speed

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Feed/Tooth

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Input Variables

The input variables - Work Diameter is automatically loaded from the Stock Radius. Based on this parameter and the Variables Limits parameters, the program computes Spindle Speed and Cut Feedrate (Cf). measured in Unites/Revolution. Changing the spindle speed modifies the cut feedrate.

Maximum Limits for Computation

Here you can set the Max Spindle Speed and Max Cut Feed (Cf) values. Once these two values are set, the Spindle Speed and Cut Feed calculated by this dialog will not exceed these values even if you attempt to enter higher values into the Computed Variables fields. To exceed these values, change them here or you must edit the operation or tool parameters manually.

Computed Variables

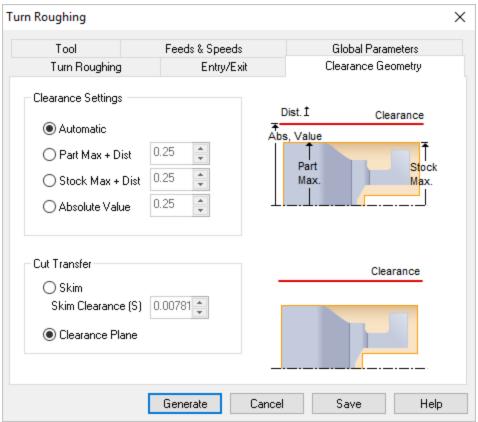
The variables for Spindle Speed and Cut Feed (Cf) are computed for you based on the selections made in this dialog but will not exceed the values set in the Maximum Limits for Computation section of the dialog. These values are then assigned to the active toolpath operation or tool. You can override either of these variables and the other will update automatically. Since this dialog is a Feeds & Speeds Calculator, you cannot override both values. To do so, you must edit the operation or tool parameters manually.

7.10 Clearance Plane

The clearance plane is a plane from which the approach motions start and retract motions end. After retracting, the tool moves rapidly along this plane to the position of the next engage. This plane is typically a certain safe distance above the part geometry. Typically you would define this plane at a certain safety distance above the part geometry. This is done to prevent the tool from touching the part being machined during transfer motions since these motions usually use a very fast or rapid feed rate.

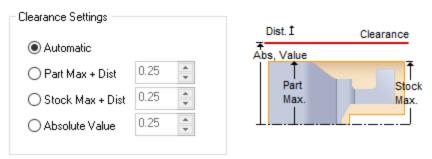
By default (Automatic option), the clearance level is calculated by adding a safety distance to the extreme point (depending whether Outer Diameter, Inner Diameter or Face is machined) found on both part and stock geometry. You can set the clearance level to be a set distance from either the part or stock, or enter the absolute Z level.

Dialog Box: Clearance Geometry for Turning operations



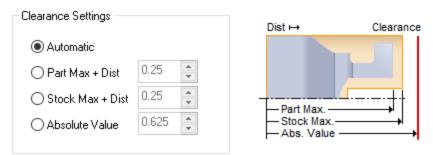
Dialog Box: Clearance Geometry for Turning operations

Dialog Box: Turn OD Clearance



Turn OD Clearance

Dialog Box: Turn Face Clearance



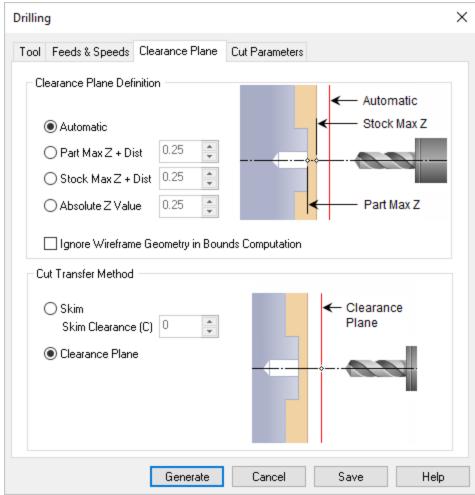
Turn Face Clearance

Dialog Box: Turn ID Clearance



Turn ID Clearance

Dialog Box: for Hole Machining operations



Dialog Box: Clearance Plane tab, Turn Reverse Boring

Clearance Settings

Automatic

The system determines the clearance height based on the part and stock geometry.

Part Max + Dist

Uses Part maximum plus the specified distance for clearance height.

Stock Max + Dist

Uses Stock maximum plus the specified distance for clearance height. If stock geometry does not exist, it would use the maximum height of the part geometry.

Absolute Value

Uses the specified distance for clearance height.

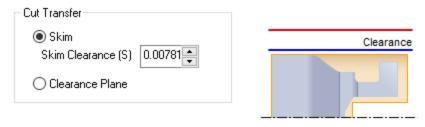
For Turning operations, the User Interface for clearance settings are automatically set for OD, ID or Face depending on the approach type specified under global parameters.

For Hole Machining operations, the clearance plane is normal to the Z axis.

Cut Transfer

You can also control the transfer motions during cutting. When the cutter has finished cutting in one region and needs to transfer to another region to begin cutting, it can either be instructed to move to the clearance plane and then perform the transfer motion to the next cut location or it could do a skim motion. In the skim motion, the system automatically determines the safe height by taking into consideration the condition of the part model and using this Skim Clearance (S) value specified as the height to perform the transfer motions.

Dialog Box: Cut Transfer Skim



Cut Transfer Skim

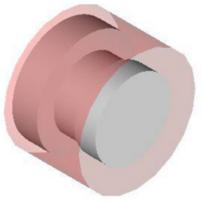
Dialog Box: Cut Transfer Clearance Plane



Cut Transfer Clearance Plane

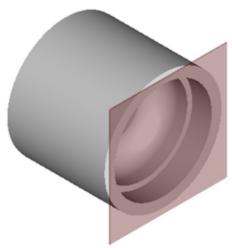
Clearance Plane for Turn OD operations

When the clearance plane dialog is active, specifying a clearance plane definition, displays the clearance plane on the part in the view port.



Clearance Plane for Turn OD operations





Clearance Plane for Hole Machining operations

7.11 Knowledge Base

The MILL and TURN modules includes powerful Knowledge Base functionality that makes "push button" programming a reality. You can archive an entire machining strategy specific to a certain class of parts in a Knowledge Database (also referred to as a K-Base) and then optionally assign Geometry Selection Rules that are applied automatically when toolpath operations are selected for use from the Knowledge Base.

In a family of parts situation, where the same set of machining operations and tools can be applied to machine these parts, it would be most appropriate to archive this processes in a K-base file and then apply it across all of the parts in this family. Another situation where this feature can be used is in shop floor programming. Experienced programmers can determine the sequence of operations to be used to machine a certain class of parts and create a K-base file capturing that knowledge for automation purposes.

More about Knowledge Bases

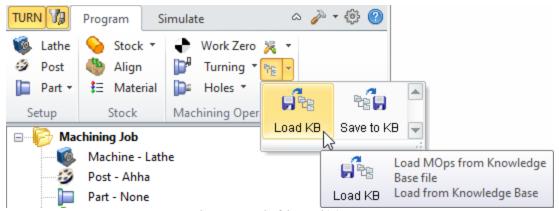
Once these K-base files are thoroughly debugged, operators at the shop floor can then load and generate toolpaths automatically. Doing this not only increases the throughput but also the productivity of the entire manufacturing team, resulting in dramatic cost savings for the enterprise.

The machining strategy can include the sequence of machining processes used, the specific parameters used in each machining processes as well as the Geometry Selection Rules.

7.11.1 Create Knowledge Base

To create a Knowledge Base, start creating machining operations. Once created these machining operations can be re-sequenced if necessary. When completely satisfied with the machining operations used and their sequence, click Knowledge Base and Save to KB from the Program tab or pick the Save to Knowledge Base option by right clicking on Machining Operations and selecting the Save to Knowledge Base option. If no Geometry Selection Rules have been defined you are asked if you wish to define them.

From the Program tab of the Machining Browser



From the Program tab of the Machining Browser

by right click on Machining Operations

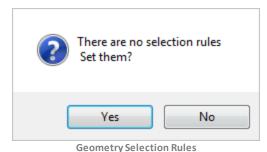
Select the Machining Job or one or more operations, then right-click and select Save to Knowledge Base.



by right click on Machining Operations

Geometry Selection Rules (MILL ONLY)

If there are no Geometry Selection Rules set for the Knowledge Base the following message is displayed. If you wish to set Global selection rules for the Knowledge Base, pick Yes to display the Geometry Selection Rules dialog. You can assign Geometry Selection Rules for each operation in the Knowledge Base after it is loaded into another part. See Knowledge Base Rules for information about setting Selection Rules for a Knowledge Base.



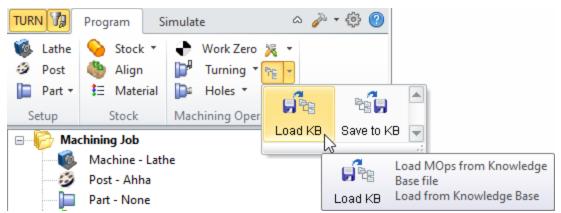
7.11.2 Load Knowledge Base

A Knowledge Base file must be created before you can Load it. See Create a Knowledge Base for information about creating one. Once created, you can Load the Knowledge Base and re-use it in any other part file that may be appropriate. You can Load one or more Knowledge Base files into the currently active part. When a Knowledge Base is loaded, its operations are automatically appended to the existing list of machining operations shown in the K-Bases tab of the Machining Objects Browser.

A Knowledge Base <u>DOES NOT</u> have associated toolpaths. It contains the Knowledge parameters and the Geometry Selection Rules for machining. Once loaded, you then Drag & Drop operations from the Knowledge Base from the K-Bases tab into your Setup in the Machining Browser. If Geometry Selection Rules have been set in the Knowledge Base, they are applied automatically when the toolpath operations in your Setup are Generated.

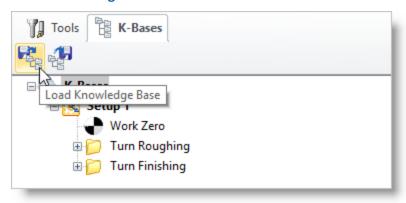
You can load a Knowledge Base either from the Machining Browser or the K-Bases tab of the Machining Objects Browser. Both methods are shown below:

Load a Knowledge Base from the Machining Browser



To Load a Knowledge Base from Machining Browser

Load a Knowledge Base from the K-Bases tab



To Load a Knowledge Base from the K-Bases tab of the Machining Objects Browser

7.11.3 Apply a Knowledge Base

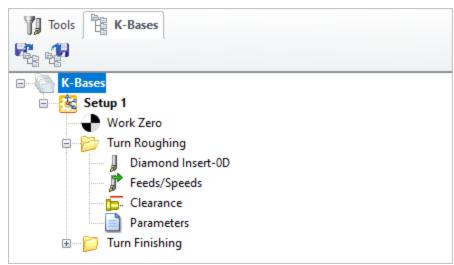
After a Knowledge Base is Loaded into the K-Bases tab of the Machining Objects Browser you can apply its operation definitions and selection rules to any current Setup in the Machining Browser.

Basic Work Flow

- 1. Open a part file containing operations to use to create your Knowledge Base.
- 2. Create a Knowledge Base file.
- 3. Open a part that you want to apply the Knowledge Base to.

- 4. Load the Knowledge Base from the K-Bases tab of the Machining Objects Browser.
- 5. When asked if you want to set rules, pick No.
- 6. If desired, defined selection rules after the Knowledge Base is Loaded into the K-Bases tab.
- 7. Drag & Drop operations from the K-Bases into your Setup.
- 8. Open each operation in the Setup, assign Control Geometry and Regenerate.

Knowledge Base is Loaded

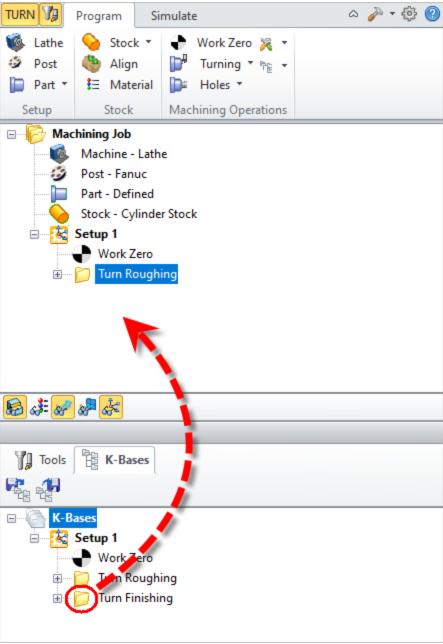


K-Bases tab of the Machining Objects Browser

Drag & Drop Operations from the Knowledge Base

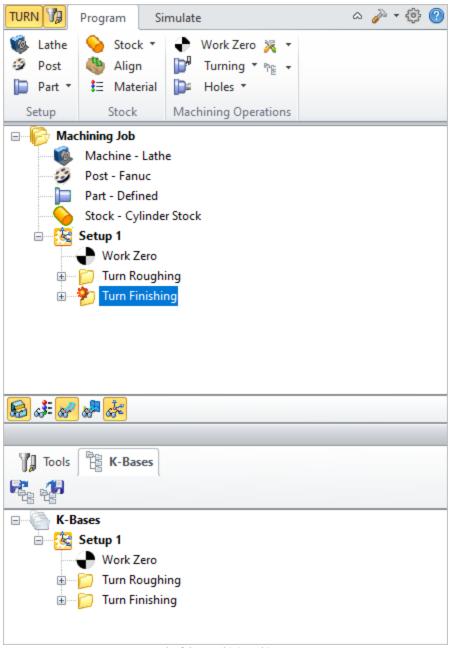
Expanding an operation under the K-Bases tab displays the Selection Rules, Tool, Feeds/Speeds, Clearance and Parameters for that operation type in the Knowledge Base.

You can Drag & Drop an operation type from the K-Bases tab up to your current Setup in the Machining Browser for programming.



K-Bases tab of the Machining Objects Browser

The operation is now available under the Machining Browser. Once you have defined the part geometry, you can edit the operation from the Machining Browser and generate the toolpath.



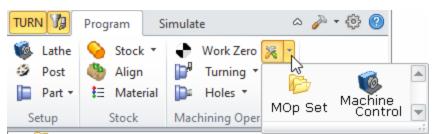
K-Bases tab of the Machining Objects Browser

! Drag & Drop the same operation from Machining Objects Browser to the Machining Browser multiple times, creates copies of the same operation.

7.12 Create Miscellaneous Operations



Mop Sets and Machine Control operations are grouped under miscellaneous operations. These can be found under Program tab in Machining Browser.



Create Miscellaneous Operations Menu Item

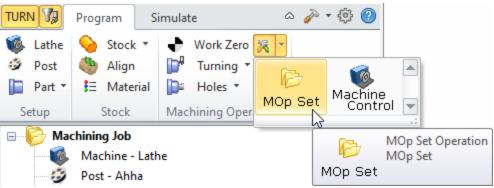
7.12.1 Mop Set



This feature allows you to group operation to a folder called Machining Operation Set. This can be useful where you would like to group operations by type or by tool. You can then post process machining operations by selecting a Mop Set.

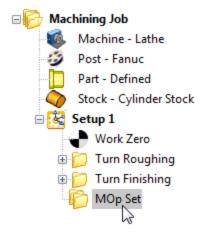
Selecting Mop Set from Create Miscellaneous Operations under Program tab creates a Mop Set folder in the Machining Browser.

Machining Operation Set (Mop Set) Menu Item



Machining Operation Set (MOp Set) Menu Item

Mop Set folder in the Machining Browser

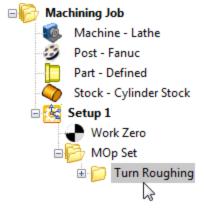


Selecting MOp Set from Create Miscellaneous Operations under Program tab, creates a MOp Set folder in the browser.

Create a new operation under a Mop Set

You can now create machining operations or move existing machining operations under Mop Set folder.

To create a new operation under a Mop Set, select the Mop Set under the Machining Browser and then choose the Turning or Hole Machining operation. The operation would appear below the Mop Set and is a level into the Job tree structure.



create a new operation under a MOp Set

Move existing operations to a Mop Set

To move existing operations, select a machining operation, drag and drop it into the Mop Set so the machining operation appears one level into the Job tree. Multiple Mop Sets can be created and operations can be grouped under each Mop Set.

7.12.2 Machine Control



This operation allows you to output a set of code or instructions for the machine. These can be inserted at the start, end and between machining operations. The

instruction set for these operations are defined in the post processor. This eliminates the need for inserting codes manually in the posted code.

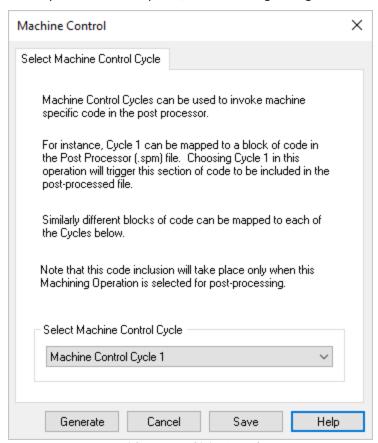
Machining Control Operation Menu Item



Machining Control Operation Menu Item TURN Module)

Dialog Box: Machining Control

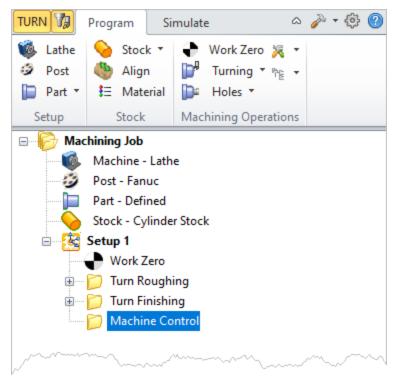
When you select this option, the following dialog will be invoked.



Dialog Box: Machining Control

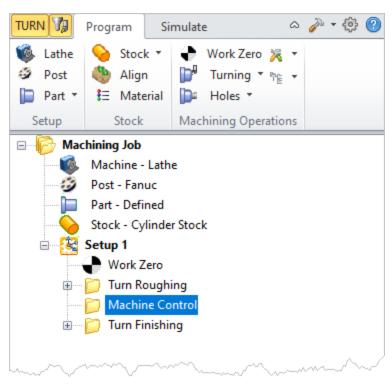
The cycle code for each cycle is specified in the post processor file. Selecting a cycle triggers this section of code to be included in the post processed file.

Select a Cycle and click Generate. A Machine Control operation is now created and listed under Setup.



Select a Cycle and click Generate. A Machine Control operation is now created and listed under Setup

Post processing the operation will output the Machine Control code specified in the post processor file to the posted output file. Here is an example that shows Machine Control cycle inserted between two machining operations.

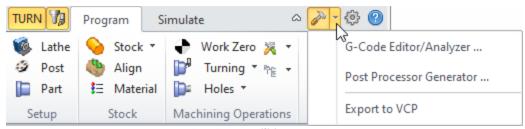


example that shows Machine Control cycle inserted between two machining operations

7.13 Tools and Utilities



CAM system Tools and Utilities provides access to G-Code Editor/Analyzer and Post process generator. To access the functions, select the Tools option under the Machining Browser.



CAM System Utilities Menu Item

Loads the NC editor. By default this is set to notepad.

This is specified under Program to send posted file to which can be found in Set Post-Processor Options dialog.

Refer to Set Post Options for additional information.

Post Process Generator - This loads Post Processor Generator utility.

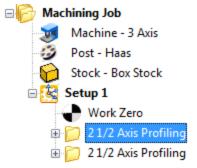
7.13.1 Save As Defaults

Save As Defaults allows you to set default parameters for machining operations. This allows the reuse of the machining parameters without having to enter the same parameters when creating new machining operations on same part or new part files.

To Save As Defaults:



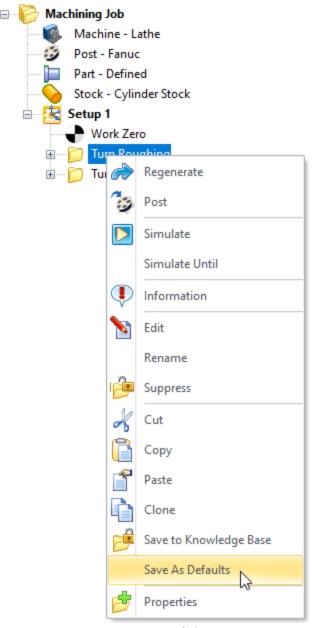
Create or Select a machining operation under the Program tab in Machining Browser.



Step 1: Create or Select a Machining Operation

Step 2: Save As Defaults

Right mouse button click on a machining operation and select Save As Defaults.



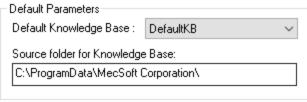
Step 2: Save As Defaults

Step 3: Specify a File Name

This displays a Save As dialog when a default knowledge base is not specified under Set Machining Preferences.

Specify a file name Click Save. This creates a default knowledge base for the profiling operation and is saved to the file name you chose.

The saved knowledge base is then automatically set as the default knowledge base to load under Machining Preferences and the parameters defined in this knowledge base are used when creating new machining operations.



Set Machining Preferences

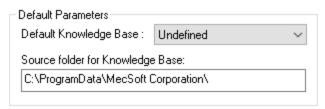
Step 4: Things to Remember

- Save As Defaults can be set for all machining operation types.
- ! Once a default Knowledge base is specified under Machining Preferences, selecting Save as Defaults for other machining operation types, adds other operation parameters to the same Default knowledge base file.
- If a default for a specific operation type does not exist, the system defaults are loaded.
- ! Changing the parameters for the above machining operation and saving as defaults overwrites the default parameters with the new one.
- ! Multiple Default Knowledge bases can be created and saved.
 This could come in handy when machining different types of materials, which requires different cutting parameters. You could create one for machining Steel, Aluminum, Wood, etc...

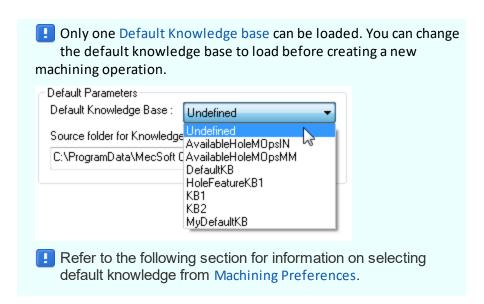
Step 5: To Create a NEW Default Knowledge Base

To create a new default knowledge base:

a. Under Machining Preferences, change the Default Knowledge Base to load to Undefined.

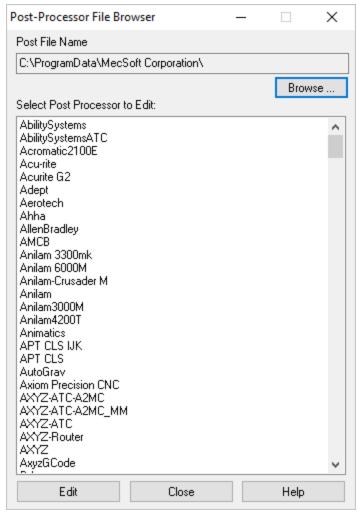


- b. Select a machining operation under the Mops browser, right mouse button click and select Save As Defaults.
- c. Specify a new file name and click Save. The saved knowledge base is now set as the default knowledge base to load under Machining Preferences and the parameters defined in the knowledge base is used when creating new machining operation.



7.13.2 Post Process Generator ...

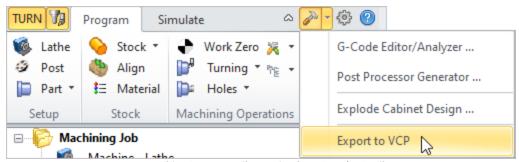
This utility can be used to edit and set up new post-processors to be used in RhinoCAM. The default location of the Post File Names is selected. Pick Browse ... to select a different location. Select a post processor from the list and click Edit to display the Post Processor Generator dialog box.



Dialog Box: Post Process Generator

7.13.3 Export to VCP

You can use this utility to export the current RhinoCAM *.3dm part file (*.3dm) to a VisualCADCAM part file (*.vcp) retaining all part geometry and existing toolpath operation definitions.



Export RhinoCAM Parts Files to VisualCADCAM *.VCP Files



Creating Turning Operations

The section details all of the Turning operation types that can be created in TURN Module.

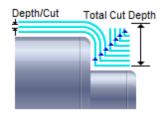
8.1 Roughing



This is the RhinoCAM TURN Module's principal method of roughing, in which the material is roughed out in multiple cuts. This type of machining is very efficient for removing large volumes of material, and is typically performed with

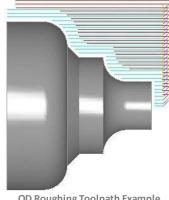
a large radius tool. Roughing is typically followed by finishing toolpaths.

Both part and stock geometry are used to determine the regions that can be safely machined. Roughing can be of 3 types: OD Roughing, ID Roughing, and Front Facing (Face Roughing).

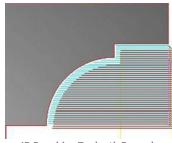


Turn Roughing Operation

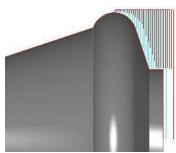
Turn Roughing Examples







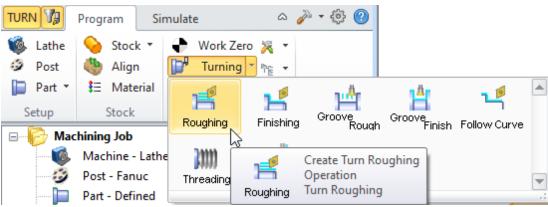
ID Roughing Toolpath Example



Face Roughing Toolpath Example

Turn Roughing Menu Item

The Turn Roughing toolpath method is invoked by selecting the Program tab, clicking on the Turning button in the Machining Browser and selecting the Roughing operation.

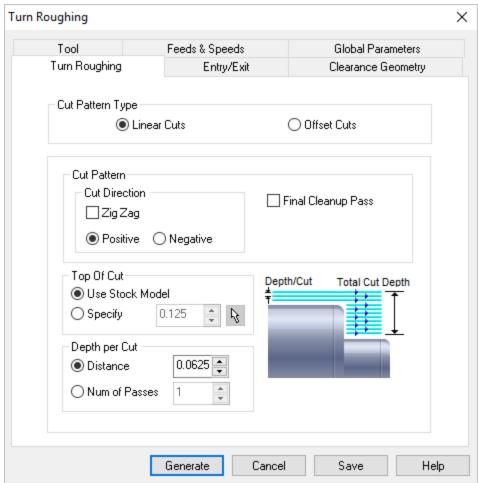


Turn Roughing Menu Item

Dialog Box: Turn Roughing

The toolpath generated depends on user-defined parameters. The various parameters that you can set can be seen in the dialog box that is invoked when you choose the Turn Roughing operation. This dialog box is shown below.

This dialog has six tabs. Each tab defines a set of parameters that you can specify. The sections below describe them in detail.

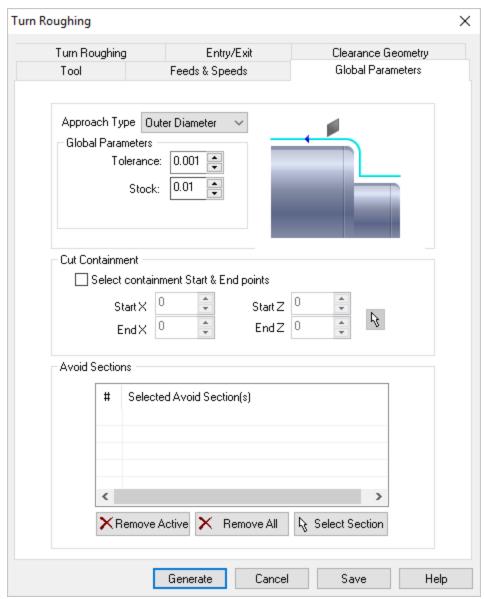


Dialog Box: Turn Roughing

8.1.1 Global Parameters

The following dialog allows you to set the Global Parameters for Turn Roughing operations. You can set the Approach Type, Global Parameters and Cut Containment and Avoid Sections via this property page.

Dialog Box: Global Parameters tab, Turn Roughing



Dialog Box: Global Parameters tab, Turn Roughing

Approach Type

Approach Type

Allows user to choose between Outer Diameter (OD), Front Facing and Inner Diameter (ID). The toolpaths are generated for the selected approach types.

In rouging and finishing operations, for tools with OD orientation, the approach type can be set to Outer Diameter or Front Facing. For tools with ID orientation, the approach type is automatically set to Inner Diameter.

Global Parameters section allows you to set the tolerance value to be used in machining. A uniform thickness or stock that needs to be left around the part can be specified here.

Tolerance

This is the allowable deviation from the actual part geometry plus the Stock layer (if any).

Stock (Roughing Operations Only)

This is the layer of material that will remain around the part after the toolpath is completed. Generally Roughing operations leave a thin layer of stock, unlike finishing operations where this value is usually set to zero.

Cut Containment

This allows you to select an area to contain the toolpath. This is useful in cases where a section of the part needs to be machined. This is done by selecting the check box for Select containment Start & End points.



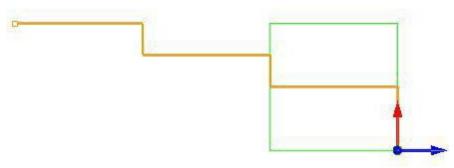
Cut Containment

You can either input the X and Z coordinate values that represent 2 corners of a containment rectangle or use the pick option to graphically select 2 corners of a rectangle for containment.

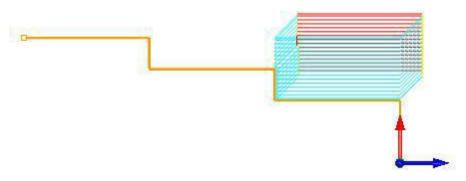
You can use the object snap tools from the status bar to snap to points on the part geometry.

Cut Containment Examples for Turn Roughing

A containment rectangle is displayed in the viewport.

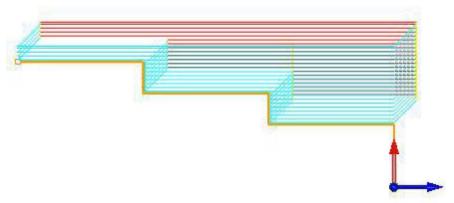


Cut Containment Examples for Turn Roughing



Cut Containment Examples for Turn Roughing

If containment is not specified, the roughing toolpath is generated for the turn part geometry based on the approach type and the defined stock geometry.



Turn Roughing Example without Cut Containment

Avoid Sections

This allows user to select areas to be excluded from the turn part geometry for toolpath computation. This is done by selecting 2 points on the part geometry. A line is inserted between the 2 selected points as avoid region and this now becomes part of your turn part geometry. One or more avoid areas can be selected.

Defining Avoid Sections

To select an area to avoid:

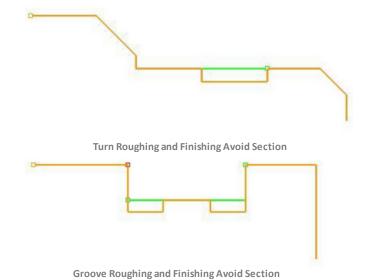
From the Global Parameters tab in the Turn Operations dialog box, click Select Section under Avoid Sections and pick 2 points on the part geometry. The selection is now displayed under avoid selection.

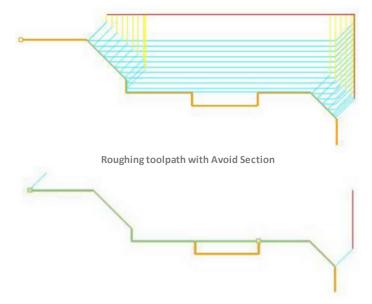
Selecting an Avoid Region from the list highlights it on the part geometry.



Avoid Sections, Global Parameters tab of Turn Operations dialog box

Examples for various Turn Operations



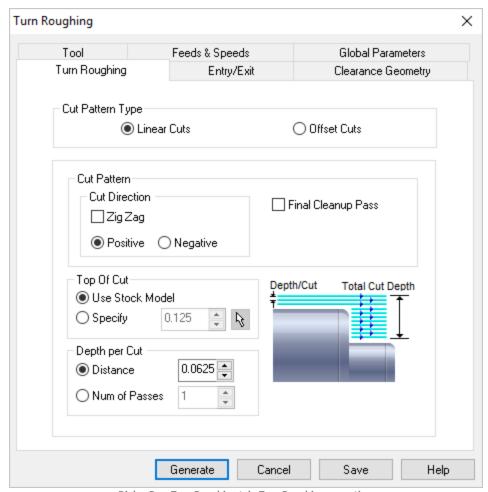


Finishing toolpath with Avoid Section

8.1.2 Turn Roughing Options

The following dialog allows you to set Turn Roughing parameters. In this tab, parameters like the Cut Pattern Type, Cut Pattern Direction and the Depth per cut can be specified.

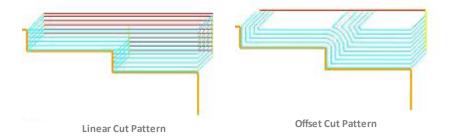
Dialog Box: Turn Roughing tab



Dialog Box: Turn Roughing tab, Turn Roughing operations

Cut Pattern Type

This defines the type of path that the tool will follow at each cut level. You can choose a linear cut pattern where the tool will always traverse in linear cuts or an Offset cut pattern where the tool will traverse in successive uniform offsets of the part shape.

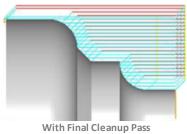


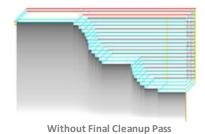
Cut Direction

This can be specified as Positive, Negative or ZigZag.

Final Cleanup Pass

This adds a finish pass at the end of the roughing passes.





Top of Cut

The top value for the cut can be either specified or determined using the internal algorithms of TURN Module.

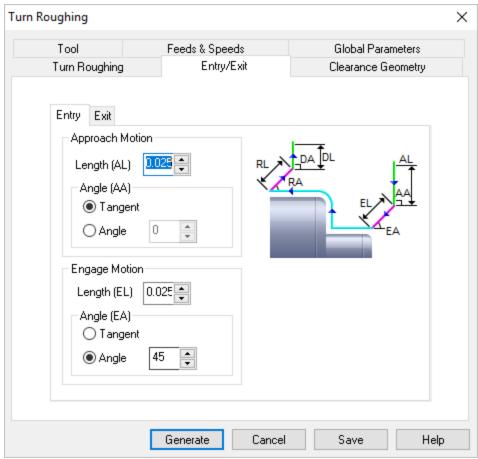
Depth per Cut

The depth per cut can be either specified as the actual depth per cut or as the number of passes required to remove the stock material to manufacture the final part.

8.1.3 Entry/Exit

The following dialog allows you to set Entry/Exit Parameters for Turn Roughing operations. Entry and Exit determines the way in which tool enters and leaves the part geometry. TURN Module allows you to specify how the cutter approaches, engages, retracts and departs when starting and stopping a cut.

Dialog Box: Entry/Exit tab



Dialog Box: Entry/Exit tab, Turn Roughing operations

Entry Tab

The Entry tab (shown in the dialog box above) consists of Approach and Engage. You can set different feeds for plunge, approach, engage, cut, retract and depart moves. The tool moves to the position above the approach point with a plunge feed, then uses the approach feed rate for the vertical approach motion and engage feed rate for the engage motion.

The approach can be either Tangential or at an angle to the Engage motion. This is followed by the engage motion that can be Tangential or at an angle.

Exit Tab

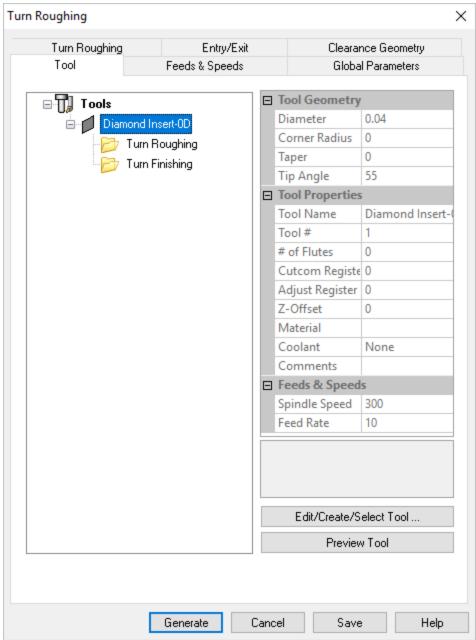
Similarly the Exit motion consists of a Retract motion followed by a departure motion. The retract motion can be either Tangential or at an angle. The departure motion can be either Tangential or at an angle to the Retract motion.

8.1.4 Tool

The following dialog allows you to select the appropriate tool for the Turn Roughing operation. The Tools in Session are listed on the left. Expanding the Tool tree will list the current operations

assigned to that tool. The geometry parameters of the selected tool are displayed to the right. See Create Edit Tools for more information.

Dialog Box: Tool tab



Dialog Box: Tool tab, Turn Roughing operations

Edit/Create/Select Tool ...

If there are no Tools listed, select this button to Create a new tool. If a tool is listed and selected by default, select this button to Edit the parameters for that tool or to

Select a different tool for the current operation.

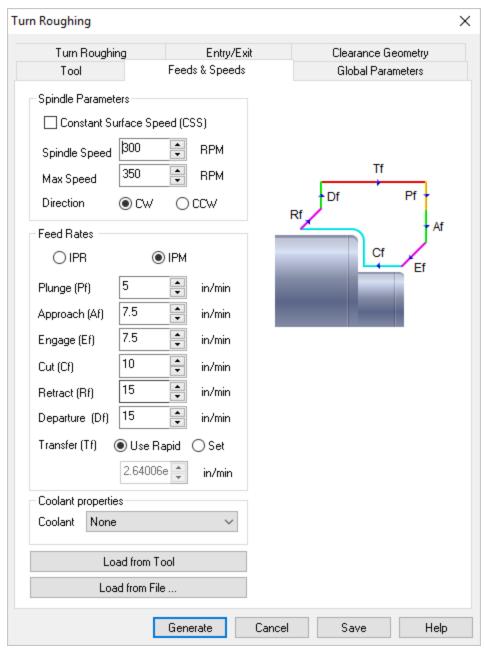


Preview Tool - Select this button to display a graphical representation of the currently selected tool. This is the same Preview of the tool that you see displayed in the Edit/Create/Select Tool dialog.

8.1.5 Feeds & Speeds

The following dialog allows you to select the appropriate Feeds & Speeds for the Turn Roughing operation. In this tab, Spindle Parameters and Feed Rates can be specified. Speeds & Feeds can also be loaded from a File or from the Tool.

Dialog Box: Feeds & Speeds tab



Dialog Box: Feeds & Speeds tab, Turn Roughing

Spindle Parameters

Constant Surface Speed (CSS)

This is the Spindle Speed Mode. If this box is checked, the mode is set to Constant Surface Speed (CSS). If unchecked, the mode is set to Constant Rotational Speed (CRS).

If the Constant Surface Speed is checked, the controller would automatically calculate and adjust the spindle speed based on the current diameter of the work-piece. If this calculated spindle speed is greater than the maximum spindle speed specified in your

post, the spindle speed would be reduced to the maximum speed. Refer to the Spindle section of the Post-Processor Generator to ensure your Spindle Mode is set correctly.

Spindle Speed

his is the rotational speed of the spindle expressed in RPM.

Surface Speed

Surface speed is set in units/min when Constant Surface Speed is selected. This is only applicable for turning inserts.

Max Speed

The maximum rotational speed of the spindle, in RPM. This is only applicable for turning inserts.

Direction

This determines the direction of spindle rotation and can be set to Clockwise or Counter Clockwise.

Feed Rates

Feedrate can be set in Units/Min or Units/Revolution for Turning Inserts.

Plunge (Pf)

This rate is the feed before the tool starts to engage in material. This is always vertical.

Approach (Af)

This is the feedrate used that prepares the cutter just before it starts engaging into material as it starts cutting. The approach motions are dependent on the method of machining.

Engage (Ef)

This is the feedrate used when the tool is performing an engage move. TURN Module sets this value to be 75% of the cutting speed.

Cut (Cf)

This is the feedrate used when the tool is cutting material

Retract (Rf)

The feedrate used when the tool is performing a retract move away from material. TURN Module sets this also to also be 75% of the cutting speed.

Departure (Df)

The feedrate used to retract the tool from the material.

Transfer (Tf)

This is the feedrate (in Units/Min), used for Transfer motions. Select Use Rapid to set this to the Transfer Feed value defined in the Feeds & Speeds section of the CAM Preferences dialog.

Coolant

Here you can override the Coolant that is specified by the Tool. Coolant can be set to Flood, Mist or Through. Coolant codes are defined in the post processor generator under Misc tab.

Load from Tool

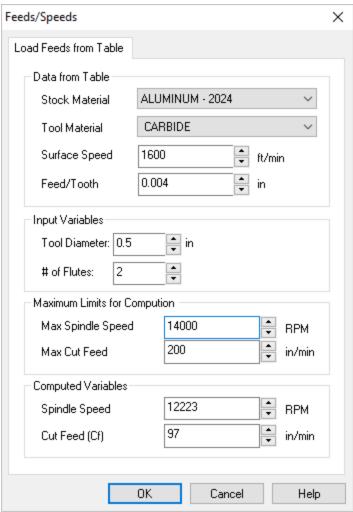
Feeds & Speeds are defined when a tool is created using Create/Edit Tools from the Machining Objects Browser. Selecting this button loads the Feeds & Speeds from the tool that is selected for the current machining operation.

Load from File ...

This loads the Feeds & Speeds values from the Feeds & Speeds Table file. This will display the Load Feeds from Table dialog box to make your selections.

Dialog Box: Load Feeds from Table

Selecting OK from this dialog transfers the spindle speed and cut feedrate to the Feeds & Speeds tab. The plunge, approach, engage, retract and departure feeds are determined using a percent of the cut feed. The percent to use for transferring the computed cut feed can be set under Feeds & Speeds Preferences.



Dialog Box: Load Feeds from Table

Data from Table

Stock Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Tool Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Surface Speed

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Feed/Tooth

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Input Variables

The input variables - Work Diameter is automatically loaded from the Stock Radius. Based on this parameter and the Variables Limits parameters, the program computes Spindle Speed and Cut Feedrate (Cf). measured in Unites/Revolution. Changing the spindle speed modifies the cut feedrate.

Maximum Limits for Computation

Here you can set the Max Spindle Speed and Max Cut Feed (Cf) values. Once these two values are set, the Spindle Speed and Cut Feed calculated by this dialog will not exceed these values even if you attempt to enter higher values into the Computed Variables fields. To exceed these values, change them here or you must edit the operation or tool parameters manually.

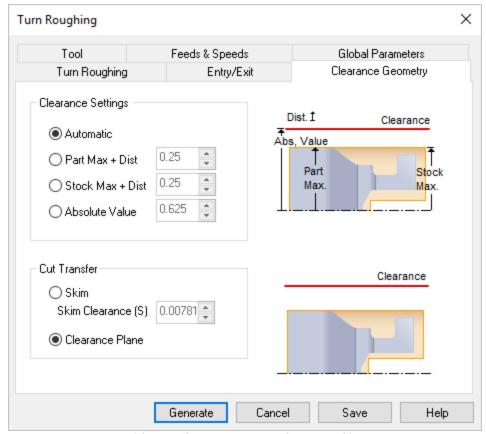
Computed Variables

The variables for Spindle Speed and Cut Feed (Cf) are computed for you based on the selections made in this dialog but will not exceed the values set in the Maximum Limits for Computation section of the dialog. These values are then assigned to the active toolpath operation or tool. You can override either of these variables and the other will update automatically. Since this dialog is a Feeds & Speeds Calculator, you cannot override both values. To do so, you must edit the operation or tool parameters manually.

8.1.6 Clearance

The following dialog allows you to select the appropriate Clearance Geometry for the Turn Roughing operation. In this tab, Clearance Settings and Cut Transfer parameters can be specified. See Clearance Plane for additional information.

Dialog Box: Clearance Geometry tab



Dialog Box: Clearance Geometry tab, Turn Roughing

Clearance Settings

Automatic

The system determines the clearance height based on the part and stock geometry.

Part Max + Dist

Uses Part maximum plus the specified distance for clearance height.

Stock Max + Dist

Uses Stock maximum plus the specified distance for clearance height. If stock geometry does not exist, it would use the maximum height of the part geometry.

Absolute Value

Uses the specified distance for clearance height.

For Turning operations, the User Interface for clearance settings are automatically set for OD, ID or Face depending on the approach type specified under global parameters.

For Hole Machining operations, the clearance plane is normal to the Z axis.

Cut Transfer

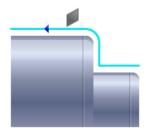
You can also control the transfer motions during cutting. When the cutter has finished cutting in one region and needs to transfer to another region to begin cutting, it can either be instructed to move to the clearance plane and then perform the transfer motion to the next cut location or it could do a skim motion. In the skim motion, the system automatically determines the safe height by taking into consideration the condition of the part model and using this Skim Clearance (S) value specified as the height to perform the transfer motions.

8.2 Finishing



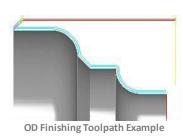
This is one of the most commonly used machining processes. The part is rotated while a single point cutting tool is moved parallel to the axis of rotation following the contour of the geometry. Finishing can be

done on the external surface of the part (OD, Face) as well as internally (boring). You can define offsets so that the tool makes multiple passes relative to the regions. Finishing is typically done after a Roughing operation, or it can be used alone.

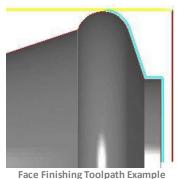


Turn Finishing Operation

Turn Finishing Examples

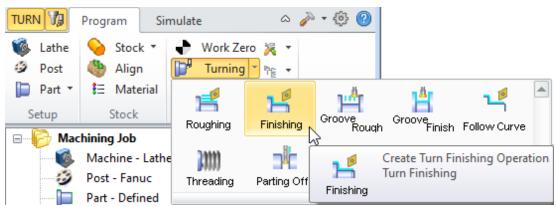






Turn Finishing Menu Item

The Turn Finishing toolpath method is invoked by selecting the Program tab, clicking on the Turning button in the Machining Browser and selecting the Finishing operation.

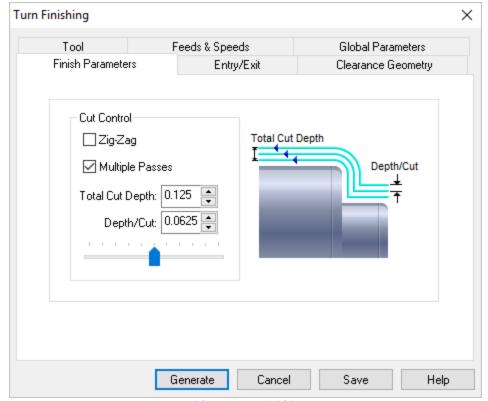


Turn Finishing Menu Item

Dialog Box: Turn Roughing

This section describes the various parameters that you can set to execute this machining operation. The dialog that is invoked when you choose this toolpath method is shown below:

This dialog has six tabs. Each tab defines a set of parameters that you can specify. The sections below describe them in detail.

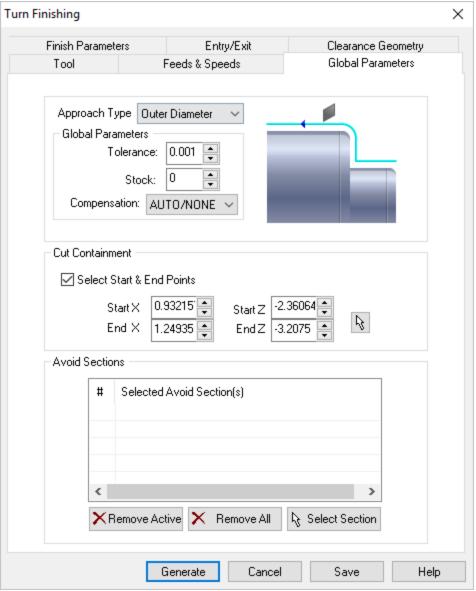


Dialog Box: Turn Finishing

8.2.1 Global Parameters

The following dialog allows you to set Global Parameters for Turn Finishing operations. You can set the Approach Type, Global Parameters and Cut Containment and Avoid Sections via this property page.

Dialog Box: Global Parameters tab



Dialog Box: Global Parameters tab, Turn Finishing

Approach Type

Approach Type

Allows user to choose between Outer Diameter (OD), Front Facing and Inner Diameter

(ID). The toolpaths are generated for the selected approach types.

In rouging and finishing operations, for tools with OD orientation, the approach type can be set to Outer Diameter or Front Facing. For tools with ID orientation, the approach type is automatically set to Inner Diameter.

Global Parameters section allows you to set the tolerance value to be used in machining. A uniform thickness or stock that needs to be left around the part can be specified here.

Tolerance

This is the allowable deviation from the actual part geometry plus the Stock layer (if any).

Stock (Roughing Operations Only)

This is the layer of material that will remain around the part after the toolpath is completed. Generally Roughing operations leave a thin layer of stock, unlike finishing operations where this value is usually set to zero.

Compensation

This stands for cutter compensation. You can turn this on by selecting from the drop down menu. The cutter compensation direction, Left or Right, is determined by the Cut Direction (Climb or Conventional). Refer to the following section for additional information - Cutter Compensation

Cut Containment

This allows you to select an area to contain the toolpath. This is useful in cases where a section of the part needs to be machined. This is done by selecting the check box for Select containment Start & End points.



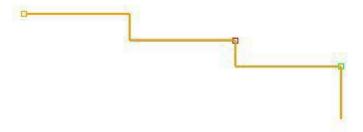
Cut Containment

You can either input the X and Z coordinate values that represent 2 corners of a containment rectangle or use the pick option to graphically select 2 corners of a rectangle for containment.

You can use the object snap tools from the status bar to snap to points on the part geometry.

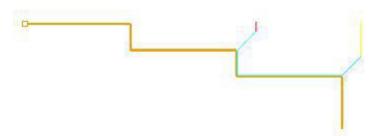
Cut Containment Examples for Turn Roughing

The start and end points are displayed on the part geometry. The start point is represented in **Green** color and end point in **Red**.



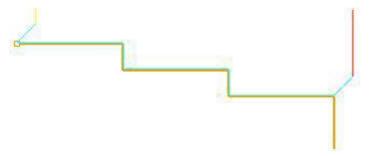
Cut Containment Examples for Turn Finishing

The finishing toolpath is contained between start and end points and cut direction of the toolpath is from the start to end point. The selection of start and end points can also be used to determine the cut direction.



Cut Containment Examples for Turn Finishing

If a containment is not specified, the finishing toolpath is generated for the turn part geometry based on the approach type and the part geometry.



Cut Containment Examples for Turn Finishing

Avoid Sections

This allows user to select areas to be excluded from the turn part geometry for toolpath computation. This is done by selecting 2 points on the part geometry. A line is

inserted between the 2 selected points as avoid region and this now becomes part of your turn part geometry. One or more avoid areas can be selected.

Defining Avoid Sections

To select an area to avoid:

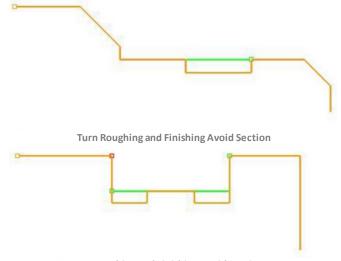
From the Global Parameters tab in the Turn Operations dialog box, click Select Section under Avoid Sections and pick 2 points on the part geometry. The selection is now displayed under avoid selection.

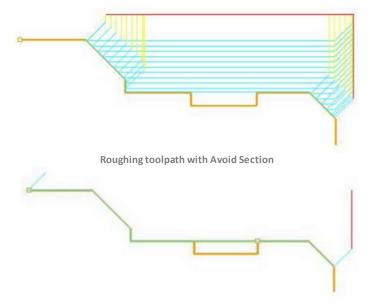
Selecting an Avoid Region from the list highlights it on the part geometry.



Avoid Sections, Global Parameters tab of Turn Operations dialog box

Examples for various Turn Operations



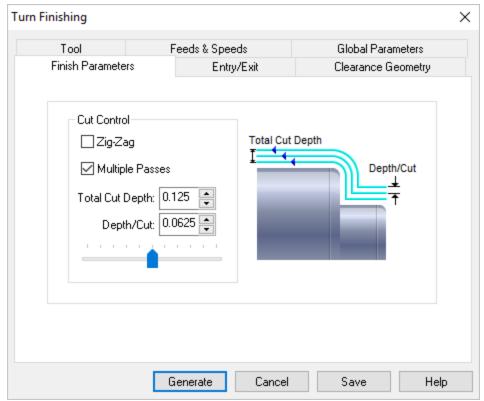


Finishing toolpath with Avoid Section

8.2.2 Finishing Parameters

The following dialog allows you to set Cut Control finishing parameters for Turn Finishing operations.

Dialog Box: Finishing Parameters tab



Dialog Box: Global Parameters tab, Turn Finishing

Cut Control

Final finishing cut can be specified in terms of the total passes of the cutter over the stock.

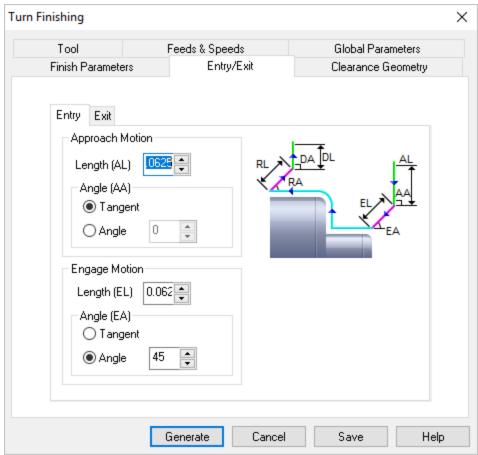
Cut Control - Allows specifying multiple passes for finishing. Selecting Multiple Passes allows user to set the Total Cut Depth and Depth/Cut.

The direction of cut can be either unidirectional or Bi-directional (Zig-Zag)

8.2.3 Entry/Exit

The following dialog allows you to set Entry/Exit Parameters for Turn Finishing operations. Entry and Exit determines the way in which tool enters and leaves the part geometry. TURN Module allows you to specify how the cutter approaches, engages, retracts and departs when starting and stopping a cut.

Dialog Box: Entry/Exit tab



Dialog Box: Entry/Exit tab, Turn Roughing operations

Entry Tab

The Entry tab (shown in the dialog box above) consists of Approach and Engage. You can set different feeds for plunge, approach, engage, cut, retract and depart moves. The tool moves to the position above the approach point with a plunge feed, then uses the approach feed rate for the vertical approach motion and engage feed rate for the engage motion.

The approach can be either Tangential or at an angle to the Engage motion. This is followed by the engage motion that can be Tangential or at an angle.

Exit Tab

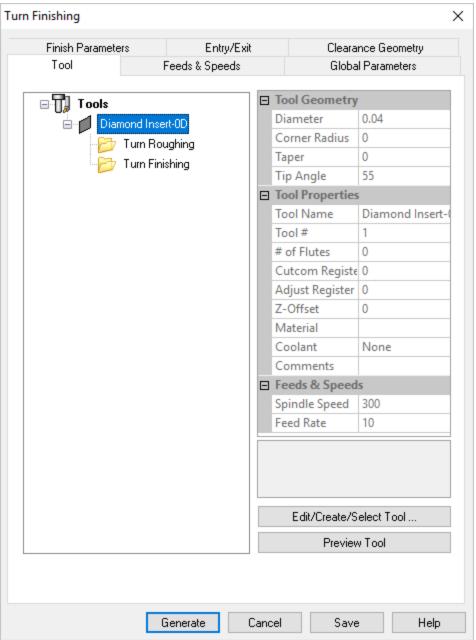
Similarly the Exit motion consists of a Retract motion followed by a departure motion. The retract motion can be either Tangential or at an angle. The departure motion can be either Tangential or at an angle to the Retract motion.

8.2.4 Tool

The following dialog allows you to select the appropriate tool for the Turn Finishing operation. The Tools in Session are listed on the left. Expanding the Tool tree will list the current operations

assigned to that tool. The geometry parameters of the selected tool are displayed to the right. See Create Edit Tools for more information.

Dialog Box: Tool tab



Dialog Box: Tool tab, Turn Finishing

Edit/Create/Select Tool ...

If there are no Tools listed, select this button to Create a new tool. If a tool is listed and selected by default, select this button to Edit the parameters for that tool or to

Select a different tool for the current operation.

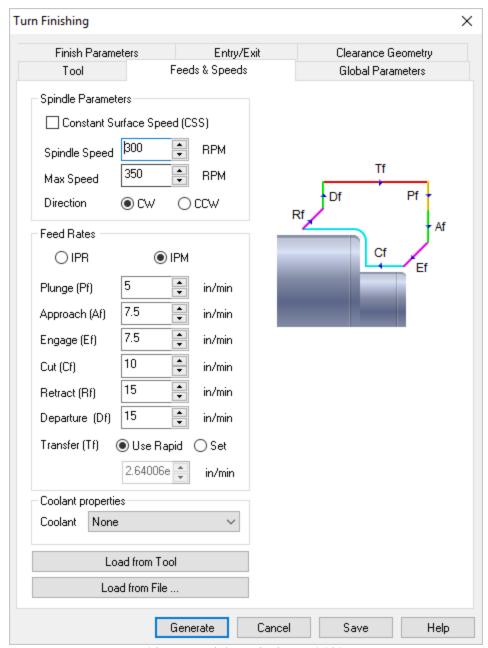


Preview Tool - Select this button to display a graphical representation of the currently selected tool. This is the same Preview of the tool that you see displayed in the Edit/Create/Select Tool dialog.

8.2.5 Feeds & Speeds

The following dialog allows you to select the appropriate Feeds & Speeds for the Turn Finishing operation. In this tab, Spindle Parameters and Feed Rates can be specified. Speeds & Feeds can also be loaded from a File or from the Tool.

Dialog Box: Feeds & Speeds tab



Dialog Box: Feeds & Speeds tab, Turn Finishing

Spindle Parameters

Constant Surface Speed (CSS)

This is the Spindle Speed Mode. If this box is checked, the mode is set to Constant Surface Speed (CSS). If unchecked, the mode is set to Constant Rotational Speed (CRS).

If the Constant Surface Speed is checked, the controller would automatically calculate and adjust the spindle speed based on the current diameter of the work-piece. If this calculated spindle speed is greater than the maximum spindle speed specified in your

post, the spindle speed would be reduced to the maximum speed. Refer to the Spindle section of the Post-Processor Generator to ensure your Spindle Mode is set correctly.

Spindle Speed

his is the rotational speed of the spindle expressed in RPM.

Surface Speed

Surface speed is set in units/min when Constant Surface Speed is selected. This is only applicable for turning inserts.

Max Speed

The maximum rotational speed of the spindle, in RPM. This is only applicable for turning inserts.

Direction

This determines the direction of spindle rotation and can be set to Clockwise or Counter Clockwise.



Feed Rates

Feedrate can be set in Units/Min or Units/Revolution for Turning Inserts.

Plunge (Pf)

This rate is the feed before the tool starts to engage in material. This is always vertical.

Approach (Af)

This is the feedrate used that prepares the cutter just before it starts engaging into material as it starts cutting. The approach motions are dependent on the method of machining.

Engage (Ef)

This is the feedrate used when the tool is performing an engage move. TURN Module sets this value to be 75% of the cutting speed.

This is the feedrate used when the tool is cutting material

Retract (Rf)

The feedrate used when the tool is performing a retract move away from material. TURN Module sets this also to also be 75% of the cutting speed.

Departure (Df)

The feedrate used to retract the tool from the material.

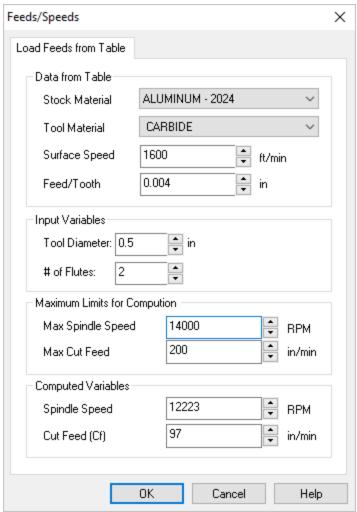
Transfer (Tf)

This is the feedrate (in Units/Min), used for Transfer motions. Select Use Rapid to set this to the Transfer Feed value defined in the Feeds & Speeds section of the CAM Preferences dialog.

Coolant Here you can override the Coolant that is specified by the Tool. Coolant can be set to Flood, Mist or Through. Coolant codes are defined in the post processor generator under Misc tab. Load from Tool Feeds & Speeds are defined when a tool is created using Create/Edit Tools from the Machining Objects Browser. Selecting this button loads the Feeds & Speeds from the tool that is selected for the current machining operation. Load from File ... This loads the Feeds & Speeds values from the Feeds & Speeds Table file. This will display the Load Feeds from Table dialog box to make your selections.

Dialog Box: Load Feeds from Table

Selecting OK from this dialog transfers the spindle speed and cut feedrate to the Feeds & Speeds tab. The plunge, approach, engage, retract and departure feeds are determined using a percent of the cut feed. The percent to use for transferring the computed cut feed can be set under Feeds & Speeds Preferences.



Dialog Box: Load Feeds from Table

Data from Table

Stock Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Tool Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Surface Speed

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Feed/Tooth

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Input Variables

The input variables - Work Diameter is automatically loaded from the Stock Radius. Based on this parameter and the Variables Limits parameters, the program computes Spindle Speed and Cut Feedrate (Cf). measured in Unites/Revolution. Changing the spindle speed modifies the cut feedrate.

Maximum Limits for Computation

Here you can set the Max Spindle Speed and Max Cut Feed (Cf) values. Once these two values are set, the Spindle Speed and Cut Feed calculated by this dialog will not exceed these values even if you attempt to enter higher values into the Computed Variables fields. To exceed these values, change them here or you must edit the operation or tool parameters manually.

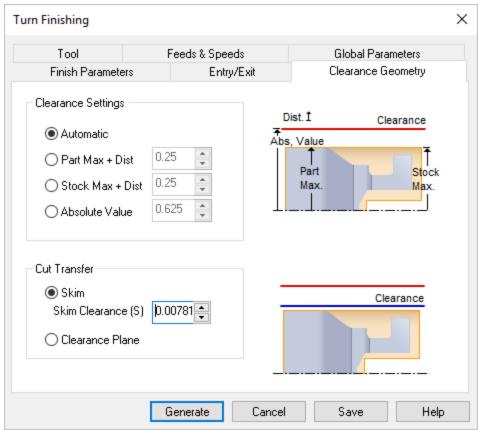
Computed Variables

The variables for Spindle Speed and Cut Feed (Cf) are computed for you based on the selections made in this dialog but will not exceed the values set in the Maximum Limits for Computation section of the dialog. These values are then assigned to the active toolpath operation or tool. You can override either of these variables and the other will update automatically. Since this dialog is a Feeds & Speeds Calculator, you cannot override both values. To do so, you must edit the operation or tool parameters manually.

8.2.6 Clearance

The following dialog allows you to select the appropriate Clearance Geometry for the Turn Finishing operation. In this tab, Clearance Settings and Cut Transfer parameters can be specified. See Clearance Plane for additional information.

Dialog Box: Clearance Geometry tab



Dialog Box: Clearance Geometry tab, Turn Finishing

Clearance Settings

Automatic

The system determines the clearance height based on the part and stock geometry.

Part Max + Dist

Uses Part maximum plus the specified distance for clearance height.

Stock Max + Dist

Uses Stock maximum plus the specified distance for clearance height. If stock geometry does not exist, it would use the maximum height of the part geometry.

Absolute Value

Uses the specified distance for clearance height.

For Turning operations, the User Interface for clearance settings are automatically set for OD, ID or Face depending on the approach type specified under global parameters.

For Hole Machining operations, the clearance plane is normal to the Z axis.

Cut Transfer

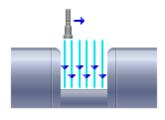
You can also control the transfer motions during cutting. When the cutter has finished cutting in one region and needs to transfer to another region to begin cutting, it can either be instructed to move to the clearance plane and then perform the transfer motion to the next cut location or it could do a skim motion. In the skim motion, the system automatically determines the safe height by taking into consideration the condition of the part model and using this Skim Clearance (S) value specified as the height to perform the transfer motions.

8.3 Groove Roughing



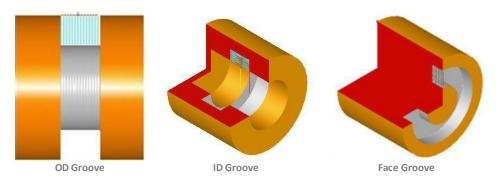
This operation is performed to machine grooves in multiple cuts on the part. This roughing operation provides user the control to set the step down and step over and choose the cut direction.

Both part and stock geometry are used to determine the regions that can be safely machined. Groove Roughing can be of 3 types: OD Groove Roughing, ID Groove Roughing, and Face Groove Roughing. The grooves are typically used to slide/fit one part into another to obtain the required assembly.



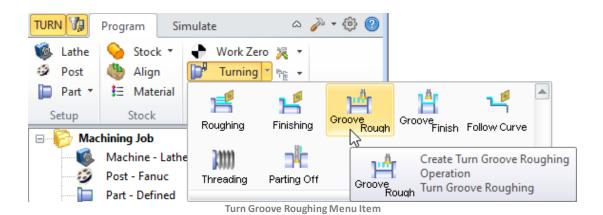
Groove Roughing

Turn Groove Roughing Examples



Turn Groove Roughing Menu Item

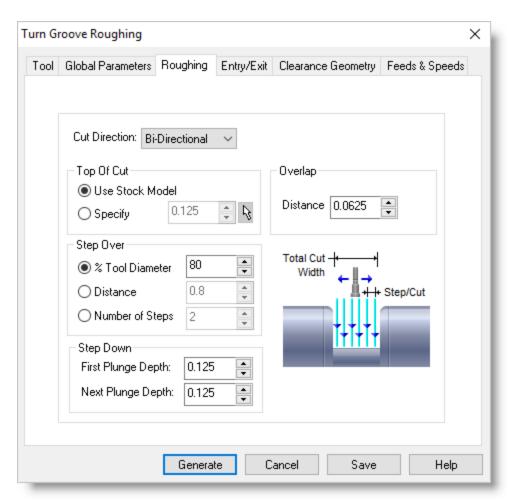
The Groove Roughing toolpath method is invoked by selecting the Program tab, clicking on the **Turning** button in the Machining Browser and selecting the Groove Roughing operation.



Dialog Box: Turn Groove Roughing

This section describes the various parameters that you can set to execute this machining operation. The dialog that is invoked when you choose this toolpath method is shown below:

This dialog has six tabs. Each tab defines a set of parameters that you can specify. The sections below describe them in detail.

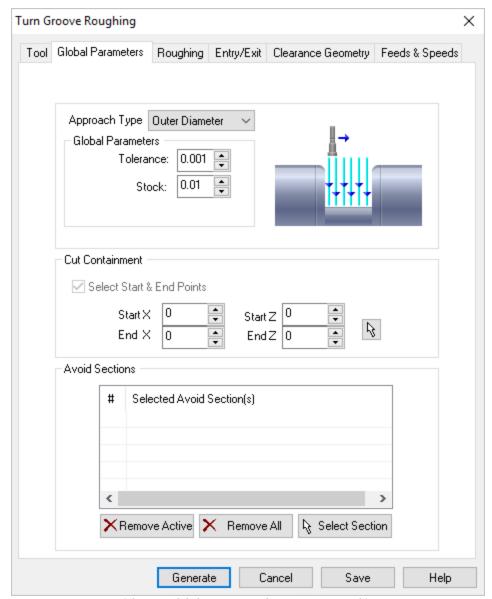


Dialog Box: Turn Groove Roughing

8.3.1 Global Parameters

The following dialog allows you to set Global Parameters for Turn Groove Roughing operations. You can set the Approach Type, Global Parameters and Cut Containment and Avoid Sections via this property page.

Dialog Box: Global Parameters tab



Dialog Box: Global Parameters tab, Turn Groove Roughing

Approach Type

Approach Type

Allows user to choose between Outer Diameter (OD), Front Facing and Inner Diameter (ID). The toolpaths are generated for the selected approach types.

In rouging and finishing operations, for tools with OD orientation, the approach type can be set to Outer Diameter or Front Facing. For tools with ID orientation, the approach type is automatically set to Inner Diameter.

Global Parameters section allows you to set the tolerance value to be used in machining. A uniform thickness or stock that needs to be left around the part can be specified here.

Tolerance

This is the allowable deviation from the actual part geometry plus the Stock layer (if any).

Stock (Roughing Operations Only)

This is the layer of material that will remain around the part after the toolpath is completed. Generally Roughing operations leave a thin layer of stock, unlike finishing operations where this value is usually set to zero.

Cut Containment

This allows you to select an area to contain the toolpath. This is useful in cases where a section of the part needs to be machined. This is done by selecting the check box for Select containment Start & End points.



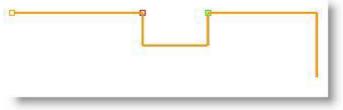
Cut Containment

You can either input the X and Z coordinate values that represent 2 corners of a containment rectangle or use the pick option to graphically select 2 corners of a rectangle for containment.

You can use the object snap tools from the status bar to snap to points on the part geometry.

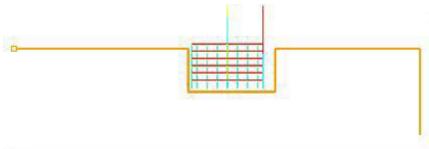
Cut Containment Examples for Turn Groove Roughing

The start and end points are displayed on the part geometry. The start point is represented in **Green** color and end point in **Red**.



Cut Containment Examples for Turn Groove Roughing

The groove roughing toolpath is generated between start and end points.



Cut Containment Examples for Turn Groove Roughing

The start and end points are also used to determine the cut direction when cut direction is set to Uni-Directional under the Roughing tab.

Avoid Sections

This allows user to select areas to be excluded from the turn part geometry for toolpath computation. This is done by selecting 2 points on the part geometry. A line is inserted between the 2 selected points as avoid region and this now becomes part of your turn part geometry. One or more avoid areas can be selected.

Defining Avoid Sections

To select an area to avoid:

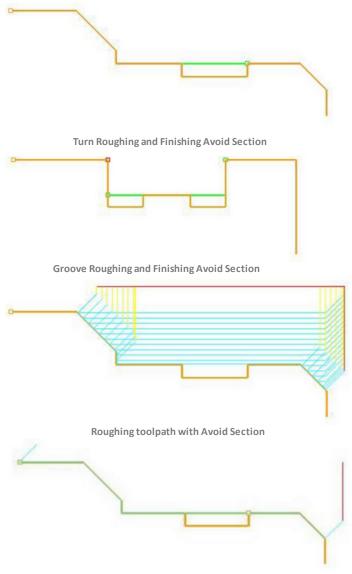
From the Global Parameters tab in the Turn Operations dialog box, click Select Section under Avoid Sections and pick 2 points on the part geometry. The selection is now displayed under avoid selection.

Selecting an Avoid Region from the list highlights it on the part geometry.



Avoid Sections, Global Parameters tab of Turn Operations dialog box

Examples for various Turn Operations

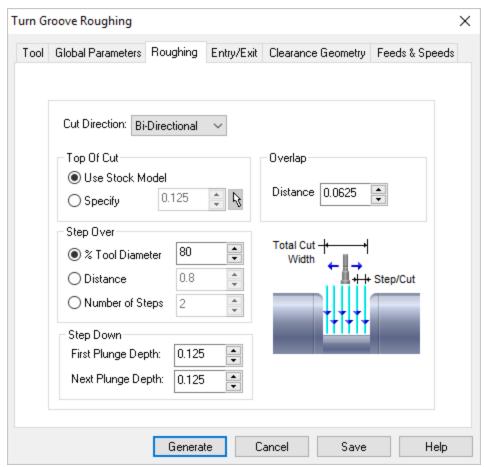


Finishing toolpath with Avoid Section

8.3.2 Roughing Parameters

In this tab, parameters like the Cut Direction, Step Over and Step Down can be specified for Turn Groove Roughing operations.

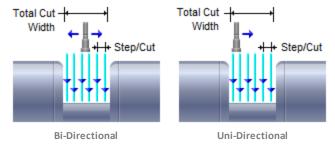
Dialog Box: Roughing tab



Dialog Box: Roughing tab, Turn Groove Roughing

Cut Direction

This can be either Bi-Direction or Uni-Directional. Bi-Directional cuts start at the center of the groove and works its way in both directions towards the start and end points. Uni-Directional cuts start from the start point and works its way towards the end point of the groove feature. When using Bi-Directional, an Overlap distance parameter can be specified.



Top of Cut

This tells the system where to begin cutting. Select Use Stock Model to allow the

system to determine this location based on the Stock. Select Specify and then enter a value to locate where to begin cutting.



You can select the Pick button and then select a point on your part for the top of cut. It's distance will calculated and entered into the Distance field.

Overlap

With Cut Direction set to Bi-Directional, you can also specify an Overlap Distance. Enter a value in the Distance field.

Step Over

This allows you to specify the spacing between groove cuts. You can set this to one of the following: % Tool Diameter: Enter the percentage of the groove tool to use. Distance: Enter the step over distance. Number of Steps: Enter the total number of steps to use.

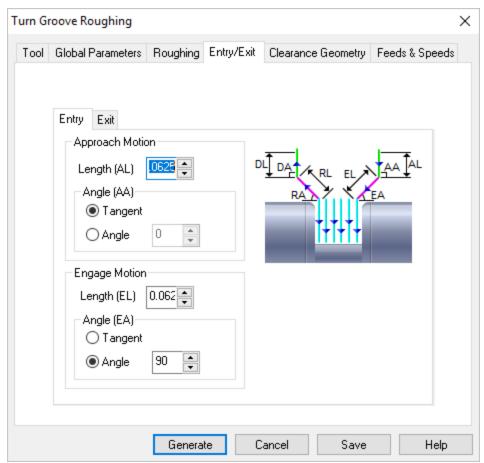
Step Down

This allows you to define the depth between the cut levels for the roughing operation. You can specify the First Plunge Depth and the Next Plunge Depth for subsequent levels. These are set as a specified distance.

8.3.3 Entry/Exit

The following dialog allows you to set Entry/Exit parameters for Groove Roughing operations. Entry and Exit determines the way in which tool enters and leaves the part geometry. TURN Module allows you to specify how the cutter approaches, engages, retracts and departs when starting and stopping a cut.

Dialog Box: Entry/Exit tab



Dialog Box: Entry/Exit tab, Groove Roughing

Entry Tab

The Entry tab (shown in the dialog box above) consists of Approach and Engage. You can set different feeds for plunge, approach, engage, cut, retract and depart moves. The tool moves to the position above the approach point with a plunge feed, then uses the approach feed rate for the vertical approach motion and engage feed rate for the engage motion.

The approach can be either Tangential or at an angle to the Engage motion. This is followed by the engage motion that can be Tangential or at an angle.

Exit Tab

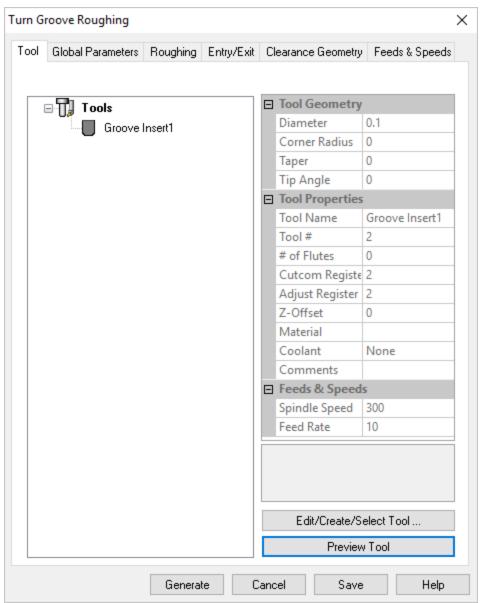
Similarly the Exit motion consists of a Retract motion followed by a departure motion. The retract motion can be either Tangential or at an angle. The departure motion can be either Tangential or at an angle to the Retract motion.

8.3.4 Tool

The following dialog allows you to select the appropriate tool for the Turn Groove Roughing operation. The Tools in Session are listed on the left. Expanding the Tool tree will list the current

operations assigned to that tool. The geometry parameters of the selected tool are displayed to the right. See Create Edit Tools for more information.

Dialog Box: Tool tab



Dialog Box: Tool tab, Turn Groove Roughing

Edit/Create/Select Tool ...

If there are no Tools listed, select this button to Create a new tool. If a tool is listed and selected by default, select this button to Edit the parameters for that tool or to Select a different tool for the current operation.

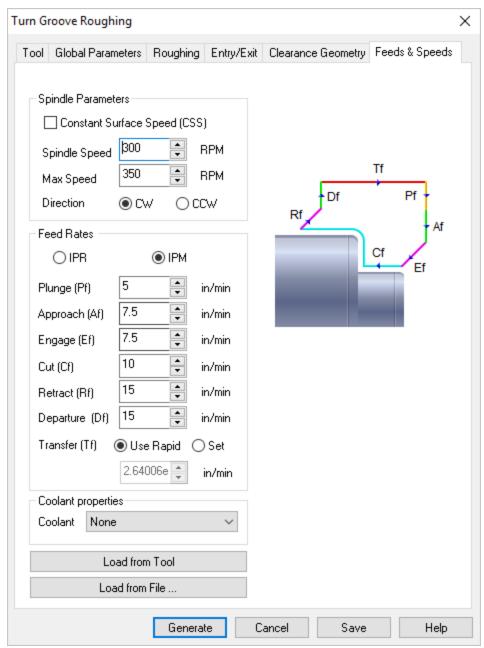


Preview Tool - Select this button to display a graphical representation of the currently selected tool. This is the same Preview of the tool that you see displayed in the Edit/Create/Select Tool dialog.

8.3.5 Feeds & Speeds

The following dialog allows you to select the appropriate Feeds & Speeds for the Turn Groove Roughing operation. In this tab, Spindle Parameters and Feed Rates can be specified. Speeds & Feeds can also be loaded from a File or from the Tool.

Dialog Box: Feeds & Speeds tab



Dialog Box: Feeds & Speeds tab, Turn Groove Roughing

Spindle Parameters

Constant Surface Speed (CSS)

This is the Spindle Speed Mode. If this box is checked, the mode is set to Constant Surface Speed (CSS). If unchecked, the mode is set to Constant Rotational Speed (CRS).

If the Constant Surface Speed is checked, the controller would automatically calculate and adjust the spindle speed based on the current diameter of the work-piece. If this calculated spindle speed is greater than the maximum spindle speed specified in your

post, the spindle speed would be reduced to the maximum speed. Refer to the Spindle section of the Post-Processor Generator to ensure your Spindle Mode is set correctly.

Spindle Speed

his is the rotational speed of the spindle expressed in RPM.

Surface Speed

Surface speed is set in units/min when Constant Surface Speed is selected. This is only applicable for turning inserts.

Max Speed

The maximum rotational speed of the spindle, in RPM. This is only applicable for turning inserts.

Direction

This determines the direction of spindle rotation and can be set to Clockwise or Counter Clockwise.



Feed Rates

Feedrate can be set in Units/Min or Units/Revolution for Turning Inserts.

Plunge (Pf)

This rate is the feed before the tool starts to engage in material. This is always vertical.

Approach (Af)

This is the feedrate used that prepares the cutter just before it starts engaging into material as it starts cutting. The approach motions are dependent on the method of machining.

Engage (Ef)

This is the feedrate used when the tool is performing an engage move. TURN Module sets this value to be 75% of the cutting speed.

This is the feedrate used when the tool is cutting material

Retract (Rf)

The feedrate used when the tool is performing a retract move away from material. TURN Module sets this also to also be 75% of the cutting speed.

Departure (Df)

The feedrate used to retract the tool from the material.

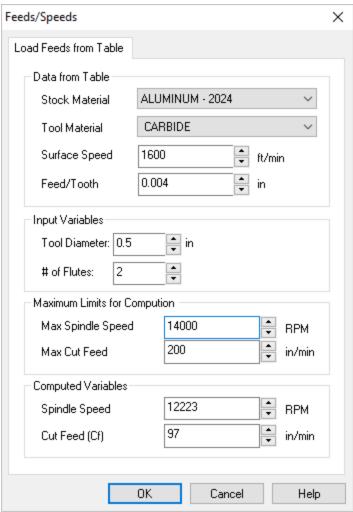
Transfer (Tf)

This is the feedrate (in Units/Min), used for Transfer motions. Select Use Rapid to set this to the Transfer Feed value defined in the Feeds & Speeds section of the CAM Preferences dialog.

Coolant Here you can override the Coolant that is specified by the Tool. Coolant can be set to Flood, Mist or Through. Coolant codes are defined in the post processor generator under Misc tab. Load from Tool Feeds & Speeds are defined when a tool is created using Create/Edit Tools from the Machining Objects Browser. Selecting this button loads the Feeds & Speeds from the tool that is selected for the current machining operation. Load from File ... This loads the Feeds & Speeds values from the Feeds & Speeds Table file. This will display the Load Feeds from Table dialog box to make your selections.

Dialog Box: Load Feeds from Table

Selecting OK from this dialog transfers the spindle speed and cut feedrate to the Feeds & Speeds tab. The plunge, approach, engage, retract and departure feeds are determined using a percent of the cut feed. The percent to use for transferring the computed cut feed can be set under Feeds & Speeds Preferences.



Dialog Box: Load Feeds from Table

Data from Table

Stock Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Tool Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Surface Speed

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Feed/Tooth

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Input Variables

The input variables - Work Diameter is automatically loaded from the Stock Radius. Based on this parameter and the Variables Limits parameters, the program computes Spindle Speed and Cut Feedrate (Cf). measured in Unites/Revolution. Changing the spindle speed modifies the cut feedrate.

Maximum Limits for Computation

Here you can set the Max Spindle Speed and Max Cut Feed (Cf) values. Once these two values are set, the Spindle Speed and Cut Feed calculated by this dialog will not exceed these values even if you attempt to enter higher values into the Computed Variables fields. To exceed these values, change them here or you must edit the operation or tool parameters manually.

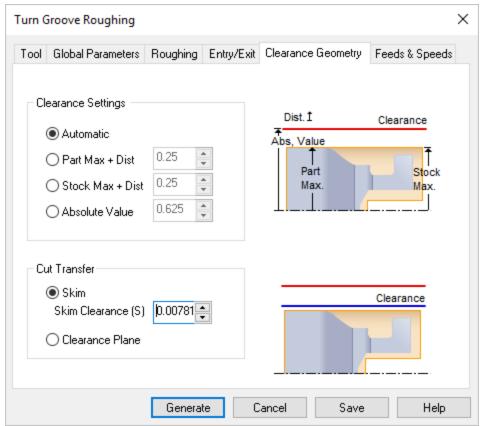
Computed Variables

The variables for Spindle Speed and Cut Feed (Cf) are computed for you based on the selections made in this dialog but will not exceed the values set in the Maximum Limits for Computation section of the dialog. These values are then assigned to the active toolpath operation or tool. You can override either of these variables and the other will update automatically. Since this dialog is a Feeds & Speeds Calculator, you cannot override both values. To do so, you must edit the operation or tool parameters manually.

8.3.6 Clearance

The following dialog allows you to select the appropriate Clearance Geometry for the Turn Groove Roughing operation. In this tab, Clearance Settings and Cut Transfer parameters can be specified. See Clearance Plane for additional information.

Dialog Box: Clearance Geometry tab



Dialog Box: Clearance Geometry tab, Turn Groove Roughing

Clearance Settings

Automatic

The system determines the clearance height based on the part and stock geometry.

Part Max + Dist

Uses Part maximum plus the specified distance for clearance height.

Stock Max + Dist

Uses Stock maximum plus the specified distance for clearance height. If stock geometry does not exist, it would use the maximum height of the part geometry.

Absolute Value

Uses the specified distance for clearance height.

For Turning operations, the User Interface for clearance settings are automatically set for OD, ID or Face depending on the approach type specified under global parameters.

For Hole Machining operations, the clearance plane is normal to the Z axis.

Cut Transfer

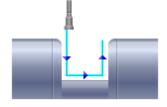
You can also control the transfer motions during cutting. When the cutter has finished cutting in one region and needs to transfer to another region to begin cutting, it can either be instructed to move to the clearance plane and then perform the transfer motion to the next cut location or it could do a skim motion. In the skim motion, the system automatically determines the safe height by taking into consideration the condition of the part model and using this Skim Clearance (S) value specified as the height to perform the transfer motions.

8.4 Groove Finishing



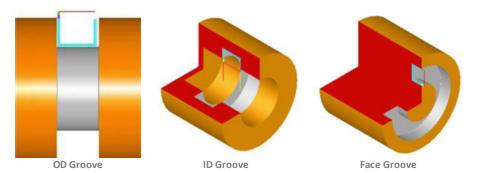
This operation is used to finish the grooves. This operation is performed after the Groove Roughing operation. Groove Finishing can be of 3 types: OD, ID, and Front Facing.

Turning Operations



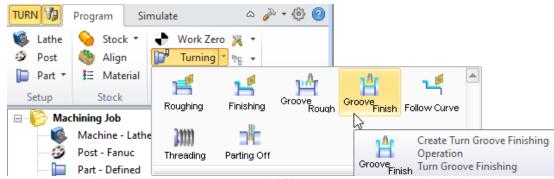
Turn Groove Finishing Examples





Turn Groove Finishing Menu Item

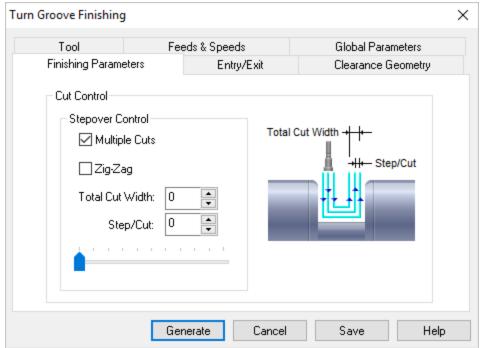
The Groove Finishing toolpath method is invoked by selecting the Program tab, clicking on the Turning button in the Machining Browser and selecting the Groove Finishing operation.



Dialog Box: Turn Groove Finishing

This section describes the various parameters that you can set to execute this machining operation. The dialog that is invoked when you choose this toolpath method is shown below:

This dialog has six tabs. Each tab defines a set of parameters that you can specify. The sections below describe them in detail.

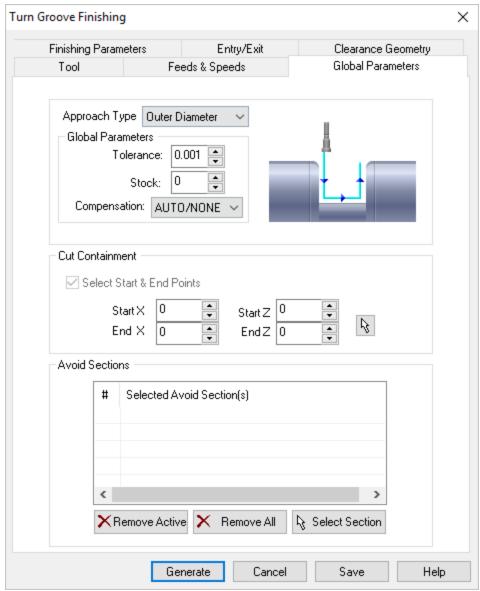


Dialog Box: Turn Groove Finishing

8.4.1 Global Parameters

The following dialog allows you to set Global Parameters for Groove Finishing operations. You can set the Approach Type, Global Parameters and Cut Containment via this property page. For grooving operations, the use needs to specify the start and end points of the groove. This is specified under the Cut Containment.

Dialog Box: Global Parameters tab



Dialog Box: Global Parameters tab, Turn Groove Finishing

Approach Type

Approach Type

Allows user to choose between Outer Diameter (OD), Front Facing and Inner Diameter (ID). The toolpaths are generated for the selected approach types.

In rouging and finishing operations, for tools with OD orientation, the approach type can be set to Outer Diameter or Front Facing. For tools with ID orientation, the approach type is automatically set to Inner Diameter.

Global Parameters section allows you to set the tolerance value to be used in machining. A uniform thickness or stock that needs to be left around the part can be specified here.

Tolerance

This is the allowable deviation from the actual part geometry plus the Stock layer (if any).

Stock (Roughing Operations Only)

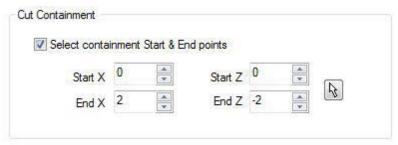
This is the layer of material that will remain around the part after the toolpath is completed. Generally Roughing operations leave a thin layer of stock, unlike finishing operations where this value is usually set to zero.

Compensation

This stands for cutter compensation. You can turn this on by selecting from the drop down menu. The cutter compensation direction, Left or Right, is determined by the Cut Direction (Climb or Conventional). Refer to the following section for additional information - Cutter Compensation

Cut Containment

This allows you to select an area to contain the toolpath. This is useful in cases where a section of the part needs to be machined. This is done by selecting the check box for Select containment Start & End points.



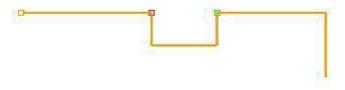
Cut Containment

You can either input the X and Z coordinate values that represent 2 corners of a containment rectangle or use the pick option to graphically select 2 corners of a rectangle for containment.

You can use the object snap tools from the status bar to snap to points on the part geometry.

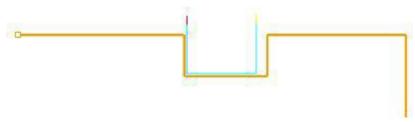
Cut Containment Examples for Turn Groove Finishing

The start and end points are displayed on the part geometry. The start point is represented in **Green** color and end point in **Red**.



Cut Containment Examples for Turn Groove Finishing

The groove finishing toolpath is generated for the specified start and end points.



Cut Containment Examples for Turn Groove Finishing

The start and end points are also used to determine the Cut Direction in Groove Finishing operation.



Avoid Sections

This allows user to select areas to be excluded from the turn part geometry for toolpath computation. This is done by selecting 2 points on the part geometry. A line is inserted between the 2 selected points as avoid region and this now becomes part of your turn part geometry. One or more avoid areas can be selected.



Defining Avoid Sections

To select an area to avoid:

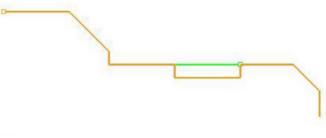
From the Global Parameters tab in the Turn Operations dialog box, click Select Section under Avoid Sections and pick 2 points on the part geometry. The selection is now displayed under avoid selection.

Selecting an Avoid Region from the list highlights it on the part geometry.

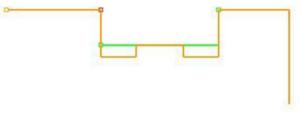


Avoid Sections, Global Parameters tab of Turn Operations dialog box

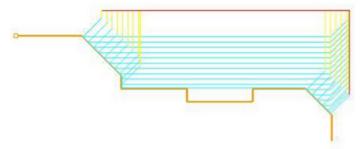
Examples for various Turn Operations



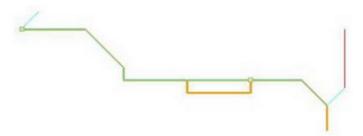
Turn Roughing and Finishing Avoid Section



Groove Roughing and Finishing Avoid Section



Roughing toolpath with Avoid Section

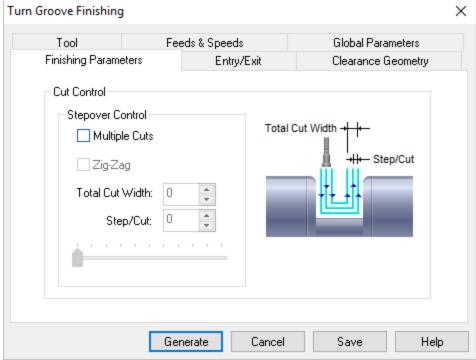


Finishing toolpath with Avoid Section

8.4.2 Finishing Parameters

In this tab, parameters like the Cut Direction, Step Over and Step Down can be specified for Turn Groove Roughing operations.

Dialog Box: Finishing Parameters tab



Dialog Box: Finishing Parameters tab, Turn Groove Finishing

Cut Control

Groove finishing cut can be specified in terms of the total passes of the cutter over the stock.

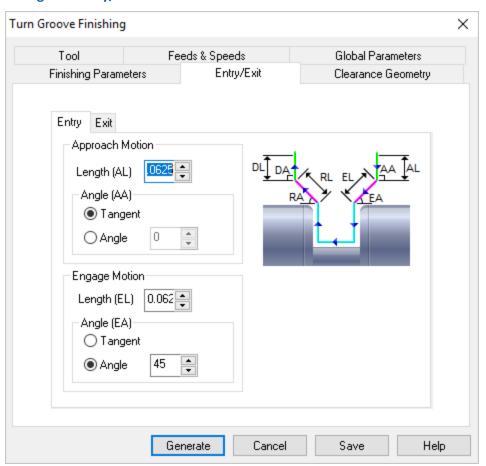
Stepover Control - Allows specifying multiple passes for groove finishing. Selecting multiple cuts allows user to set the total cut width and step per cut. The direction of

cut can be either unidirectional or Bi-directional (Zig-Zag) with Multiple Cuts supported.

8.4.3 Entry/Exit

The following dialog allows you to set Entry/Exit parameters for Groove Finishing operations. Entry and Exit determines the way in which tool enters and leaves the part geometry. TURN Module allows you to specify how the cutter approaches, engages, retracts and departs when starting and stopping a cut.

Dialog Box: Entry/Exit tab



Dialog Box: Entry/Exit tab, Groove Finishing

Entry Tab

The Entry tab (shown in the dialog box above) consists of Approach and Engage. You can set different feeds for plunge, approach, engage, cut, retract and depart moves. The tool moves to the position above the approach point with a plunge feed, then uses the approach feed rate for the vertical approach motion and engage feed rate for the engage motion.

The approach can be either Tangential or at an angle to the Engage motion. This is followed by the engage motion that can be Tangential or at an angle.

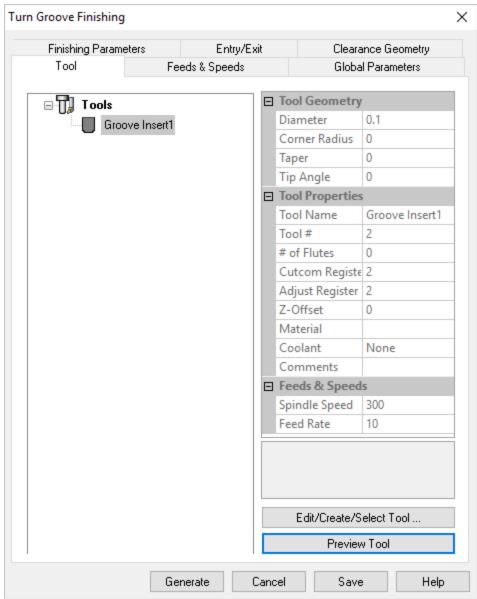


Similarly the Exit motion consists of a Retract motion followed by a departure motion. The retract motion can be either Tangential or at an angle. The departure motion can be either Tangential or at an angle to the Retract motion.

8.4.4 Tool

The following dialog allows you to select the appropriate Groove insert tool for the Turn Groove Roughing operation. The Tools in Session are listed on the left. Expanding the Tool tree will list the current operations assigned to that tool. The geometry parameters of the selected tool are displayed to the right. See Create Edit Tools for more information.

Dialog Box: Tool tab



Dialog Box: Tool tab, Turn Groove Finishing

Edit/Create/Select Tool ...

If there are no Tools listed, select this button to Create a new tool. If a tool is listed and selected by default, select this button to Edit the parameters for that tool or to Select a different tool for the current operation.

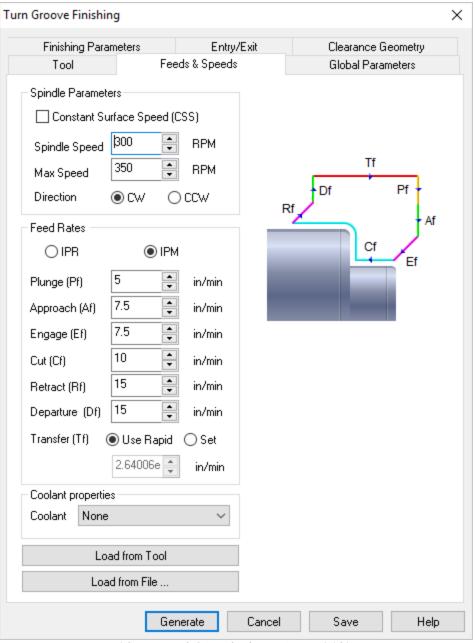
Preview Tool

Preview Tool - Select this button to display a graphical representation of the currently selected tool. This is the same Preview of the tool that you see displayed in the Edit/Create/Select Tool dialog.

8.4.5 Feeds & Speeds

The following dialog allows you to select the appropriate Feeds & Speeds for the Turn Groove Finishing operation. In this tab, Spindle Parameters and Feed Rates can be specified. Speeds & Feeds can also be loaded from a File or from the Tool.

Dialog Box: Feeds & Speeds tab



Dialog Box: Feeds & Speeds tab, Turn Groove Finishing

Spindle Parameters

Constant Surface Speed (CSS)

This is the Spindle Speed Mode. If this box is checked, the mode is set to Constant Surface Speed (CSS). If unchecked, the mode is set to Constant Rotational Speed (CRS).

If the Constant Surface Speed is checked, the controller would automatically calculate and adjust the spindle speed based on the current diameter of the work-piece. If this calculated spindle speed is greater than the maximum spindle speed specified in your post, the spindle speed would be reduced to the maximum speed. Refer to the Spindle section of the Post-Processor Generator to ensure your Spindle Mode is set correctly.

Spindle Speed

his is the rotational speed of the spindle expressed in RPM.

Surface Speed

Surface speed is set in units/min when Constant Surface Speed is selected. This is only applicable for turning inserts.

Max Speed

The maximum rotational speed of the spindle, in RPM. This is only applicable for turning inserts.

Direction

This determines the direction of spindle rotation and can be set to Clockwise or Counter Clockwise.



Feed Rates

Feedrate can be set in Units/Min or Units/Revolution for Turning Inserts.

Plunge (Pf)

This rate is the feed before the tool starts to engage in material. This is always vertical.

Approach (Af)

This is the feedrate used that prepares the cutter just before it starts engaging into material as it starts cutting. The approach motions are dependent on the method of machining.

Engage (Ef)

This is the feedrate used when the tool is performing an engage move. TURN Module sets this value to be 75% of the cutting speed.

Cut (Cf)

This is the feedrate used when the tool is cutting material

Retract (Rf)

The feedrate used when the tool is performing a retract move away from material. TURN Module sets this also to also be 75% of the cutting speed.

Departure (Df)

The feedrate used to retract the tool from the material.

Transfer (Tf)

This is the feedrate (in Units/Min), used for Transfer motions. Select Use Rapid to set this to the Transfer Feed value defined in the Feeds & Speeds section of the CAM Preferences dialog.

Coolant

Here you can override the Coolant that is specified by the Tool. Coolant can be set to Flood, Mist or Through. Coolant codes are defined in the post processor generator under Misc tab.

Load from Tool

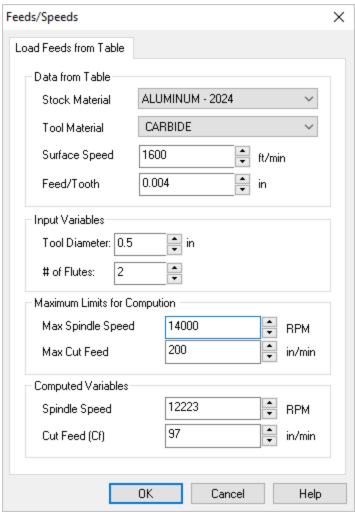
Feeds & Speeds are defined when a tool is created using Create/Edit Tools from the Machining Objects Browser. Selecting this button loads the Feeds & Speeds from the tool that is selected for the current machining operation.

Load from File ...

This loads the Feeds & Speeds values from the Feeds & Speeds Table file. This will display the Load Feeds from Table dialog box to make your selections.

Dialog Box: Load Feeds from Table

Selecting OK from this dialog transfers the spindle speed and cut feedrate to the Feeds & Speeds tab. The plunge, approach, engage, retract and departure feeds are determined using a percent of the cut feed. The percent to use for transferring the computed cut feed can be set under Feeds & Speeds Preferences.



Dialog Box: Load Feeds from Table

Data from Table

Stock Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Tool Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Surface Speed

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Feed/Tooth

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Input Variables

The input variables - Work Diameter is automatically loaded from the Stock Radius. Based on this parameter and the Variables Limits parameters, the program computes Spindle Speed and Cut Feedrate (Cf). measured in Unites/Revolution. Changing the spindle speed modifies the cut feedrate.

Maximum Limits for Computation

Here you can set the Max Spindle Speed and Max Cut Feed (Cf) values. Once these two values are set, the Spindle Speed and Cut Feed calculated by this dialog will not exceed these values even if you attempt to enter higher values into the Computed Variables fields. To exceed these values, change them here or you must edit the operation or tool parameters manually.

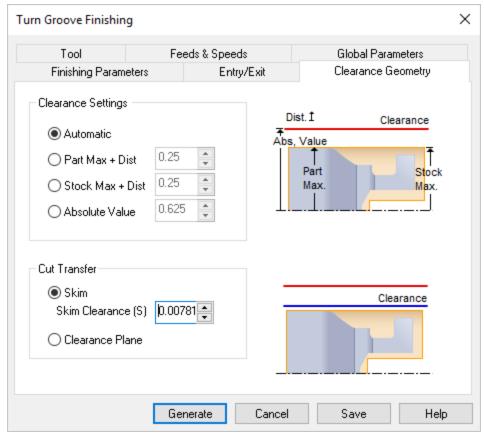
Computed Variables

The variables for Spindle Speed and Cut Feed (Cf) are computed for you based on the selections made in this dialog but will not exceed the values set in the Maximum Limits for Computation section of the dialog. These values are then assigned to the active toolpath operation or tool. You can override either of these variables and the other will update automatically. Since this dialog is a Feeds & Speeds Calculator, you cannot override both values. To do so, you must edit the operation or tool parameters manually.

8.4.6 Clearance

The following dialog allows you to select the appropriate Clearance Geometry for the Turn Groove Finishing operation. In this tab, Clearance Settings and Cut Transfer parameters can be specified. See Clearance Plane for additional information.

Dialog Box: Clearance Geometry tab



Dialog Box: Clearance Geometry tab, Turn Groove Finishing

Clearance Settings

Automatic

The system determines the clearance height based on the part and stock geometry.

Part Max + Dist

Uses Part maximum plus the specified distance for clearance height.

Stock Max + Dist

Uses Stock maximum plus the specified distance for clearance height. If stock geometry does not exist, it would use the maximum height of the part geometry.

Absolute Value

Uses the specified distance for clearance height.

For Turning operations, the User Interface for clearance settings are automatically set for OD, ID or Face depending on the approach type specified under global parameters.

For Hole Machining operations, the clearance plane is normal to the Z axis.

Cut Transfer

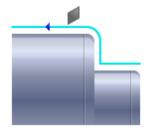
You can also control the transfer motions during cutting. When the cutter has finished cutting in one region and needs to transfer to another region to begin cutting, it can either be instructed to move to the clearance plane and then perform the transfer motion to the next cut location or it could do a skim motion. In the skim motion, the system automatically determines the safe height by taking into consideration the condition of the part model and using this Skim Clearance (S) value specified as the height to perform the transfer motions.

8.5 Follow Curve



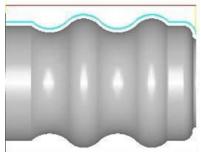
This operation is performed after the roughing operation. This is similar to finishing operation where the toolpath follows the selected curve to obtain better surface finish and is characterized by smaller

depth of cut to obtain tighter tolerances and better surface finish. This method is similar to engraving in milling where the tool nose radius compensation is not applied to the toolpath. Follow curve can be used in OD, ID, and Front Facing operations.



Follow Curve

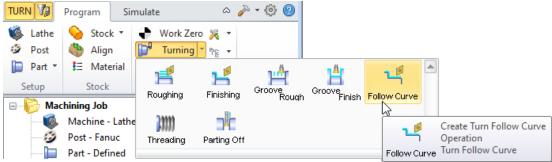
Turn Follow Curve Example



Follow Curve Operation Toolpath Example

Turn Follow Curve Menu Item

The Follow Curve toolpath method is invoked by selecting the Program tab, clicking on the Turning button in the Machining Browser and selecting the Follow Curve operation.

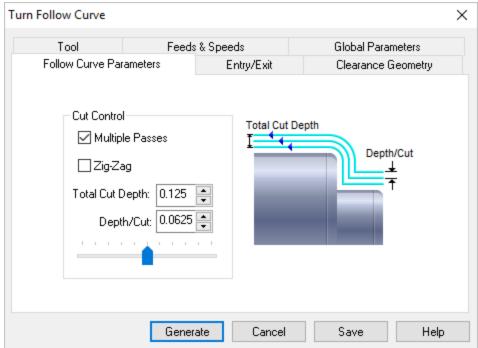


Flow Curve Menu Item

Dialog Box: Turn Follow Curve

This section describes the various parameters that you can set to execute this machining operation. The dialog that is invoked when you choose this toolpath method is shown below:

This dialog has six tabs. Each tab defines a set of parameters that you can specify. The sections below describe them in detail.

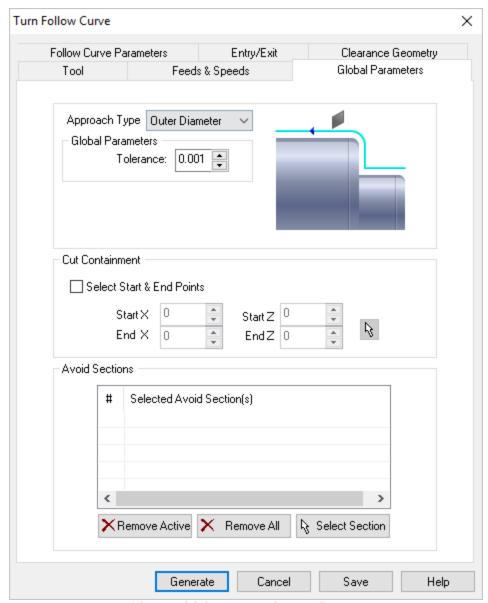


Dialog Box: Turn Follow Curve

8.5.1 Global Parameters

The following dialog allows you to set Global Parameters for Turn Follow Curve operations. You can set the Approach Type, Global Parameters and Cut Containment via this property page.

Dialog Box: Global Parameters tab



Dialog Box: Global Parameters tab, Turn Follow Curve

Approach Type

Approach Type

Allows user to choose between Outer Diameter (OD), Front Facing and Inner Diameter (ID). The toolpaths are generated for the selected approach types.

In rouging and finishing operations, for tools with OD orientation, the approach type can be set to Outer Diameter or Front Facing. For tools with ID orientation, the approach type is automatically set to Inner Diameter.

Global Parameters section allows you to set the tolerance value to be used in machining. A uniform thickness or stock that needs to be left around the part can be specified here.

Tolerance

This is the allowable deviation from the actual part geometry plus the Stock layer (if any).

Stock (Roughing Operations Only)

This is the layer of material that will remain around the part after the toolpath is completed. Generally Roughing operations leave a thin layer of stock, unlike finishing operations where this value is usually set to zero.

Cut Containment

This allows you to select an area to contain the toolpath. This is useful in cases where a section of the part needs to be machined. This is done by selecting the check box for Select containment Start & End points.



Cut Containment

You can either input the X and Z coordinate values that represent 2 corners of a containment rectangle or use the pick option to graphically select 2 corners of a rectangle for containment.

You can use the object snap tools from the status bar to snap to points on the part geometry.

Cut Containment Examples for Turn Follow Curve

The start and end points are displayed on the part geometry. The start point is represented in **Green** color and end point in **Red**.



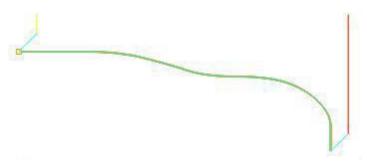
Cut Containment Examples for Turn Follow Curve

The finishing toolpath is contained between start and end points and cut direction of the toolpath is from the start to end point. The selection of start and end points can also be used to determine the cut direction.



Cut Containment Examples for Turn Follow Curve

If a containment is not specified, the follow curve toolpath is generated for the turn part geometry based on the approach type and the part geometry.



Cut Containment Examples for Turn Follow Curve

Avoid Sections

This allows user to select areas to be excluded from the turn part geometry for toolpath computation. This is done by selecting 2 points on the part geometry. A line is inserted between the 2 selected points as avoid region and this now becomes part of your turn part geometry. One or more avoid areas can be selected.



To select an area to avoid:

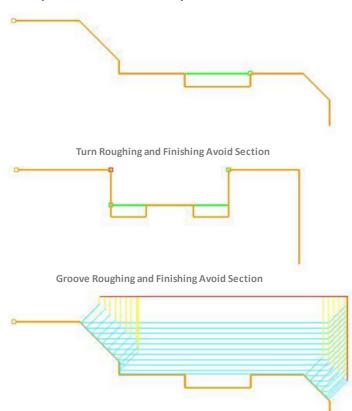
From the Global Parameters tab in the Turn Operations dialog box, click Select Section under Avoid Sections and pick 2 points on the part geometry. The selection is now displayed under avoid selection.

Selecting an Avoid Region from the list highlights it on the part geometry.

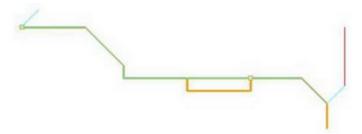


Avoid Sections, Global Parameters tab of Turn Operations dialog box

Examples for various Turn Operations



Roughing toolpath with Avoid Section

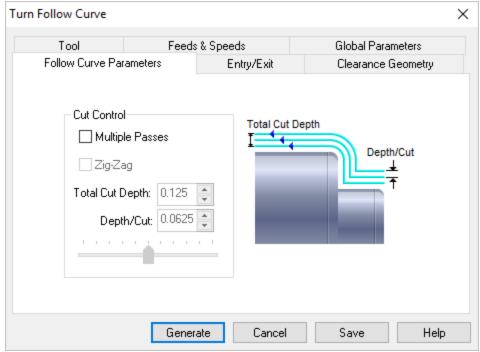


Finishing toolpath with Avoid Section

8.5.2 Follow Curve Parameters

In this tab, Cut Control parameters can be specified for Turn Follow Curve operations.

Dialog Box: Follow Curve Parameters tab



Dialog Box: Follow Curve Parameters tab, Turn Follow Curve

Cut Control

Final finishing cut can be specified in terms of the total passes of the cutter over the stock.

Cut Control

Allows specifying multiple passes for follow curve operation.

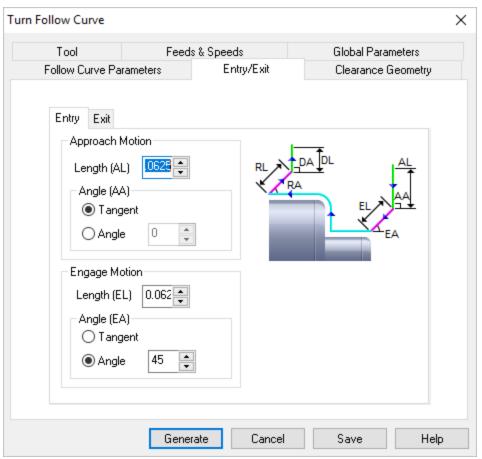
Multiple Passes

Allows user to set the Total Cut Depth and Depth/Cut. The direction of cut can be either unidirectional or Bi-directional (Zig-Zag)

8.5.3 Entry/Exit

The following dialog allows you to set Entry/Exit parameters for Turn Follow Curve operations. Entry and Exit determines the way in which tool enters and leaves the part geometry. TURN Module allows you to specify how the cutter approaches, engages, retracts and departs when starting and stopping a cut.

Dialog Box: Entry/Exit tab



Dialog Box: Entry/Exit tab, Turn Follow Curve

Entry Tab

Approach Motion

Entry consists of an Approach and an Engage move. Approach consists of a length and an angle. Enter a value for Length (AL). Then for Angle (AA) you can select Tangent or Angle. Tangent will approach the part tangent to the part surface. Angle will approach at the angle you specify.

Engage Motion

Entry consists of an Approach and an Engage move. Engage consists of a length and an angle. Enter a value for Length (EL). Then for Angle (EA) you can select Tangent or Angle. Tangent will engage tangent to the part surface. Angle will engage at the angle you specify.

Exit Tab

Retract Motion

Exit consists of a Retract Motion and a Departure Motion. Length (RL) is added beginning at the last cut point.

Angle (RA)

This is the angle of the departure from the last cut point. You can select Tangent or Angle.

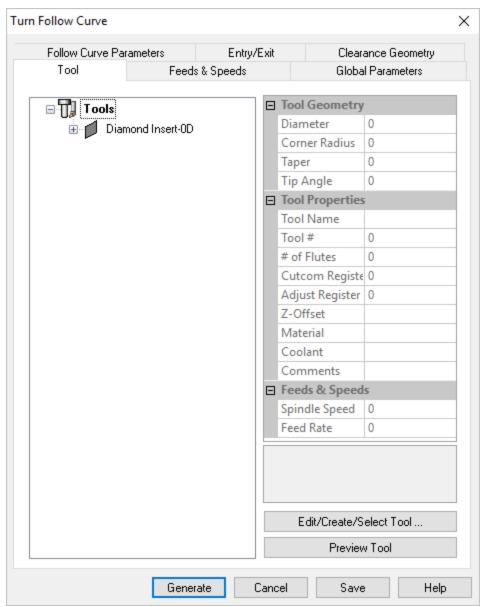
Depart Motion

Departure consists of a length and an angle. Enter a value for Length (DL). Then for Angle (DA) you can select Tangent or Angle. Tangent will depart tangent to the part surface. Angle will depart at the angle you specify.

8.5.4 Tool

The following dialog allows you to select the appropriate tool for the Turn Follow Curve operation. The Tools in Session are listed on the left. Expanding the Tool tree will list the current operations assigned to that tool. The geometry parameters of the selected tool are displayed to the right. See Create Edit Tools for more information.

Dialog Box: Tool tab



Dialog Box: Tool tab, Turn Follow Curve

Edit/Create/Select Tool ...

If there are no Tools listed, select this button to Create a new tool. If a tool is listed and selected by default, select this button to Edit the parameters for that tool or to Select a different tool for the current operation.

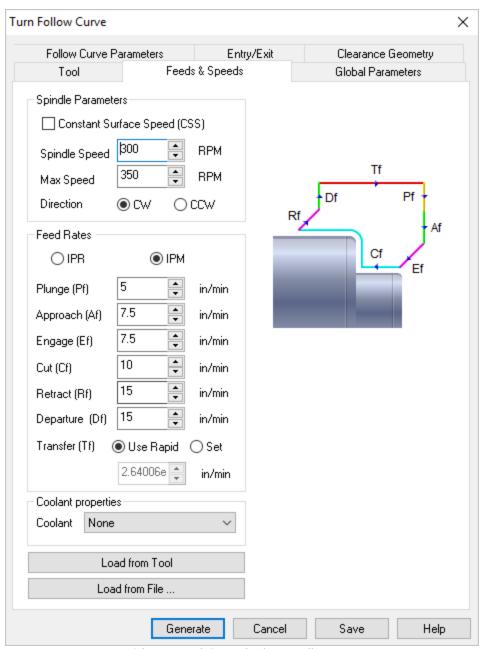
Preview Tool

Preview Tool - Select this button to display a graphical representation of the currently selected tool. This is the same Preview of the tool that you see displayed in the Edit/Create/Select Tool dialog.

8.5.5 Feeds & Speeds

The following dialog allows you to select the appropriate Feeds & Speeds for the Turn Follow Curve operation. In this tab, Spindle Parameters and Feed Rates can be specified. Speeds & Feeds can also be loaded from a File or from the Tool.

Dialog Box: Feeds & Speeds tab



Dialog Box: Feeds & Speeds tab, Turn Follow Curve

Spindle Parameters

Constant Surface Speed (CSS)

This is the Spindle Speed Mode. If this box is checked, the mode is set to Constant Surface Speed (CSS). If unchecked, the mode is set to Constant Rotational Speed (CRS).

If the Constant Surface Speed is checked, the controller would automatically calculate and adjust the spindle speed based on the current diameter of the work-piece. If this calculated spindle speed is greater than the maximum spindle speed specified in your post, the spindle speed would be reduced to the maximum speed. Refer to the Spindle section of the Post-Processor Generator to ensure your Spindle Mode is set correctly.

Spindle Speed

his is the rotational speed of the spindle expressed in RPM.

Surface Speed

Surface speed is set in units/min when Constant Surface Speed is selected. This is only applicable for turning inserts.

Max Speed

The maximum rotational speed of the spindle, in RPM. This is only applicable for turning inserts.

Direction

This determines the direction of spindle rotation and can be set to Clockwise or Counter Clockwise.



Feed Rates

Feedrate can be set in Units/Min or Units/Revolution for Turning Inserts.

Plunge (Pf)

This rate is the feed before the tool starts to engage in material. This is always vertical.

Approach (Af)

This is the feedrate used that prepares the cutter just before it starts engaging into material as it starts cutting. The approach motions are dependent on the method of machining.

Engage (Ef)

This is the feedrate used when the tool is performing an engage move. TURN Module sets this value to be 75% of the cutting speed.

Cut (Cf)

This is the feedrate used when the tool is cutting material

Retract (Rf)

The feedrate used when the tool is performing a retract move away from material. TURN Module sets this also to also be 75% of the cutting speed.

Departure (Df)

The feedrate used to retract the tool from the material.

Transfer (Tf)

This is the feedrate (in Units/Min), used for Transfer motions. Select Use Rapid to set this to the Transfer Feed value defined in the Feeds & Speeds section of the CAM Preferences dialog.

Coolant

Here you can override the Coolant that is specified by the Tool. Coolant can be set to Flood, Mist or Through. Coolant codes are defined in the post processor generator under Misc tab.

Load from Tool

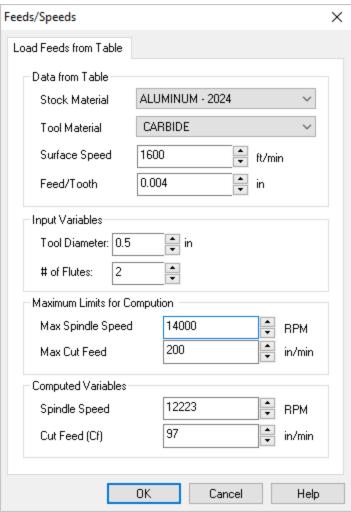
Feeds & Speeds are defined when a tool is created using Create/Edit Tools from the Machining Objects Browser. Selecting this button loads the Feeds & Speeds from the tool that is selected for the current machining operation.

Load from File ...

This loads the Feeds & Speeds values from the Feeds & Speeds Table file. This will display the Load Feeds from Table dialog box to make your selections.

Dialog Box: Load Feeds from Table

Selecting OK from this dialog transfers the spindle speed and cut feedrate to the Feeds & Speeds tab. The plunge, approach, engage, retract and departure feeds are determined using a percent of the cut feed. The percent to use for transferring the computed cut feed can be set under Feeds & Speeds Preferences.



Dialog Box: Load Feeds from Table

Data from Table

Stock Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Tool Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Surface Speed

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Feed/Tooth

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Input Variables

The input variables - Work Diameter is automatically loaded from the Stock Radius. Based on this parameter and the Variables Limits parameters, the program computes Spindle Speed and Cut Feedrate (Cf). measured in Unites/Revolution. Changing the spindle speed modifies the cut feedrate.

Maximum Limits for Computation

Here you can set the Max Spindle Speed and Max Cut Feed (Cf) values. Once these two values are set, the Spindle Speed and Cut Feed calculated by this dialog will not exceed these values even if you attempt to enter higher values into the Computed Variables fields. To exceed these values, change them here or you must edit the operation or tool parameters manually.

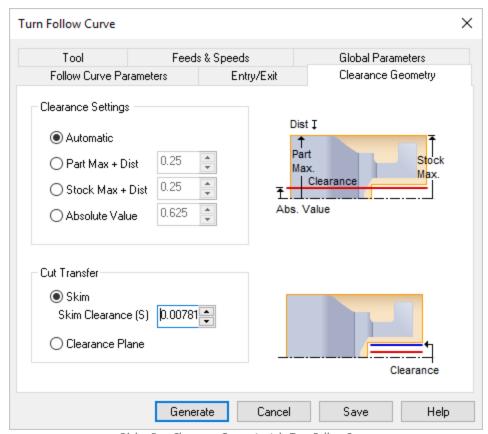
Computed Variables

The variables for Spindle Speed and Cut Feed (Cf) are computed for you based on the selections made in this dialog but will not exceed the values set in the Maximum Limits for Computation section of the dialog. These values are then assigned to the active toolpath operation or tool. You can override either of these variables and the other will update automatically. Since this dialog is a Feeds & Speeds Calculator, you cannot override both values. To do so, you must edit the operation or tool parameters manually.

8.5.6 Clearance

The following dialog allows you to select the appropriate Clearance Geometry for the Turn Follow Curve operation. In this tab, Clearance Settings and Cut Transfer parameters can be specified. See Clearance Plane for additional information.

Dialog Box: Clearance Geometry tab



Dialog Box: Clearance Geometry tab, Turn Follow Curve

Clearance Settings

Automatic

The system determines the clearance height based on the part and stock geometry.

Part Max + Dist

Uses Part maximum plus the specified distance for clearance height.

Stock Max + Dist

Uses Stock maximum plus the specified distance for clearance height. If stock geometry does not exist, it would use the maximum height of the part geometry.

Absolute Value

Uses the specified distance for clearance height.

For Turning operations, the User Interface for clearance settings are automatically set for OD, ID or Face depending on the approach type specified under global parameters.

For Hole Machining operations, the clearance plane is normal to the Z axis.

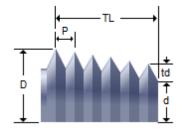
Cut Transfer

You can also control the transfer motions during cutting. When the cutter has finished cutting in one region and needs to transfer to another region to begin cutting, it can either be instructed to move to the clearance plane and then perform the transfer motion to the next cut location or it could do a skim motion. In the skim motion, the system automatically determines the safe height by taking into consideration the condition of the part model and using this Skim Clearance (S) value specified as the height to perform the transfer motions.

8.6 Threading

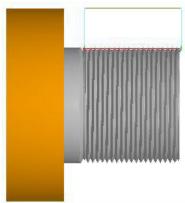


This operation is performed to machine threads on the part. Threads are used as fasteners for assembly purposes. OD and ID threads can be programmed using this method.



Turn Threading

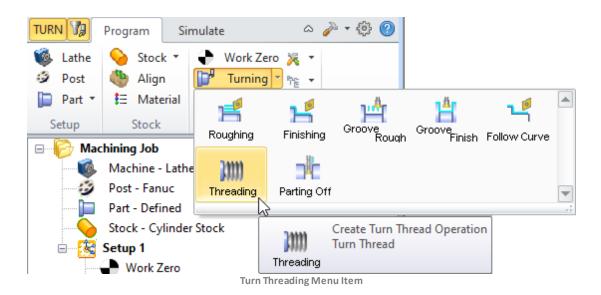
Turn Threading Example



Threading Operation Toolpath Example

Turn Threading Menu Item

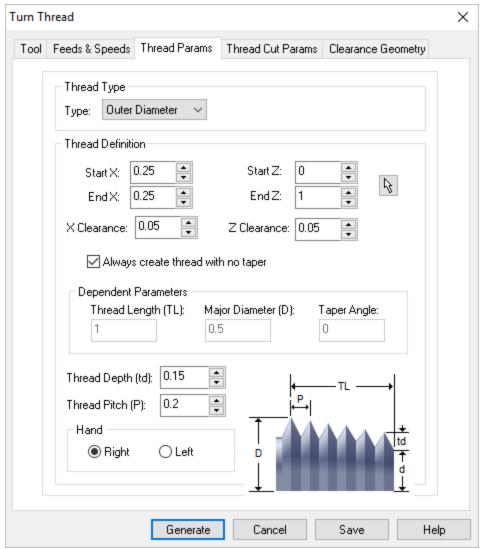
The Threading toolpath method is invoked by selecting the Program tab, clicking on the Turning button in the Machining Browser and selecting the Threading operation.



Dialog Box: Turn Thread

This section describes the various parameters that you can set to execute this machining operation. The dialog that is invoked when you choose this toolpath method is shown below:

This dialog has five tabs. Each tab defines a set of parameters that you can specify. The sections below describe them in detail.

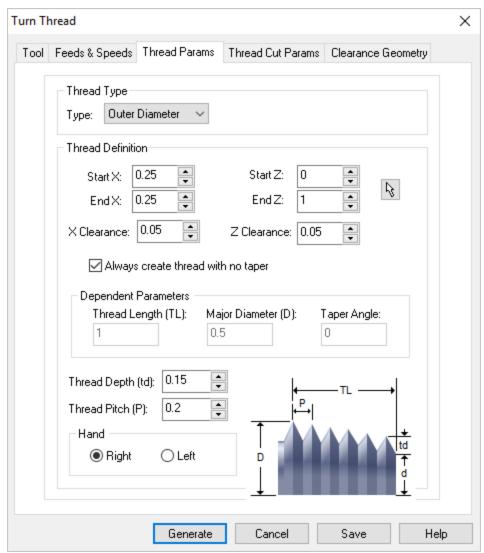


Dialog Box: Thread Parameters tab, Turn Threading

8.6.1 Thread Parameters

The following dialog allows you to set the Thread Parameters for Turn Threading operations. You can set the Thread Type and Thread Definition via this property page.

Dialog Box: Thread Parameters tab



Dialog Box: Thread Parameters tab, Turn Threading

Thread Type

This parameter determines the threading operation type for Inner Diameter or Outer Diameter (i.e., internal or external threads).

Thread Definition

You can define the starting and ending position of the threads either by inputting the X and Z coordinate values for the start and end points or using the pick option to graphically select 2 points.

Start XZ / End XZ

This defines the Start and End of the Turn Threading operation. You can enter the coordinate values directly use the Pick button and then select

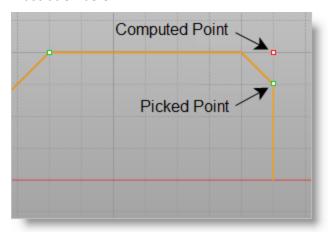
the start and end locations directly from the turn part profile. You can use the object snaps available for selecting points.

XZ Clearance

These fields allow you to set clearance along the X and Z axis. The Z Clearance is applied axially to the start of the thread. The X Clearance is an arbitrary clearance for the tool to move away from the thread.

Always create thread with no taper

Checking this box allows you to pick points on a non-straight area of the model and create a straight thread with no additional geometry creation. Refer to the illustration below:



Always create thread with no taper

• Dependent Parameters

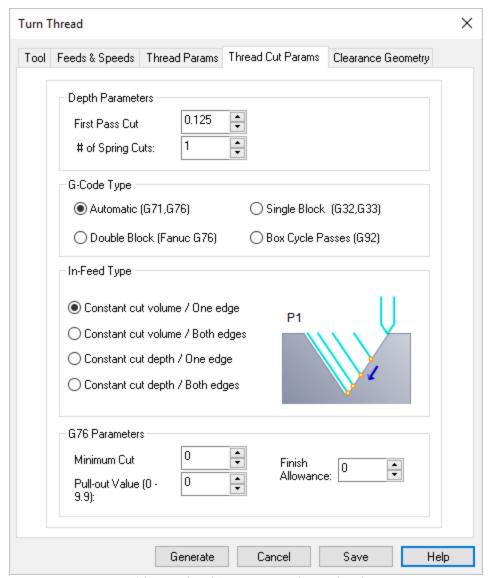
You can use the Pick button under the Thread Definition section to select the thread start and end points. Once defined, the system automatically determines the Thread Length (TL), Major Diameter (D) and Taper Angle from the part model.

- Thread Depth (tp) and Thread Pitch (P)
 These allow you to define the Thread Depth and Pitch manually.
- Hand
 The type of threads to be generated (Right Handed / Left Handed)

8.6.2 Thread Cut Parameters

This tab allows user to set the Depth parameters, Thread Cycle type and its parameters.

Dialog Box: Thread Cut Parameters tab



 ${\bf Dialog\,Box:}\,{\bf Thread\,Cut\,Parameters\,tab,\,Turn\,Thread}$

Depth Parameters

First Pass Cut

Enter the thread depth for the First Cut Pass. The tool will make one First Cut Pass along the length of the thread at this depth.

of Spring Cuts

Enter the total number of Spring Cuts to achieve the total thread depth. The tool will make one complete Spring Cut along the length of the thread and then repeat the Spring Cut the number of times specified. The depth of each Spring Cut is calculated automatically.

G-Code Type

The following types of threading cycles are supported:

Automatic (G71,G76)

Pick this option to choose the Automatic (G71,G76) g-code type. This is a repetitive threading cycle. With this selection, the In-Feed Type section and the G76 Parameters section of this dialog are activated.

Single Block (G32,G33)

Pick this option to choose the Single Block (G32,G33) g-code type. This is a single pass threading cycle.

Double Block (Fanuc G76)

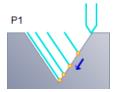
Pick this option to choose the Double Block (Fanuc G76) g-code type. This is a double pass threading cycle.

Box Cycle Passes (G92)

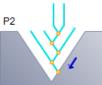
Pick this option to choose the Box Cycle Passes (G92) g-code type. This is a multiple pass threading cycle.

In-Feed Type

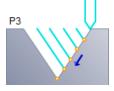
Constant cut volume / One edge - When G-Code Type is set to Automatic (G71,G76), select this option to perform a constant cut volume from one edge as shown.



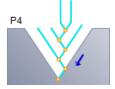
Constant cut volume / Both edges - When G-Code Type is set to Automatic (G71,G76), select this option to perform a constant cut volume from both edges as shown in the dialog image.



Constant cut depth / One edge - When G-Code Type is set to Automatic (G71,G76), select this option to perform a constant cut depth from one edge as shown.

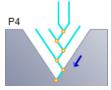


Constant cut depth / Both edges - When G-Code Type is set to Automatic (G71,G76), select this option to perform a constant cut depth from both edges as shown.



G76 Parameters

Constant cut depth / Both edges - When G-Code Type is set to Automatic (G71,G76), select this option to perform a constant cut depth from both edges as shown.



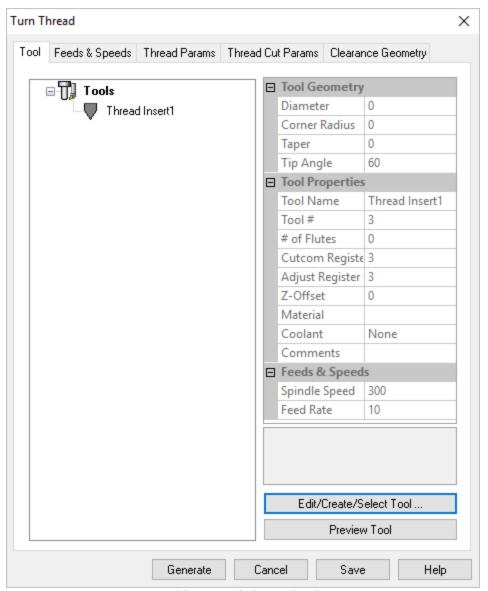
G76 Parameters / Pull-out Value (0-9.0) - The G76 threading cycle allows for a Pull-out Value. This is the lead or pullout when exiting the thread. The value can be set between 0 and 9.9.

G76 Parameters / Finish Allowance - This is the amount of material left on the thread before the final Finish pass.

8.6.3 Tool

The following dialog allows you to select the appropriate Thread Insert tool for the Turn Thread operation. The Tools in Session are listed on the left. Expanding the Tool tree will list the current operations assigned to that tool. The geometry parameters of the selected tool are displayed to the right. See Create Edit Tools for more information.





Dialog Box: Tool tab, Turn Thread

Edit/Create/Select Tool ...

If there are no Tools listed, select this button to Create a new tool. If a tool is listed and selected by default, select this button to Edit the parameters for that tool or to Select a different tool for the current operation.

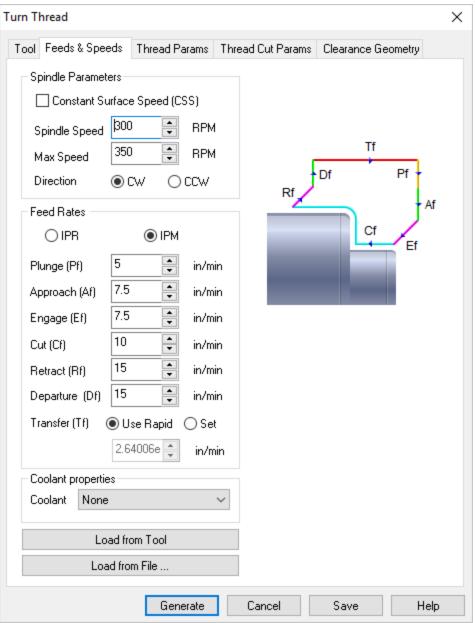
Preview Tool

Preview Tool - Select this button to display a graphical representation of the currently selected tool. This is the same Preview of the tool that you see displayed in the Edit/Create/Select Tool dialog.

8.6.4 Feeds & Speeds

The following dialog allows you to select the appropriate Feeds & Speeds for the Turn Thread operation. In this tab, Spindle Parameters and Feed Rates can be specified. Speeds & Feeds can also be loaded from a File or from the Tool.

Dialog Box: Feeds & Speeds tab



Dialog Box: Feeds & Speeds tab, Turn Thread

Spindle Parameters

Constant Surface Speed (CSS)

This is the Spindle Speed Mode. If this box is checked, the mode is set to Constant Surface Speed (CSS). If unchecked, the mode is set to Constant Rotational Speed (CRS).

If the Constant Surface Speed is checked, the controller would automatically calculate and adjust the spindle speed based on the current diameter of the work-piece. If this calculated spindle speed is greater than the maximum spindle speed specified in your post, the spindle speed would be reduced to the maximum speed. Refer to the Spindle section of the Post-Processor Generator to ensure your Spindle Mode is set correctly.

Spindle Speed

his is the rotational speed of the spindle expressed in RPM.

Surface Speed

Surface speed is set in units/min when Constant Surface Speed is selected. This is only applicable for turning inserts.

Max Speed

The maximum rotational speed of the spindle, in RPM. This is only applicable for turning inserts.

Direction

This determines the direction of spindle rotation and can be set to Clockwise or Counter Clockwise.



Feed Rates

Feedrate can be set in Units/Min or Units/Revolution for Turning Inserts.

Plunge (Pf)

This rate is the feed before the tool starts to engage in material. This is always vertical.

Approach (Af)

This is the feedrate used that prepares the cutter just before it starts engaging into material as it starts cutting. The approach motions are dependent on the method of machining.

Engage (Ef)

This is the feedrate used when the tool is performing an engage move. TURN Module sets this value to be 75% of the cutting speed.

Cut (Cf)

This is the feedrate used when the tool is cutting material

Retract (Rf)

The feedrate used when the tool is performing a retract move away from material. TURN Module sets this also to also be 75% of the cutting speed.

Departure (Df)

The feedrate used to retract the tool from the material.

Transfer (Tf)

This is the feedrate (in Units/Min), used for Transfer motions. Select Use Rapid to set this to the Transfer Feed value defined in the Feeds & Speeds section of the CAM Preferences dialog.

Coolant

Here you can override the Coolant that is specified by the Tool. Coolant can be set to Flood, Mist or Through. Coolant codes are defined in the post processor generator under Misc tab.

Load from Tool

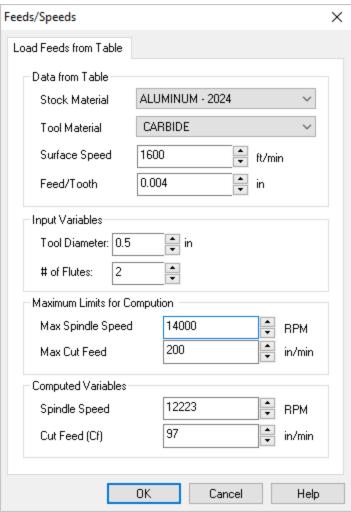
Feeds & Speeds are defined when a tool is created using Create/Edit Tools from the Machining Objects Browser. Selecting this button loads the Feeds & Speeds from the tool that is selected for the current machining operation.

Load from File ...

This loads the Feeds & Speeds values from the Feeds & Speeds Table file. This will display the Load Feeds from Table dialog box to make your selections.

Dialog Box: Load Feeds from Table

Selecting OK from this dialog transfers the spindle speed and cut feedrate to the Feeds & Speeds tab. The plunge, approach, engage, retract and departure feeds are determined using a percent of the cut feed. The percent to use for transferring the computed cut feed can be set under Feeds & Speeds Preferences.



Dialog Box: Load Feeds from Table

Data from Table

Stock Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Tool Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Surface Speed

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Feed/Tooth

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Input Variables

The input variables - Work Diameter is automatically loaded from the Stock Radius. Based on this parameter and the Variables Limits parameters, the program computes Spindle Speed and Cut Feedrate (Cf). measured in Unites/Revolution. Changing the spindle speed modifies the cut feedrate.

Maximum Limits for Computation

Here you can set the Max Spindle Speed and Max Cut Feed (Cf) values. Once these two values are set, the Spindle Speed and Cut Feed calculated by this dialog will not exceed these values even if you attempt to enter higher values into the Computed Variables fields. To exceed these values, change them here or you must edit the operation or tool parameters manually.

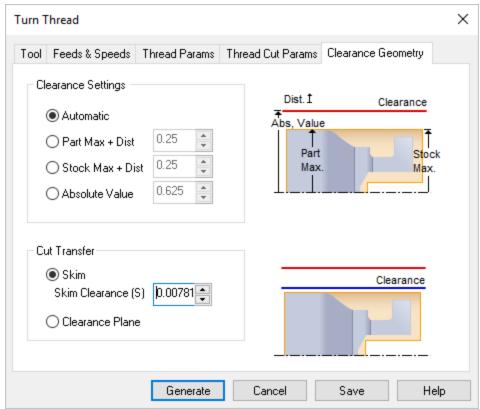
Computed Variables

The variables for Spindle Speed and Cut Feed (Cf) are computed for you based on the selections made in this dialog but will not exceed the values set in the Maximum Limits for Computation section of the dialog. These values are then assigned to the active toolpath operation or tool. You can override either of these variables and the other will update automatically. Since this dialog is a Feeds & Speeds Calculator, you cannot override both values. To do so, you must edit the operation or tool parameters manually.

8.6.5 Clearance

The following dialog allows you to select the appropriate Clearance Geometry for the Turn Thread operation. In this tab, Clearance Settings and Cut Transfer parameters can be specified. See Clearance Plane for additional information.

Dialog Box: Clearance Geometry tab



Dialog Box: Clearance Geometry tab, Turn Thread

Clearance Settings

Automatic

The system determines the clearance height based on the part and stock geometry.

Part Max + Dist

Uses Part maximum plus the specified distance for clearance height.

Stock Max + Dist

Uses Stock maximum plus the specified distance for clearance height. If stock geometry does not exist, it would use the maximum height of the part geometry.

Absolute Value

Uses the specified distance for clearance height.

For Turning operations, the User Interface for clearance settings are automatically set for OD, ID or Face depending on the approach type specified under global parameters.

For Hole Machining operations, the clearance plane is normal to the Z axis.

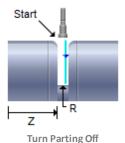
Cut Transfer

You can also control the transfer motions during cutting. When the cutter has finished cutting in one region and needs to transfer to another region to begin cutting, it can either be instructed to move to the clearance plane and then perform the transfer motion to the next cut location or it could do a skim motion. In the skim motion, the system automatically determines the safe height by taking into consideration the condition of the part model and using this Skim Clearance (S) value specified as the height to perform the transfer motions.

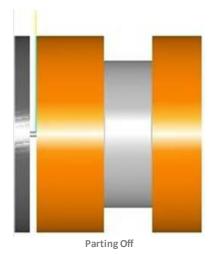
8.7 Parting Off



This operation is performed to cut off the finished part from the rest of the bar stock which is typically done as the last operation in OD.

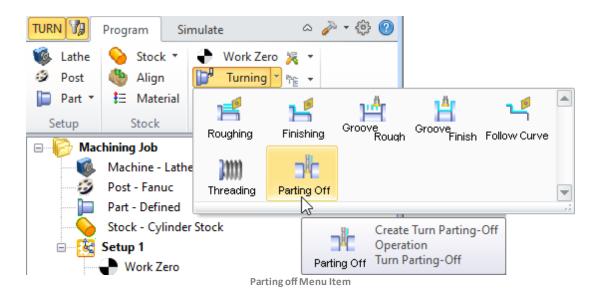


Turn Parting Off Example



Turn Parting Off Menu Item

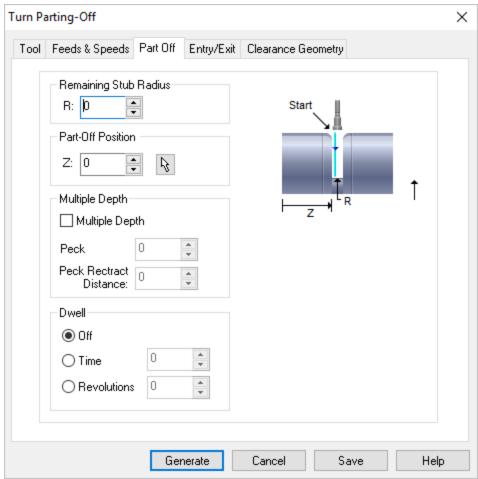
The Parting Off toolpath method is invoked by selecting the Program tab, clicking on the Turning button in the Machining Browser and selecting the Parting Off operation.



Dialog Box: Turn Parting-Off

This section describes the various parameters that you can set to execute this machining operation. The dialog that is invoked when you choose this toolpath method is shown below:

This dialog has five tabs. Each tab defines a set of parameters that you can specify. The sections below describe them in detail.

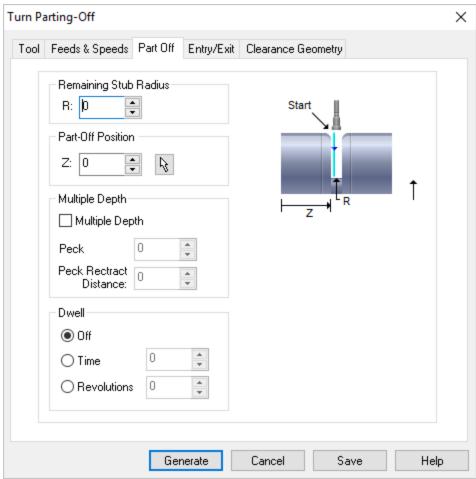


Dialog Box: Turn Parting-Off

8.7.1 Part Off Parameters

The following dialog allows you to set the Part Off Parameters for Turn Part Off operations. You can set the Remaining Stub Radius, PartOff Position, Multiple Depth and Dwell via this property page. All the turning operations as mentioned below, except Part Off Position, can be carried on the Outer Diameter, Inner Diameter or the Front Face of the work-piece.

Dialog Box: Part Off tab



Dialog Box: Turn Parting-Off

Remaining Stub Radius

Remaining Stub Radius (R) - This is the radius of the final part of the stock to be left uncut during the parting operation.

Part Off Position

Part-Off Position - This is the Z coordinate location for positioning the part-off location. You can enter the coordinate value directly or select the Pick button to select the point from your part model whose Z coordinate to use.

Multiple Depth

Multiple Depth - Check this box to enable Multiple Depth pecking for the part-off operation. For Peck enter the peck depth. For Peck Retract Distance, enter the distance that you want the tool to retract between pecks.

Dwell

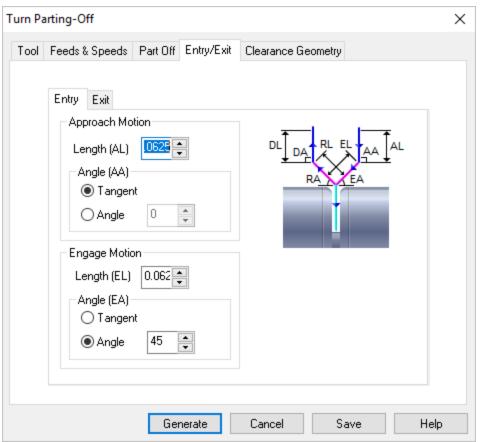
Dwell - This is an optional parameter that allows you to set a machine delay (Dwell) during the Part-Off operation. You can set this to Off (no dwell), Time (enter the

number of seconds to Dwell) or Revolutions (enter number of revolutions to Dwell).

8.7.2 Entry/Exit

The following dialog allows you to set Entry/Exit parameters for Turn Part Off operations. Entry and Exit determines the way in which tool enters and leaves the part geometry. TURN Module allows you to specify how the cutter approaches, engages, retracts and departs when starting and stopping a cut.

Dialog Box: Entry/Exit tab



Dialog Box: Entry/Exit tab, Turn Part Off

Entry Tab

The Entry tab (shown in the dialog box above) consists of Approach and Engage. You can set different feeds for plunge, approach, engage, cut, retract and depart moves. The tool moves to the position above the approach point with a plunge feed, then uses the approach feed rate for the vertical approach motion and engage feed rate for the engage motion.

The approach can be either Tangential or at an angle to the Engage motion. This is followed by the engage motion that can be Tangential or at an angle.

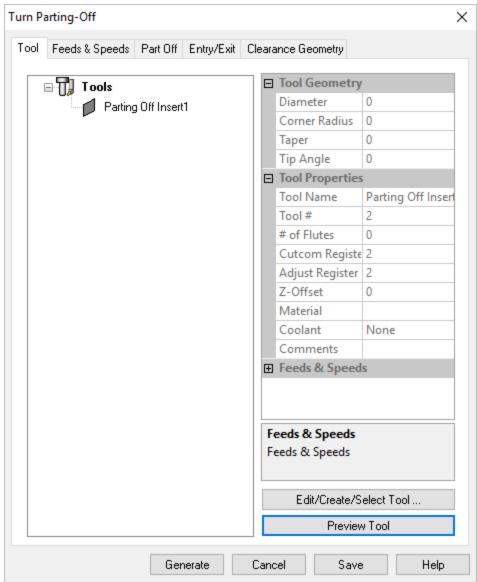
Exit Tab

Similarly the Exit motion consists of a Retract motion followed by a departure motion. The retract motion can be either Tangential or at an angle. The departure motion can be either Tangential or at an angle to the Retract motion.

8.7.3 Tool

The following dialog allows you to select the appropriate insert tool for the Turn Part Off operation. The Tools in Session are listed on the left. Expanding the Tool tree will list the current operations assigned to that tool. The geometry parameters of the selected tool are displayed to the right. See Create Edit Tools for more information.

Dialog Box: Tool tab



Dialog Box: Tool tab, Turn Part Off

Edit/Create/Select Tool ...

If there are no Tools listed, select this button to Create a new tool. If a tool is listed and selected by default, select this button to Edit the parameters for that tool or to Select a different tool for the current operation.

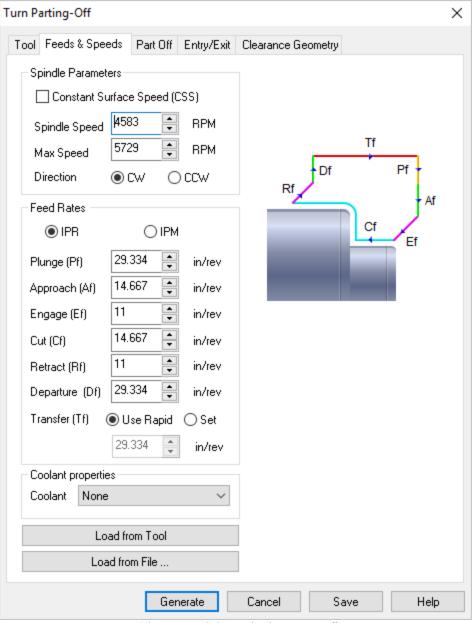
Preview Tool

Preview Tool - Select this button to display a graphical representation of the currently selected tool. This is the same Preview of the tool that you see displayed in the Edit/Create/Select Tool dialog.

8.7.4 Feeds & Speeds

The following dialog allows you to select the appropriate Feeds & Speeds for the Turn Part Off operation. In this tab, Spindle Parameters and Feed Rates can be specified. Speeds & Feeds can also be loaded from a File or from the Tool.

Dialog Box: Feeds & Speeds tab



Dialog Box: Feeds & Speeds tab, Turn Part Off

Spindle Parameters

Constant Surface Speed (CSS)

This is the Spindle Speed Mode. If this box is checked, the mode is set to Constant Surface Speed (CSS). If unchecked, the mode is set to Constant Rotational Speed (CRS).

If the Constant Surface Speed is checked, the controller would automatically calculate and adjust the spindle speed based on the current diameter of the work-piece. If this calculated spindle speed is greater than the maximum spindle speed specified in your post, the spindle speed would be reduced to the maximum speed. Refer to the Spindle section of the Post-Processor Generator to ensure your Spindle Mode is set correctly.

Spindle Speed

his is the rotational speed of the spindle expressed in RPM.

Surface Speed

Surface speed is set in units/min when Constant Surface Speed is selected. This is only applicable for turning inserts.

Max Speed

The maximum rotational speed of the spindle, in RPM. This is only applicable for turning inserts.

Direction

This determines the direction of spindle rotation and can be set to Clockwise or Counter Clockwise.



Feed Rates

Feedrate can be set in Units/Min or Units/Revolution for Turning Inserts.

Plunge (Pf)

This rate is the feed before the tool starts to engage in material. This is always vertical.

Approach (Af)

This is the feedrate used that prepares the cutter just before it starts engaging into material as it starts cutting. The approach motions are dependent on the method of machining.

Engage (Ef)

This is the feedrate used when the tool is performing an engage move. TURN Module sets this value to be 75% of the cutting speed.

Cut (Cf)

This is the feedrate used when the tool is cutting material

Retract (Rf)

The feedrate used when the tool is performing a retract move away from material. TURN Module sets this also to also be 75% of the cutting speed.

Departure (Df)

The feedrate used to retract the tool from the material.

Transfer (Tf)

This is the feedrate (in Units/Min), used for Transfer motions. Select Use Rapid to set this to the Transfer Feed value defined in the Feeds & Speeds section of the CAM Preferences dialog.

Coolant

Here you can override the Coolant that is specified by the Tool. Coolant can be set to Flood, Mist or Through. Coolant codes are defined in the post processor generator under Misc tab.

Load from Tool

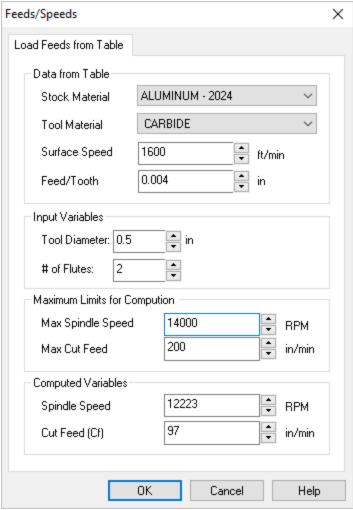
Feeds & Speeds are defined when a tool is created using Create/Edit Tools from the Machining Objects Browser. Selecting this button loads the Feeds & Speeds from the tool that is selected for the current machining operation.

Load from File ...

This loads the Feeds & Speeds values from the Feeds & Speeds Table file. This will display the Load Feeds from Table dialog box to make your selections.

Dialog Box: Load Feeds from Table

Selecting OK from this dialog transfers the spindle speed and cut feedrate to the Feeds & Speeds tab. The plunge, approach, engage, retract and departure feeds are determined using a percent of the cut feed. The percent to use for transferring the computed cut feed can be set under Feeds & Speeds Preferences.



Dialog Box: Load Feeds from Table

Data from Table

Stock Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Tool Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Surface Speed

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Feed/Tooth

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Input Variables

The input variables - Work Diameter is automatically loaded from the Stock Radius. Based on this parameter and the Variables Limits parameters, the program computes Spindle Speed and Cut Feedrate (Cf). measured in Unites/Revolution. Changing the spindle speed modifies the cut feedrate.

Maximum Limits for Computation

Here you can set the Max Spindle Speed and Max Cut Feed (Cf) values. Once these two values are set, the Spindle Speed and Cut Feed calculated by this dialog will not exceed these values even if you attempt to enter higher values into the Computed Variables fields. To exceed these values, change them here or you must edit the operation or tool parameters manually.

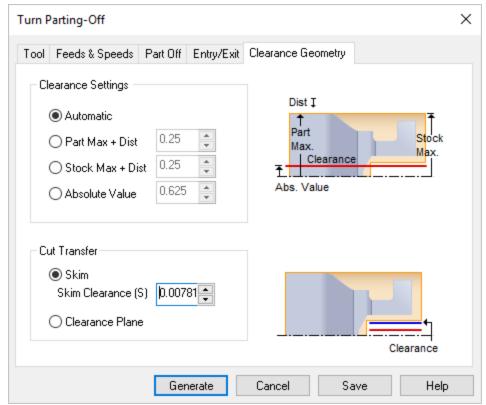
Computed Variables

The variables for Spindle Speed and Cut Feed (Cf) are computed for you based on the selections made in this dialog but will not exceed the values set in the Maximum Limits for Computation section of the dialog. These values are then assigned to the active toolpath operation or tool. You can override either of these variables and the other will update automatically. Since this dialog is a Feeds & Speeds Calculator, you cannot override both values. To do so, you must edit the operation or tool parameters manually.

8.7.5 Clearance

The following dialog allows you to select the appropriate Clearance Geometry for the Turn Part Off operation. In this tab, Clearance Settings and Cut Transfer parameters can be specified. See Clearance Plane for additional information.

Dialog Box: Clearance Geometry tab



Dialog Box: Clearance Geometry tab, Turn Part Off

Clearance Settings

Automatic

The system determines the clearance height based on the part and stock geometry.

Part Max + Dist

Uses Part maximum plus the specified distance for clearance height.

Stock Max + Dist

Uses Stock maximum plus the specified distance for clearance height. If stock geometry does not exist, it would use the maximum height of the part geometry.

Absolute Value

Uses the specified distance for clearance height.

For Turning operations, the User Interface for clearance settings are automatically set for OD, ID or Face depending on the approach type specified under global parameters.

For Hole Machining operations, the clearance plane is normal to the Z axis.

Cut Transfer

You can also control the transfer motions during cutting. When the cutter has finished cutting in one region and needs to transfer to another region to begin cutting, it can either be instructed to move to the clearance plane and then perform the transfer motion to the next cut location or it could do a skim motion. In the skim motion, the system automatically determines the safe height by taking into consideration the condition of the part model and using this Skim Clearance (S) value specified as the height to perform the transfer motions.

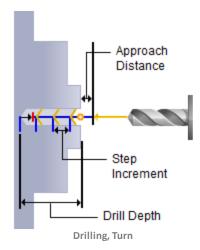
Creating Hole Making Operations

This section details the hole making operation types that can be created.

9.1 Drilling

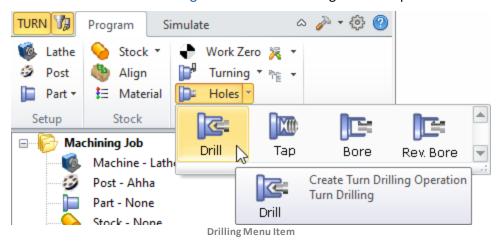


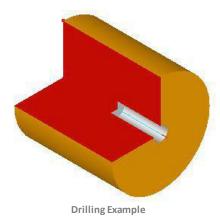
The Drill cycle is used to cut holes in the part. The drilling toolpath method is invoked by selecting the Program tab, clicking on the Holes button in the Machining Browser and selecting the Drill operation.. **Note**: For each tab in the dialog, select a topic from the Contents on the left.



Drill Menu Selection

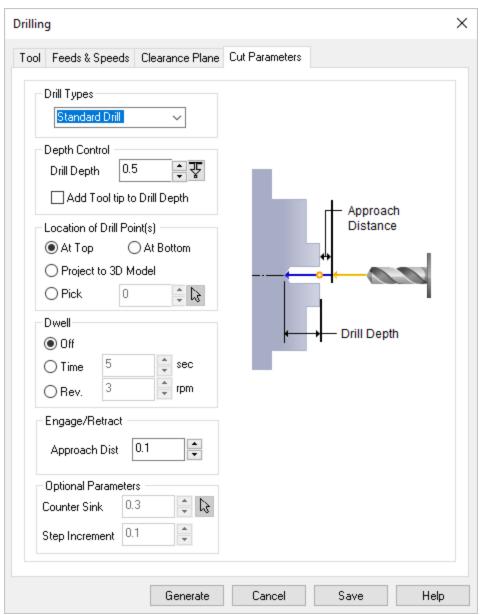
The Drilling toolpath method is invoked by selecting the Program tab, clicking on the Holes button in the Machining Browser and selecting the Drill operation.





Dialog Box: Drill

The toolpath generated depends on your defined parameters. The various parameters that you can set can be seen in the dialog box that is invoked when you choose the Drill operation. This dialog box is shown below.



Dialog Box: Global Parameters tab, Turn Roughing

The following Drill Types are available

Standard
 Used for holes whose depth is less than three times the tool diameter.

Deep

Used for holes whose depth is greater than three times the tool diameter, especially when chips are difficult to remove. The tool retracts completely to clean out all chips.

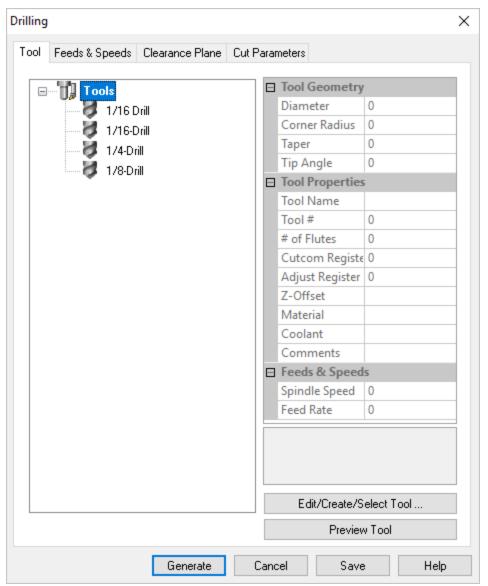
• Counter Sink
Cuts an angular opening at the end of the hole.

- Break Chip
 Similar to Deep drilling, but the tool retracts by a set clearance distance.
- User Defined Drill1 and Drill2
 Allows for the definition of user defined drill types.

9.1.1 Tool

The following dialog allows you to select the appropriate tool (Standard Drill, Center Drill or Reamer) for the Turn Drill operation. The Tools in Session are listed on the left. Expanding the Tool tree will list the current operations assigned to that tool. The geometry parameters of the selected tool are displayed to the right. See Create Edit Tools for more information.

Dialog Box: Tool tab



Dialog Box: Tool tab, Turn Drilling

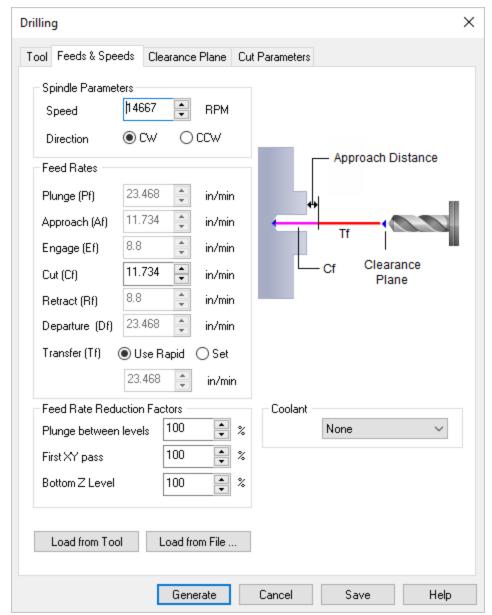
Edit/Create/Select Tool ...

If there are no Tools listed, select this button to Create a new tool. If a tool is listed and selected by default, select this button to Edit the parameters for that tool or to Select a different tool for the current operation.

9.1.2 Feeds & Speeds

The following dialog allows you to select the appropriate Feeds & Speeds for the Turn Drilling operation. In this tab, Spindle Parameters and Feed Rates can be specified. Speeds & Feeds can also be loaded from a File or from the Tool.

Dialog Box: Feeds & Speeds tab



Dialog Box: Feeds & Speeds for Hole Machining operations

Spindle Parameters

Speed

This is the rotational speed of the spindle expressed in RPM.

Direction

This determines the direction of spindle rotation and can be set to CW Clockwise or CCW Counter Clockwise.

Feed Rates

Feedrate can be set in Units/Min or Units/Revolution for Turning Inserts.

Plunge (Pf)

This rate is the feed before the tool starts to engage in material. This is always vertical.

Approach (Af)

This is the feedrate used that prepares the cutter just before it starts engaging into material as it starts cutting. The approach motions are dependent on the method of machining.

Engage (Ef)

This is the feedrate used when the tool is performing an engage move. TURN Module sets this value to be 75% of the cutting speed.

Cut (Cf)

This is the feedrate used when the tool is cutting material

Retract (Rf)

The feedrate used when the tool is performing a retract move away from material. TURN Module sets this also to also be 75% of the cutting speed.

Departure (Df)

The feedrate used to retract the tool from the material.

Transfer (Tf)

This is the feedrate (in Units/Min), used for Transfer motions. Select Use Rapid to set this to the Transfer Feed value defined in the Feeds & Speeds section of the CAM Preferences dialog.

Feed Rate Reduction Factors

This sets Feed Rate Reduction Factors for Plunge Between Levels and the First XY pass.

Load from Tool

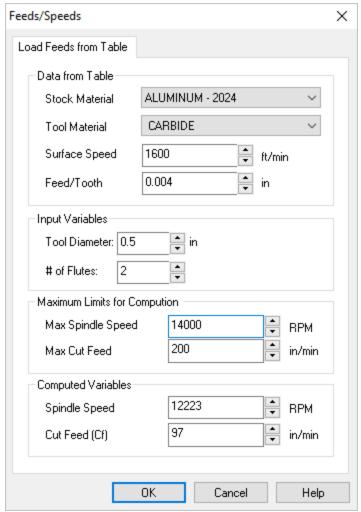
Feeds & Speeds are defined when a tool is created using Create/Edit Tools from the Machining Objects Browser. Selecting this button loads the Feeds & Speeds from the tool that is selected for the current machining operation.

Load from File ...

This loads the Feeds & Speeds values from the Feeds & Speeds Table file. This will display the Load Feeds from Table dialog box to make your selections.

Dialog Box: Load Feeds from Table

Selecting OK from this dialog transfers the spindle speed and cut feedrate to the Feeds & Speeds tab. The plunge, approach, engage, retract and departure feeds are determined using a percent of the cut feed. The percent to use for transferring the computed cut feed can be set under Feeds & Speeds Preferences.



Dialog Box: Load Feeds from Table

Data from Table

Stock Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Tool Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Surface Speed

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Feed/Tooth

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Input Variables

The input variables - Work Diameter is automatically loaded from the Stock Radius. Based on this parameter and the Variables Limits parameters, the program computes Spindle Speed and Cut Feedrate (Cf). measured in Unites/Revolution. Changing the spindle speed modifies the cut feedrate.

Maximum Limits for Computation

Here you can set the Max Spindle Speed and Max Cut Feed (Cf) values. Once these two values are set, the Spindle Speed and Cut Feed calculated by this dialog will not exceed these values even if you attempt to enter higher values into the Computed Variables fields. To exceed these values, change them here or you must edit the operation or tool parameters manually.

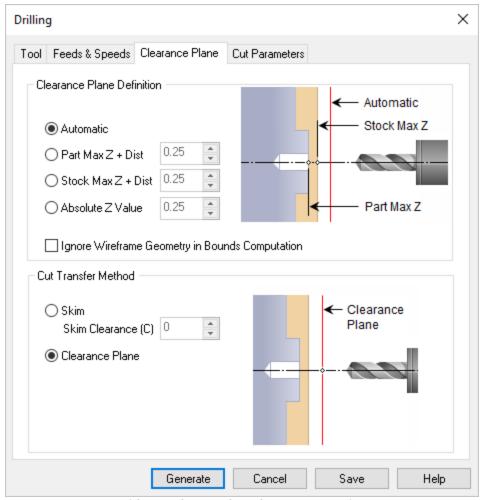
Computed Variables

The variables for Spindle Speed and Cut Feed (Cf) are computed for you based on the selections made in this dialog but will not exceed the values set in the Maximum Limits for Computation section of the dialog. These values are then assigned to the active toolpath operation or tool. You can override either of these variables and the other will update automatically. Since this dialog is a Feeds & Speeds Calculator, you cannot override both values. To do so, you must edit the operation or tool parameters manually.

9.1.3 Clearance

The following dialog allows you to select the appropriate Clearance Plane for the Turn Drilling operation. In this tab, Clearance Plane Definition and Cut Transfer Method parameters can be specified. See Clearance Plane for additional information.

Dialog Box: Clearance Plane tab



Dialog Box: Clearance Plane tab, Turn Reverse Boring

Clearance Plane Definition

Automatic

The system determines the clearance height based on the part and stock geometry.

Part Max + Dist

Uses Part maximum plus the specified distance for clearance height.

Stock Max + Dist

Uses Stock maximum plus the specified distance for clearance height. If stock geometry does not exist, it would use the maximum height of the part geometry.

Absolute Value

Uses the specified distance for clearance height.

For Turning operations, the User Interface for clearance settings are automatically set for OD, ID or Face depending on the approach type specified under global parameters.

For Hole Machining operations, the clearance plane is normal to the Z axis.

Ignore Wireframe Geometry in Bounds Computation

Check this box to ignore all wireframe geometry when calculating the Clearance Plane definition. When checked, the Automatic and Part Max options for defining the Clearance will be calculated from actual surface geometry.

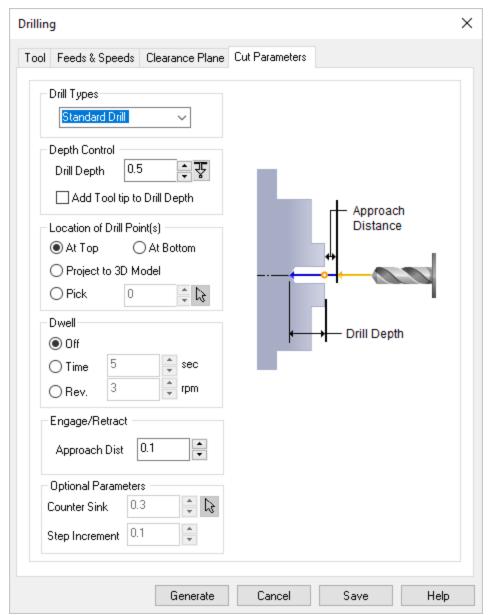
Cut Transfer Method

You can also control the transfer motions during cutting. When the cutter has finished cutting in one region and needs to transfer to another region to begin cutting, it can either be instructed to move to the clearance plane and then perform the transfer motion to the next cut location or it could do a skim motion. In the skim motion, the system automatically determines the safe height by taking into consideration the condition of the part model and using this Skim Clearance (S) value specified as the height to perform the transfer motions.

9.1.4 Cut Parameters

The following dialog allows you to set the Cut Parameters for Turn Drilling operations. You can set the Drill Type, Depth Control, Location, Dwell and other Optional Parameters via this dialog box.

Dialog Box: Cut Parameters tab



Dialog Box: Global Parameters tab, Turn Roughing

Drill Types

Drill Types - This defines the type of drill cycle to use: Standard Drill (when depth is < than 2x dia.), Deep Drill (when depth is > 2x dia.), Breakchip Drill (with Step Increment), Countersink Drill, (with Counter Sink Dia.) or User Defined Drill1-4 (see Cycles section of the Post Process Generator).

Depth Control

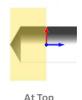
Depth refers to the actual hole depth you wish to achieve.

Add Tool Tip to Drill Depth - Check this box to compute the height of the drill tool taper and add it to the total Drill Depth.



Location of Drill Point(s)

Select this option if drilling should start at your Work Zero. The Drill Depth is then subtracted to this location. An actual point is not required. The location is determined automatically by your Work Zero location.

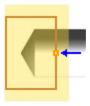


Select this option if drilling should end at your Work Zero. The Drill Depth is then added to this location. An actual point is not required. The location is determined automatically by your Work Zero location.



Project to 3D Model

Select this option if you want to project the start point to your 3D model. For example, if your stock is longer than your part but you want the Drill Depth to begin at the face of your part instead of the face of the stock. An actual point is not required. The location is determined automatically by your part model.



Project to 3D Model

Select this option if you want to specify the coordinates of point where the drilling should end at your Work Zero. The Drill Depth is then added to this location. An actual point is not required. The location is determined automatically by your Work Zero location. You can select the Pick button and then select a point on your part. It's coordinate will be calculated automatically.



Pick Top

Dwell

Dwell is an optional parameter that allows a machine delay of either Time (sec) Rev (rpm) of the spindle.

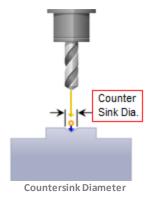
Engage/Retract

You can define the Approach Distance under Engage/Retract. The tool rapids in the Z axis to the approach plane and then applies the specified feedrate from the approach plane to the specified depth to perform the cycle.

Optional Parameters

The following additional parameters are supported:

Under Optional Parameters, Counter Sink Dia. is only required for the Counter Sink Drill Type operation. The system will automatically calculate the drill depth to achieve the required Counter Sink Diameter. Optionally, you can use the pick button to select a circle to define the diameter of the Counter Sink.

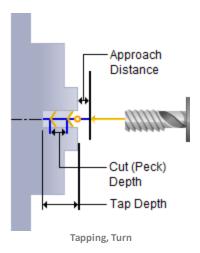


Step Increment - If Drill Type is set to either Deep Drill or Breakchip Drill, enter the Step Increment in the field provided. The tool will retract after each step increment completely to clean out the chips.

9.2 Tapping

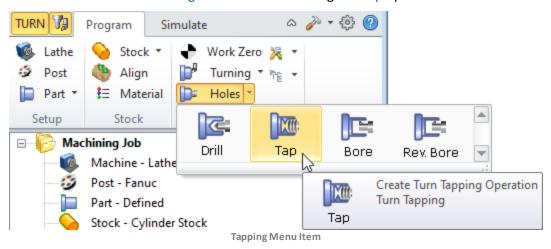


These operations are used to create tapped holes in the part. The Tapping toolpath method is invoked by selecting the Program tab, clicking on the Holes button in the Machining Browser and selecting the Tap operation. **Note**: For each tab in the dialog, select a topic from the Contents on the left.



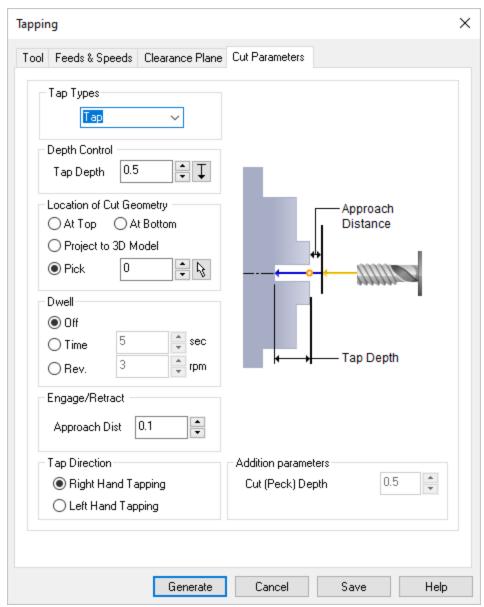
Tapping Menu Selection (TURN Module)

The Tapping toolpath method is invoked by selecting the Program tab, clicking on the Holes button in the Machining Browser and selecting the Tap operation.



Dialog Box: Tap

The toolpath generated depends on your defined parameters. The various parameters that you can set can be seen in the dialog box that is invoked when you choose the Tap operation. This dialog box is shown below.

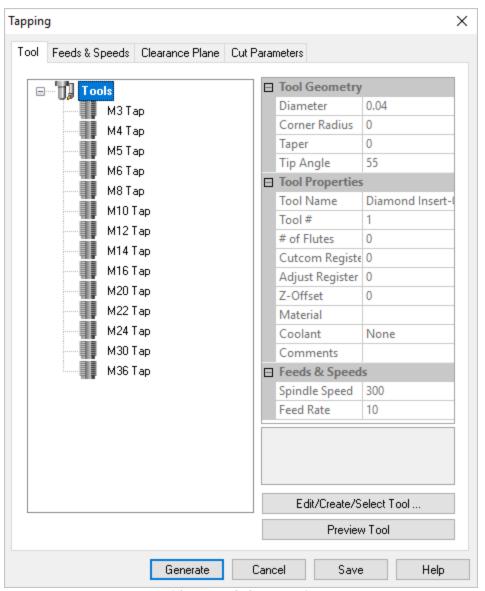


Dialog Box: Cut Parameters tab, Turn Tapping

9.2.1 Tool

The following dialog allows you to select the appropriate Tap tool for the Turn Tap operation. The Tools in Session are listed on the left. Expanding the Tool tree will list the current operations assigned to that tool. The geometry parameters of the selected tool are displayed to the right. See Create Edit Tools for more information.

Dialog Box: Tool tab



Dialog Box: Tool tab, Turn Tapping

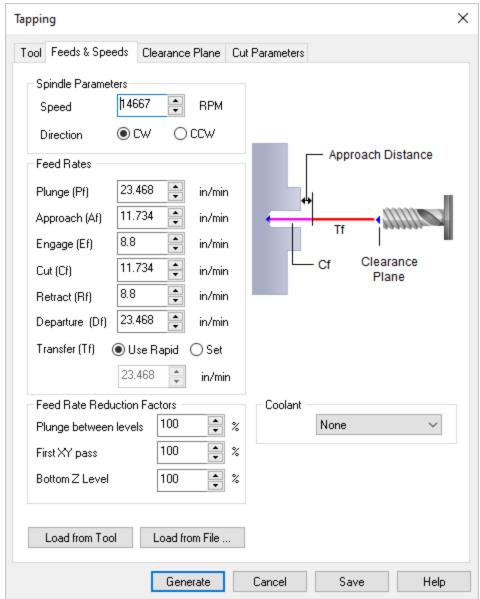
Edit/Create/Select Tool ...

If there are no Tools listed, select this button to Create a new tool. If a tool is listed and selected by default, select this button to Edit the parameters for that tool or to Select a different tool for the current operation.

9.2.2 Feeds & Speeds

The following dialog allows you to select the appropriate Feeds & Speeds for the Turn Drilling operation. In this tab, Spindle Parameters and Feed Rates can be specified. Speeds & Feeds can also be loaded from a File or from the Tool.

Dialog Box: Feeds & Speeds tab



Dialog Box: Feeds & Speeds tab, Turn Tap

Spindle Parameters

Speed

This is the rotational speed of the spindle expressed in RPM.

Direction

This determines the direction of spindle rotation and can be set to CW Clockwise or CCW Counter Clockwise.

Feed Rates

Feedrate can be set in Units/Min or Units/Revolution for Turning Inserts.

Plunge (Pf)

This rate is the feed before the tool starts to engage in material. This is always vertical.

Approach (Af)

This is the feedrate used that prepares the cutter just before it starts engaging into material as it starts cutting. The approach motions are dependent on the method of machining.

Engage (Ef)

This is the feedrate used when the tool is performing an engage move. TURN Module sets this value to be 75% of the cutting speed.

Cut (Cf)

This is the feedrate used when the tool is cutting material

Retract (Rf)

The feedrate used when the tool is performing a retract move away from material. TURN Module sets this also to also be 75% of the cutting speed.

Departure (Df)

The feedrate used to retract the tool from the material.

Transfer (Tf)

This is the feedrate (in Units/Min), used for Transfer motions. Select Use Rapid to set this to the Transfer Feed value defined in the Feeds & Speeds section of the CAM Preferences dialog.

Additional Feed Rate information for Tapped Holes

For tap operations, the feedrate can be computed in different ways. This depends on what is expected by the controller.

- Spindle Speed x Thread Pitch
- Thread Pitch
- 1/ Thread Pitch
- Cut Feedrate

The post needs to be setup with the appropriate variable to output the feedrate. The Thread Pitch is defined under the Tool tab and Spindle Speed is set under the Feeds & Speed tab shown above.

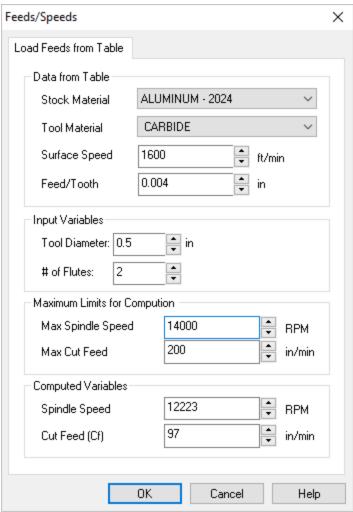
Use the following macro's in the post to output the feedrate

- [CYCL_IPR] Spindle Speed x Thread Pitch
- [CYCL_TPI] Thread Pitch
- [CYCL_1/TPI] 1/ Thread Pitch

• [CUT_FEED] – Cut Feedrate
Feed Rate Reduction Factors
This sets Feed Rate Reduction Factors for Plunge Between Levels and the First XY pass.
Load from Tool
Feeds & Speeds are defined when a tool is created using Create/Edit Tools from the Machining Objects Browser. Selecting this button loads the Feeds & Speeds from the tool that is selected for the current machining operation.
Load from File
This loads the Feeds & Speeds values from the Feeds & Speeds Table file. This will display the Load Feeds from Table dialog box to make your selections.
Dialog Box: Load Feeds from Table
Selecting OK from this dialog transfers the spindle speed and cut feedrate to the Feeds & Speeds tab. The plunge, approach, engage, retract and departure feeds are determined using a percent of the cut feed. The percent to use for

transferring the computed cut feed can be set under Feeds & Speeds

Preferences.



Dialog Box: Load Feeds from Table

Data from Table

Stock Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Tool Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Surface Speed

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Feed/Tooth

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Input Variables

The input variables - Work Diameter is automatically loaded from the Stock Radius. Based on this parameter and the Variables Limits parameters, the program computes Spindle Speed and Cut Feedrate (Cf). measured in Unites/Revolution. Changing the spindle speed modifies the cut feedrate.

Maximum Limits for Computation

Here you can set the Max Spindle Speed and Max Cut Feed (Cf) values. Once these two values are set, the Spindle Speed and Cut Feed calculated by this dialog will not exceed these values even if you attempt to enter higher values into the Computed Variables fields. To exceed these values, change them here or you must edit the operation or tool parameters manually.

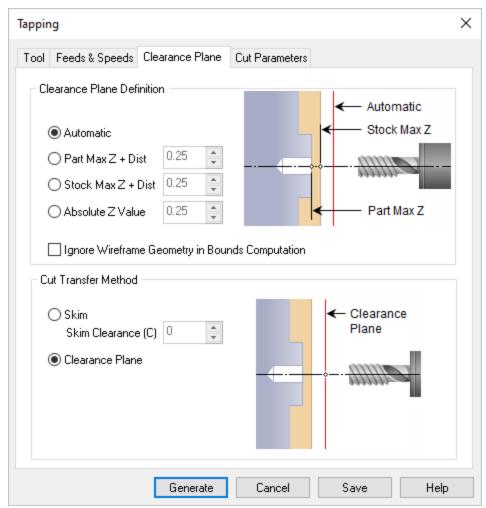
Computed Variables

The variables for Spindle Speed and Cut Feed (Cf) are computed for you based on the selections made in this dialog but will not exceed the values set in the Maximum Limits for Computation section of the dialog. These values are then assigned to the active toolpath operation or tool. You can override either of these variables and the other will update automatically. Since this dialog is a Feeds & Speeds Calculator, you cannot override both values. To do so, you must edit the operation or tool parameters manually.

9.2.3 Clearance

The following dialog allows you to select the appropriate Clearance Plane for the Turn Tapping operation. In this tab, Clearance Plane Definition and Cut Transfer Method parameters can be specified. See Clearance Plane for additional information.

Dialog Box: Clearance Plane tab



Dialog Box: Clearance Plane tab, Turn Tapping

Clearance Plane Definition

Automatic

The system determines the clearance height based on the part and stock geometry.

Part Max + Dist

Uses Part maximum plus the specified distance for clearance height.

Stock Max + Dist

Uses Stock maximum plus the specified distance for clearance height. If stock geometry does not exist, it would use the maximum height of the part geometry.

Absolute Value

Uses the specified distance for clearance height.

For Turning operations, the User Interface for clearance settings are automatically set for OD, ID or Face depending on the approach type specified under global parameters.

For Hole Machining operations, the clearance plane is normal to the Z axis.

Ignore Wireframe Geometry in Bounds Computation

Check this box to ignore all wireframe geometry when calculating the Clearance Plane definition. When checked, the Automatic and Part Max options for defining the Clearance will be calculated from actual surface geometry.

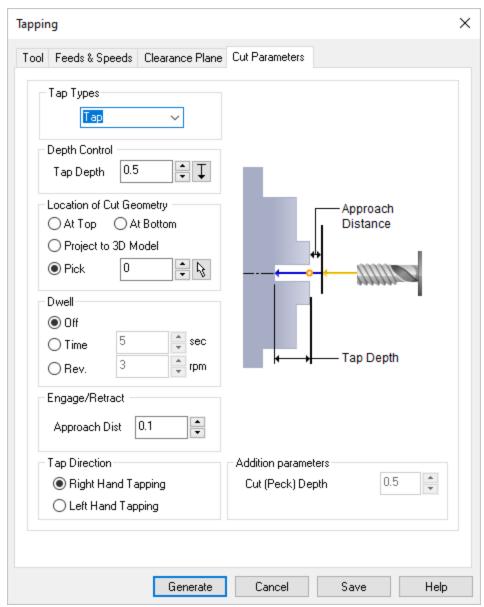


You can also control the transfer motions during cutting. When the cutter has finished cutting in one region and needs to transfer to another region to begin cutting, it can either be instructed to move to the clearance plane and then perform the transfer motion to the next cut location or it could do a skim motion. In the skim motion, the system automatically determines the safe height by taking into consideration the condition of the part model and using this Skim Clearance (S) value specified as the height to perform the transfer motions.

9.2.4 Cut Parameters

The following dialog allows you to set the Cut Parameters for Turn Tapping operations. You can set the Tap Type, Depth Control, Location, Dwell and other parameters via this dialog box.

Dialog Box: Cut Parameters tab



Dialog Box: Cut Parameters tab, Turn Tapping

Tap Types

Tap Types - This defines the type of tap cycle to use: Standard Tap (for canned tap cycles) or Peck Tapping (see Cut Peck Depth field below) and Tap 1-4 (see Cycles section of the Post Process Generator for user defined tap cycles 1-4).

Depth Control

Tap Depth - Enter the depth for the current drill operation. You can select the Pick button to pick a point on your part model that defines the drill depth.

Location of Cut Geometry

Select this option if drilling should start at your Work Zero. The Drill Depth is then subtracted to this location. An actual point is not required. The location is determined automatically by your Work Zero location.



At Top

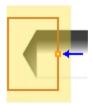
Select this option if drilling should end at your Work Zero. The Drill Depth is then added to this location. An actual point is not required. The location is determined automatically by your Work Zero location.



At Bottom

Project to 3D Model

Select this option if you want to project the start point to your 3D model. For example, if your stock is longer than your part but you want the Drill Depth to begin at the face of your part instead of the face of the stock. An actual point is not required. The location is determined automatically by your part model.



Project to 3D Model

Select this option if you want to specify the coordinates of point where the drilling should end at your Work Zero. The Drill Depth is then added to this location. An actual point is not required. The location is determined automatically by your Work Zero location. You can select the Pick button and then select a point on your part. It's coordinate will be calculated automatically.



Pick Top



Dwell is an optional parameter that allows a machine delay of either Time (sec) Rev (rpm) of the spindle.

Engage/Retract

You can define the Approach Distance under Engage/Retract. The tool rapids in the Z axis to the approach plane and then applies the specified feedrate from the approach plane to the specified depth to perform the cycle.

Tap Direction

Tap Direction - This allows you to select between clockwise and counter clockwise tap. Right Hand Tapping creates a clockwise tap cycle. Left Hand Tapping creates a counter clockwise tap cycle.

Additional Parameters

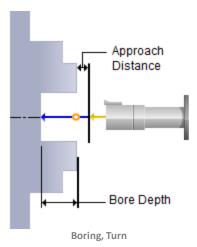
Cut Peck Depth

Used to set the peck depth increment. This needs to be specified for Peck Tapping. The tool retracts after each increment completely to clean out all the chips.

9.3 Boring

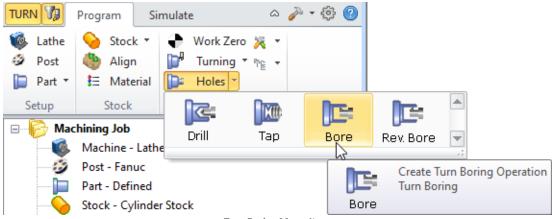


These operations are used to form shapes inside of a hole. Bore Types including Drag, No Drag and Manual are supported. Choose a selection from below for more information. **Note**: For each tab in the dialog, select a topic from the Contents on the left.



Reverse Bore Menu Selection (TURN Module)

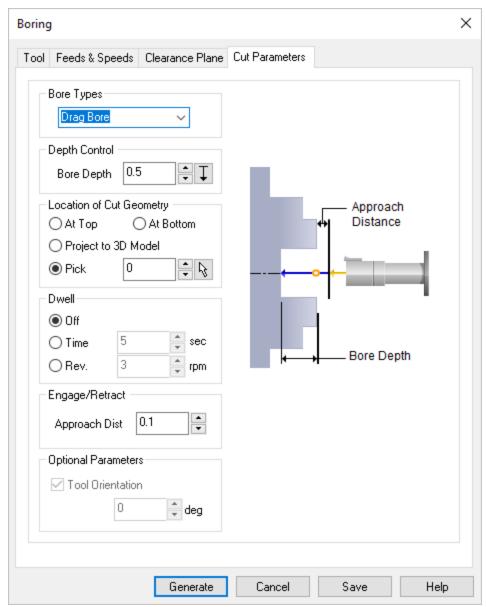
The Reverse Boring toolpath method is invoked by selecting the Program tab, clicking on the Holes button in the Machining Browser and selecting the Rev. Bore operation.



Turn Boring Menu Item

Dialog Box: Boring

The toolpath generated depends on your defined parameters. The various parameters that you can set can be seen in the dialog box that is invoked when you choose the Bore operation. This dialog box is shown below.



Dialog Box: Cut Parameters tab, Turn Boring

The following Bore Types are available

The following boring cycles are available:

Drag

The tool is fed to the specified depth at the controlled feed rate. Then the spindle is stopped and the tool retracts rapidly.

No Drag

The tool is fed to the specified depth at the controlled feed rate. It is then stopped to orient the spindle, moved away from the side of the hole and then retracted.

Manual

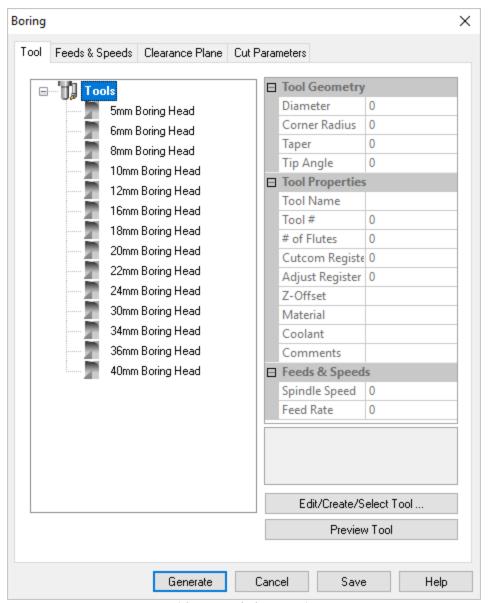
The tool traverses to the programmed point and is fed to the specified depth at the controlled feed rate. Then the tool stops and is retracted manually.

User Defined Bore1 and Bore2
 Allows for the definition of user defined bore types.

9.3.1 Tool

The following dialog allows you to select the appropriate Bore tool for the Turn Bore operation. The Tools in Session are listed on the left. Expanding the Tool tree will list the current operations assigned to that tool. The geometry parameters of the selected tool are displayed to the right. See Create Edit Tools for more information.

Dialog Box: Tool tab



Dialog Box: Tool tab, Turn Boring

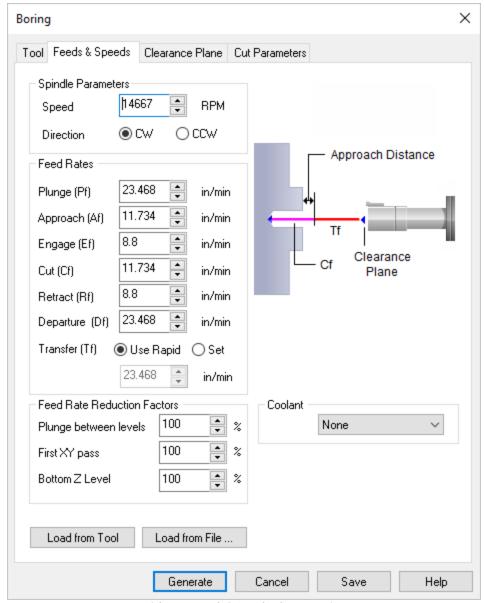
Edit/Create/Select Tool ...

If there are no Tools listed, select this button to Create a new tool. If a tool is listed and selected by default, select this button to Edit the parameters for that tool or to Select a different tool for the current operation.

9.3.2 Feeds & Speeds

The following dialog allows you to select the appropriate Feeds & Speeds for the Turn Boring operation. In this tab, Spindle Parameters and Feed Rates can be specified. Speeds & Feeds can also be loaded from a File or from the Tool.

Dialog Box: Feeds & Speeds tab



Dialog Box: Feeds & Speeds tab, Turn Boring

Spindle Parameters

Speed

This is the rotational speed of the spindle expressed in RPM.

Direction

This determines the direction of spindle rotation and can be set to CW Clockwise or CCW Counter Clockwise.

Feed Rates

Feedrate can be set in Units/Min or Units/Revolution for Turning Inserts.

Plunge (Pf)

This rate is the feed before the tool starts to engage in material. This is always vertical.

Approach (Af)

This is the feedrate used that prepares the cutter just before it starts engaging into material as it starts cutting. The approach motions are dependent on the method of machining.

Engage (Ef)

This is the feedrate used when the tool is performing an engage move. TURN Module sets this value to be 75% of the cutting speed.

Cut (Cf)

This is the feedrate used when the tool is cutting material

Retract (Rf)

The feedrate used when the tool is performing a retract move away from material. TURN Module sets this also to also be 75% of the cutting speed.

Departure (Df)

The feedrate used to retract the tool from the material.

Transfer (Tf)

Load from File ...

This is the feedrate (in Units/Min), used for Transfer motions. Select Use Rapid to set this to the Transfer Feed value defined in the Feeds & Speeds section of the CAM Preferences dialog.

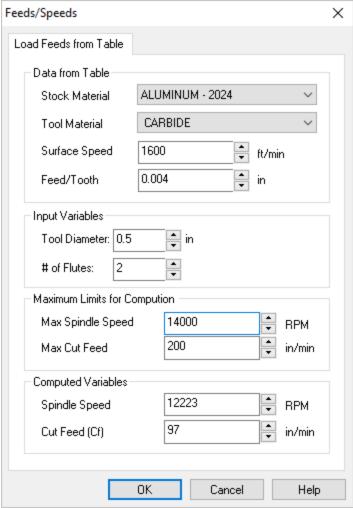
Feed Rate Reduction Factors This sets Feed Rate Reduction Factors for Plunge Between Levels and the First XY pass. Load from Tool Feeds & Speeds are defined when a tool is created using Create/Edit Tools from the Machining Objects Browser. Selecting this button loads the Feeds & Speeds from the tool that is selected for the current machining operation.

This loads the Feeds & Speeds values from the Feeds & Speeds Table file. This will display the Load Feeds from Table dialog box to make your selections.

Dialog Box: Load Feeds from Table

Selecting OK from this dialog transfers the spindle speed and cut feedrate to the Feeds & Speeds tab. The plunge, approach, engage, retract and departure

feeds are determined using a percent of the cut feed. The percent to use for transferring the computed cut feed can be set under Feeds & Speeds Preferences.



Dialog Box: Load Feeds from Table

Data from Table

Stock Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Tool Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Surface Speed

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Feed/Tooth

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Input Variables

The input variables - Work Diameter is automatically loaded from the Stock Radius. Based on this parameter and the Variables Limits parameters, the program computes Spindle Speed and Cut Feedrate (Cf). measured in Unites/Revolution. Changing the spindle speed modifies the cut feedrate.

Maximum Limits for Computation

Here you can set the Max Spindle Speed and Max Cut Feed (Cf) values. Once these two values are set, the Spindle Speed and Cut Feed calculated by this dialog will not exceed these values even if you attempt to enter higher values into the Computed Variables fields. To exceed these values, change them here or you must edit the operation or tool parameters manually.

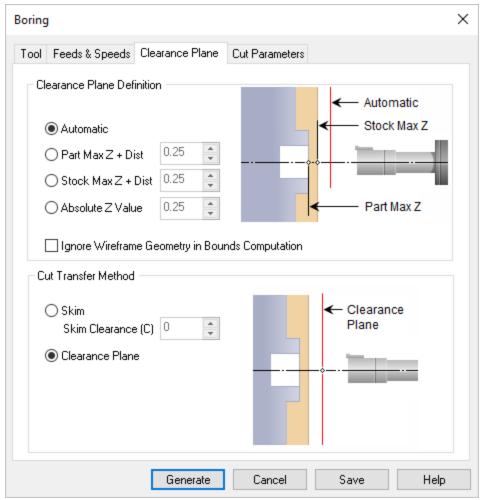
Computed Variables

The variables for Spindle Speed and Cut Feed (Cf) are computed for you based on the selections made in this dialog but will not exceed the values set in the Maximum Limits for Computation section of the dialog. These values are then assigned to the active toolpath operation or tool. You can override either of these variables and the other will update automatically. Since this dialog is a Feeds & Speeds Calculator, you cannot override both values. To do so, you must edit the operation or tool parameters manually.

9.3.3 Clearance

The following dialog allows you to select the appropriate Clearance Plane for the Turn Boring operation. In this tab, Clearance Plane Definition and Cut Transfer Method parameters can be specified. See Clearance Plane for additional information.

Dialog Box: Clearance Plane tab



Dialog Box: Clearance Plane tab, Turn Boring

Clearance Plane Definition

Automatic

The system determines the clearance height based on the part and stock geometry.

Part Max + Dist

Uses Part maximum plus the specified distance for clearance height.

Stock Max + Dist

Uses Stock maximum plus the specified distance for clearance height. If stock geometry does not exist, it would use the maximum height of the part geometry.

Absolute Value

Uses the specified distance for clearance height.

For Turning operations, the User Interface for clearance settings are automatically set for OD, ID or Face depending on the approach type specified under global parameters.

For Hole Machining operations, the clearance plane is normal to the Z axis.

Ignore Wireframe Geometry in Bounds Computation

Check this box to ignore all wireframe geometry when calculating the Clearance Plane definition. When checked, the Automatic and Part Max options for defining the Clearance will be calculated from actual surface geometry.

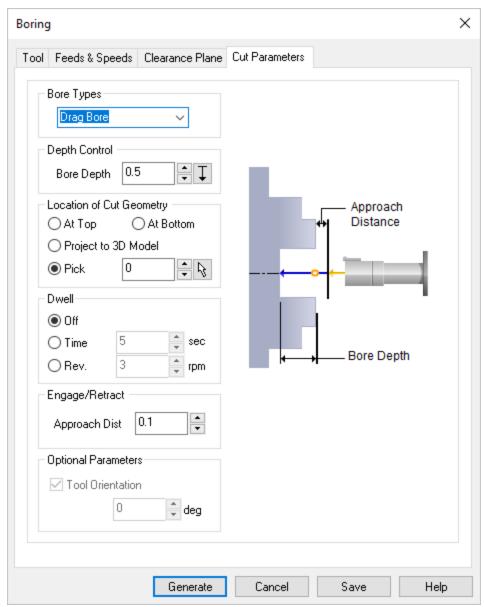
Cut Transfer Method

You can also control the transfer motions during cutting. When the cutter has finished cutting in one region and needs to transfer to another region to begin cutting, it can either be instructed to move to the clearance plane and then perform the transfer motion to the next cut location or it could do a skim motion. In the skim motion, the system automatically determines the safe height by taking into consideration the condition of the part model and using this Skim Clearance (S) value specified as the height to perform the transfer motions.

9.3.4 Cut Parameters

The following dialog allows you to set the Cut Parameters for Turn Boring operations. You can set the Bore Type, Depth Control, Location, Dwell and other parameters via this dialog box.

Dialog Box: Cut Parameters tab



Dialog Box: Cut Parameters tab, Turn Boring

Bore Types

The bore types supported are:

Drag Bore

The tool is fed to defined depth at the controlled feed rate; the spindle is stopped and then a rapid retract is performed.

No Drag Bore

The tool is fed to the specified depth at the controlled feed rate. It is then stopped to orient the spindle, moved away from the side of the hole and finally retracted. Tool Orientation is supported. See Optional Parameters listed below.

Manual Bore

The tool traverses to the programmed point; feeds to the specified depth at the controlled feed rate; and then stops motion for a manual retract.

User Defined Bore1 / User Defined Bore2

Defined using the Post-Processor Generator for your selected post definition.

Depth Control

Bore Depth - Enter the depth for the current drill operation. You can select the Pick button to pick a point on your part model that defines the drill depth.

Location of Cut Geometry

Select this option if drilling should start at your Work Zero. The Drill Depth is then subtracted to this location. An actual point is not required. The location is determined automatically by your Work Zero location.



At Top

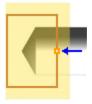
Select this option if drilling should end at your Work Zero. The Drill Depth is then added to this location. An actual point is not required. The location is determined automatically by your Work Zero location.



At Bottom

Project to 3D Model

Select this option if you want to project the start point to your 3D model. For example, if your stock is longer than your part but you want the Drill Depth to begin at the face of your part instead of the face of the stock. An actual point is not required. The location is determined automatically by your part model.



Project to 3D Model

Select this option if you want to specify the coordinates of point where the drilling should end at your Work Zero. The Drill Depth is then added to this location. An actual point is not required. The location is determined automatically by your Work Zero location. You can select the Pick button and then select a point on your part. It's coordinate will be calculated automatically.



Pick Top

U Dwell

Dwell is an optional parameter that allows a machine delay of either Time (sec) Rev (rpm) of the spindle.

Engage/Retract

You can define the Approach Distance under Engage/Retract. The tool rapids in the Z axis to the approach plane and then applies the specified feedrate from the approach plane to the specified depth to perform the cycle.

Optional Parameters

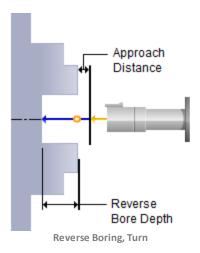
Tool Orientation - The tool is fed to the specified depth at the controlled feed rate. It is then stopped to orient the spindle, moved away from the side of the hole and finally retracted. Use this parameter to enable Tool Orientation and enter the value in degrees.

9.4 Reverse Boring



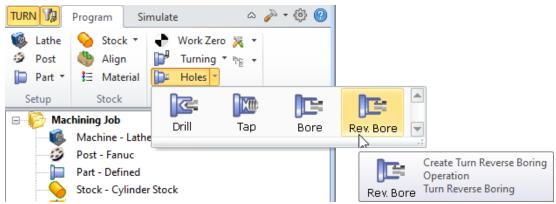
This method is used to reverse-bore a stepped hole that cannot be accessed by regular bores. The Reverse Bore parameter settings are similar to the Drill parameters. Two user defined reverse boring cycles (RBore1 and RBore2) are supported. **Note**: For each tab in the dialog, select a topic from the Contents on the

left.



Reverse Bore Menu Selection (TURN Module)

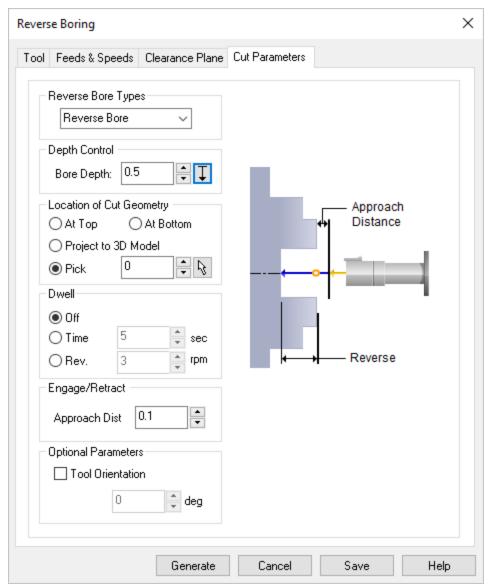
The Reverse Boring toolpath method is invoked by selecting the Program tab, clicking on the Holes button in the Machining Browser and selecting the Rev. Bore operation.



2½ Axis Hole Making, Reverse Bore Menu Item

Dialog Box: Hole Making, Reverse Bore

The toolpath generated depends on your defined parameters. The various parameters that you can set can be seen in the dialog box that is invoked when you choose the Reverse Bore operation. This dialog box is shown below.



Dialog Box: Cut Parameters tab, Turn Reverse Boring

The following Reverse Bore Types are available

The Reverse Bore Types supported are:

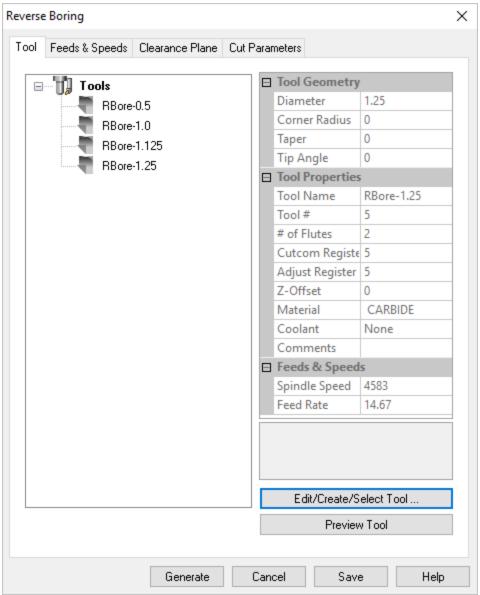
- Reverse Bore
- RBore1: User Defined Reverse Bore
- RBore2: User Defined Reverse Bore

9.4.1 Tool

The following dialog allows you to select the appropriate Bore tool for the Turn Reverse Bore operation. The Tools in Session are listed on the left. Expanding the Tool tree will list the current

operations assigned to that tool. The geometry parameters of the selected tool are displayed to the right. See Create Edit Tools for more information.

Dialog Box: Tool tab



Dialog Box: Tool tab, Turn Reverse Boring

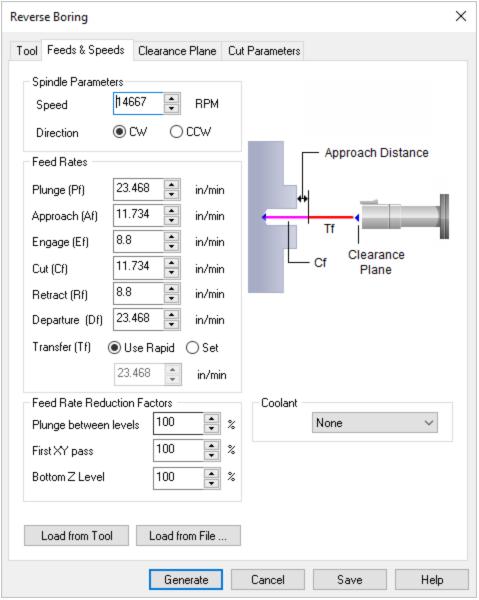
Edit/Create/Select Tool ...

If there are no Tools listed, select this button to Create a new tool. If a tool is listed and selected by default, select this button to Edit the parameters for that tool or to Select a different tool for the current operation.

9.4.2 Feeds & Speeds

The following dialog allows you to select the appropriate Feeds & Speeds for the Turn Reverse Boring operation. In this tab, Spindle Parameters and Feed Rates can be specified. Speeds & Feeds can also be loaded from a File or from the Tool.

Dialog Box: Feeds & Speeds tab



Dialog Box: Feeds & Speeds tab, Turn Reverse Boring

Spindle Parameters

Speed

This is the rotational speed of the spindle expressed in RPM.

Direction

This determines the direction of spindle rotation and can be set to CW Clockwise or CCW Counter Clockwise.

Feed Rates

Feedrate can be set in Units/Min or Units/Revolution for Turning Inserts.

Plunge (Pf)

This rate is the feed before the tool starts to engage in material. This is always vertical.

Approach (Af)

This is the feedrate used that prepares the cutter just before it starts engaging into material as it starts cutting. The approach motions are dependent on the method of machining.

Engage (Ef)

This is the feedrate used when the tool is performing an engage move. TURN Module sets this value to be 75% of the cutting speed.

Cut (Cf)

This is the feedrate used when the tool is cutting material

Retract (Rf)

The feedrate used when the tool is performing a retract move away from material. TURN Module sets this also to also be 75% of the cutting speed.

Departure (Df)

The feedrate used to retract the tool from the material.

Transfer (Tf)

This is the feedrate (in Units/Min), used for Transfer motions. Select Use Rapid to set this to the Transfer Feed value defined in the Feeds & Speeds section of the CAM Preferences dialog.

Feed Rate Reduction Factors

This sets Feed Rate Reduction Factors for Plunge Between Levels and the First XY pass.

Load from Tool

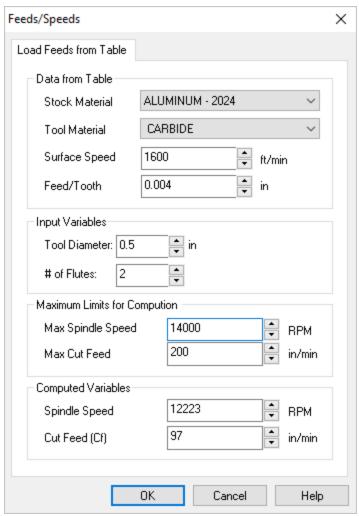
Feeds & Speeds are defined when a tool is created using Create/Edit Tools from the Machining Objects Browser. Selecting this button loads the Feeds & Speeds from the tool that is selected for the current machining operation.

Load from File ...

This loads the Feeds & Speeds values from the Feeds & Speeds Table file. This will display the Load Feeds from Table dialog box to make your selections.

Dialog Box: Load Feeds from Table

Selecting OK from this dialog transfers the spindle speed and cut feedrate to the Feeds & Speeds tab. The plunge, approach, engage, retract and departure feeds are determined using a percent of the cut feed. The percent to use for transferring the computed cut feed can be set under Feeds & Speeds Preferences.



Dialog Box: Load Feeds from Table

Data from Table

Stock Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Tool Material

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Surface Speed

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Feed/Tooth

Selecting a Stock Material and Tool Material displays the Surface Speed and Feed/Tooth. This information is contained in a feeds and speeds data file which can be edited to add newer materials.

Input Variables

The input variables - Work Diameter is automatically loaded from the Stock Radius. Based on this parameter and the Variables Limits parameters, the program computes Spindle Speed and Cut Feedrate (Cf). measured in Unites/Revolution. Changing the spindle speed modifies the cut feedrate.

Maximum Limits for Computation

Here you can set the Max Spindle Speed and Max Cut Feed (Cf) values. Once these two values are set, the Spindle Speed and Cut Feed calculated by this dialog will not exceed these values even if you attempt to enter higher values into the Computed Variables fields. To exceed these values, change them here or you must edit the operation or tool parameters manually.

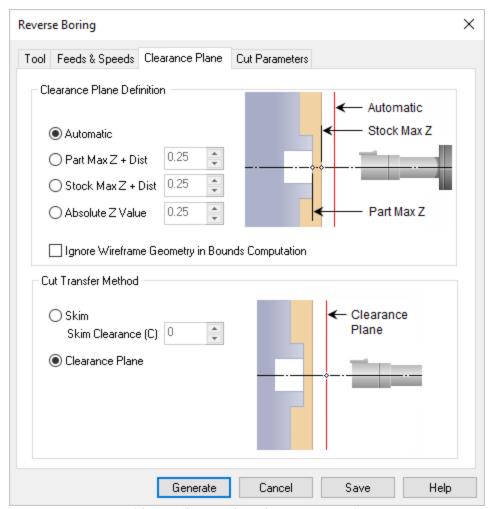
Computed Variables

The variables for Spindle Speed and Cut Feed (Cf) are computed for you based on the selections made in this dialog but will not exceed the values set in the Maximum Limits for Computation section of the dialog. These values are then assigned to the active toolpath operation or tool. You can override either of these variables and the other will update automatically. Since this dialog is a Feeds & Speeds Calculator, you cannot override both values. To do so, you must edit the operation or tool parameters manually.

9.4.3 Clearance

The following dialog allows you to select the appropriate Clearance Plane for the Turn Reverse Boring operation. In this tab, Clearance Plane Definition and Cut Transfer Method parameters can be specified. See Clearance Plane for additional information.

Dialog Box: Clearance Plane tab



Dialog Box: Clearance Plane tab, Turn Reverse Boring

Clearance Plane Definition

Automatic

The system determines the clearance height based on the part and stock geometry.

Part Max + Dist

Uses Part maximum plus the specified distance for clearance height.

Stock Max + Dist

Uses Stock maximum plus the specified distance for clearance height. If stock

geometry does not exist, it would use the maximum height of the part geometry.

Absolute Value

Uses the specified distance for clearance height.

For Turning operations, the User Interface for clearance settings are automatically set for OD, ID or Face depending on the approach type specified under global parameters.

For Hole Machining operations, the clearance plane is normal to the Z axis.

Ignore Wireframe Geometry in Bounds Computation

Check this box to ignore all wireframe geometry when calculating the Clearance Plane definition. When checked, the Automatic and Part Max options for defining the Clearance will be calculated from actual surface geometry.

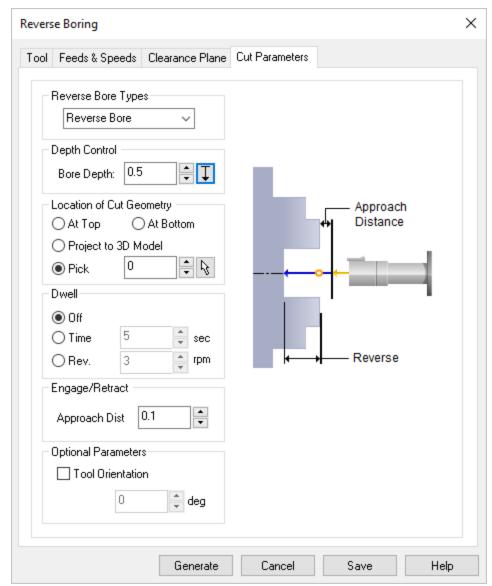
Cut Transfer Method

You can also control the transfer motions during cutting. When the cutter has finished cutting in one region and needs to transfer to another region to begin cutting, it can either be instructed to move to the clearance plane and then perform the transfer motion to the next cut location or it could do a skim motion. In the skim motion, the system automatically determines the safe height by taking into consideration the condition of the part model and using this Skim Clearance (S) value specified as the height to perform the transfer motions.

9.4.4 Cut Parameters

The following dialog allows you to set the Cut Parameters for Turn Reverse Boring operations. You can set the Bore Type, Depth Control, Location, Dwell and other parameters via this dialog box.

Dialog Box: Cut Parameters tab



Dialog Box: Cut Parameters tab, Turn Reverse Boring

Bore Types

The reverse bore types supported are:

Reverse Bore

The tool is fed to defined depth at the controlled feed rate; the spindle is stopped and then a rapid retract is performed. It is then stopped to orient the spindle, moved away from the side of the hole and finally retracted.

User Defined Bore1 / User Defined Bore2

Defined using the Post-Processor Generator for your selected post definition.

Depth Control



RBore Depth - Enter the depth for the current drill operation. You can select the Pick button to pick a point on your part model that defines the drill depth.



Location of Cut Geometry

Select this option if drilling should start at your Work Zero. The Drill Depth is then subtracted to this location. An actual point is not required. The location is determined automatically by your Work Zero location.



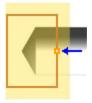
Select this option if drilling should end at your Work Zero. The Drill Depth is then added to this location. An actual point is not required. The location is determined automatically by your Work Zero location.



At Bottom

Project to 3D Model

Select this option if you want to project the start point to your 3D model. For example, if your stock is longer than your part but you want the Drill Depth to begin at the face of your part instead of the face of the stock. An actual point is not required. The location is determined automatically by your part model.



Proiect to 3D Model

Select this option if you want to specify the coordinates of point where the drilling should end at your Work Zero. The Drill Depth is then added to this location. An actual point is not required. The location is determined automatically by your Work Zero location. You can select the Pick button and then select a point on your part. It's coordinate will be calculated automatically.



Pick Top

Dwell

Dwell is an optional parameter that allows a machine delay of either Time (sec) Rev (rpm) of the spindle.

Engage/Retract

You can define the Approach Distance under Engage/Retract. The tool rapids in the Z axis to the approach plane and then applies the specified feedrate from the approach plane to the specified depth to perform the cycle.

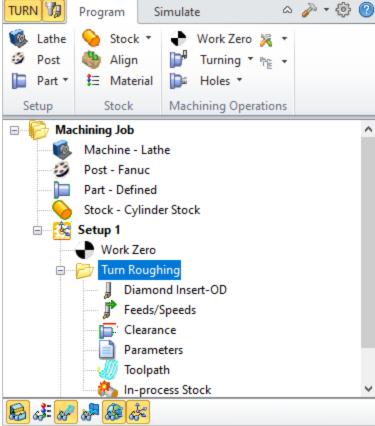
Optional Parameters

Using the Reverse Bore types (see above), the tool is fed to the specified depth at the controlled feed rate. It is then stopped to orient the spindle, moved away from the side of the hole and finally retracted. Use this parameter to enable Tool Orientation and enter the value in degrees.

Editing Machining Operations

Once a Machining operation is created it is listed under the Machining Browser. By default all the operations are created under Setup 1. A Setup can hold several machining operations. The operations can be edited in a couple of ways. Changes can be made to any of the objects that make up the operation such as the Tool, Feeds/Speeds, Clearance Geometry and Machining Parameters. This type of editing is called associative editing. This is because the edits made to the operation are saved with the operation and upon regeneration the changes would be effected.

Machining Browser

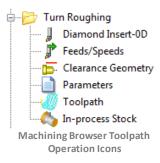


Machining Browser

10.1 Editing Operations Associatively

Machining Operations can be edited by using the Machining Browser. Each machining operation is represented as a folder in the browser. In the expanded state of this folder icon, five icons representing five different objects that make up the operation are displayed. These are:

Machining Browser, Turn Operation Tree



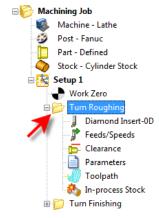
- Feeds/Speeds
- Clearance Geometry
- Parameters
- Toolpath
- In-process Stock

Double-click Editing an Operation Folder

Double clicking on Tool, Feeds/Speeds, Clearance Geometry or Parameters icons gives you an opportunity to edit the object.

- Tool
- Feeds/Speeds
- Clearance Geometry
- Parameters

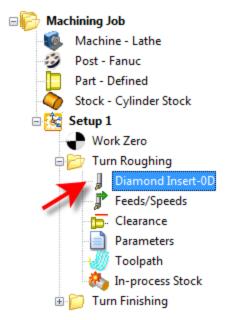
For the selected operation.



Double-click Editing an Operation from the Machining
Browser

Right-Mouse click or Double-click on an Operation Icon

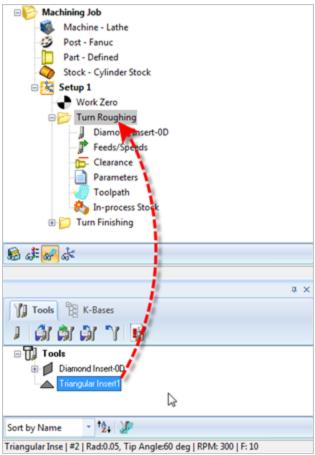
Right mouse click or double clicking a specific icon for example the Tool icon would bring up the Create/Edit Tool dialog, upon which you can substitute the current tool with another or edit the parameters of the current tool.



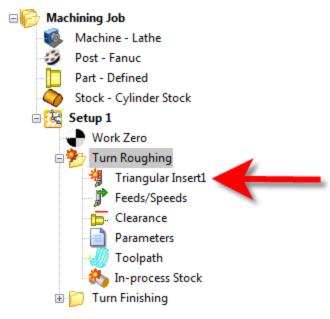
Right-Mouse click or Double-click on an Operation Icon from the Machining Browser

Drag & Drop New Tools into an Operation

The tool can also be edited by dragging and dropping it from the Tools tab to of the Machining Objects Browser to the operation folder in the Machining Browser.



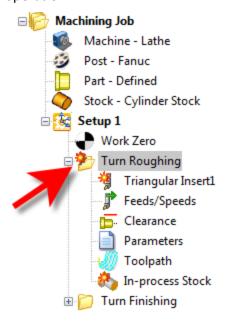
Drag & Drop Editing an Operation from the Machining Browser



Drag & Drop Editing an Operation from the Machining Browser

Indicator that an Operation needs to be Regenerated

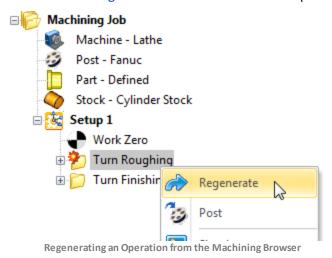
If any of the objects that make up the operation were to be edited after the toolpath was generated, the operation will be flagged dirty as needing re-computation. TURN Module indicates such a condition by adding a red flag to the operation folder (i.e.,). The object that necessitated this re-computation is also displayed with a red flag (i.e.,). An example of this is shown below. In this case the tool used in the operation was edited after the machining operation was created and so is shown differently, as is the operation.



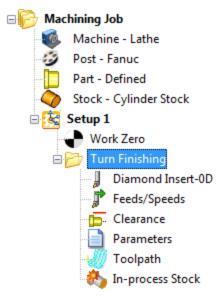
Indicator that an Operation Needs to be Regenerated

Regenerating an Operation from the Machining Browser

To regenerate an operation that is flagged dirty, first select the operation folder, right click and select Regenerate as shown in the example below.



The toolpath is now regenerated with the modified settings.

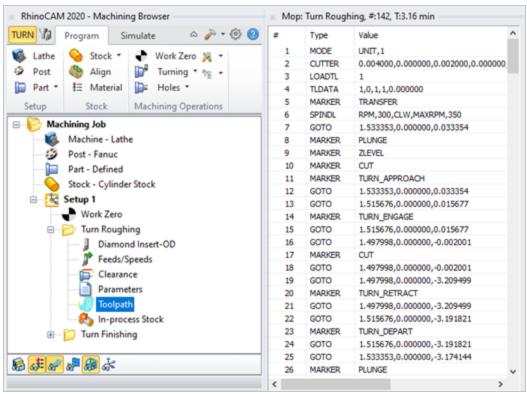


The toolpath is now regenerated with the modified settings

10.2 Toolpath Viewer

Once a machining operation is created, you can step through the toolpath motions using the Toolpath Viewer. To display the viewer, double-click on the toolpath icon of the operation in the Machining Browser. The Toolpath Viewer is a dockable dialog bar that will be initially docked next to the Machining Browser.

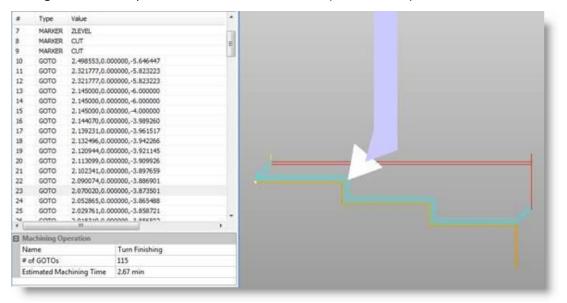
The Toolpath Viewer Displayed



The Toolpath Viewer Displayed

Viewing Toolpath Motions

Select a GOTO motion in the toolpath viewer to view the tool motion for the generated toolpath. Make sure to turn on Toolpath Visibility.

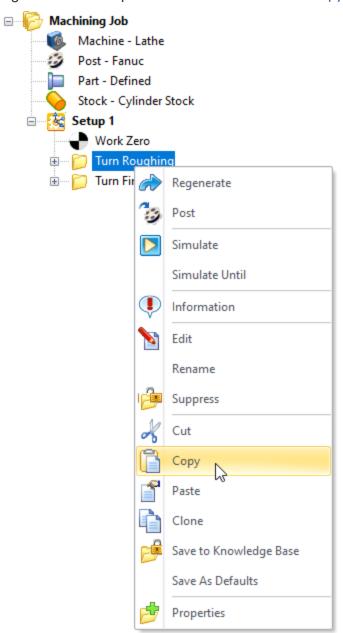


10.3 Copy & Paste Operations

You can copy and paste machining operations in TURN Module.

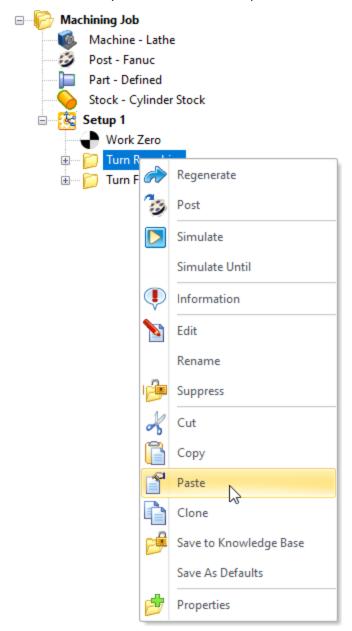
Copy & Paste an Operation from the Machining Browser

1. Right-click on the operation folder and select Copy.



Right-click on the operation folder and select Copy.

2. Right-click on the operation folder again and select Paste. The new operation is located directly below the selected operation.

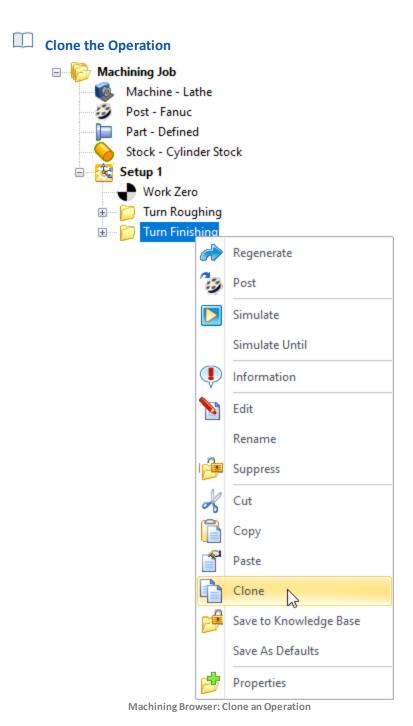


 $\label{eq:Right-click} \textbf{Right-click} \, \textbf{on} \, \textbf{the operation folder} \, \textbf{again and select Paste}$

3. This creates a copy of the operation. You can then edit the operation and regenerate toolpath.

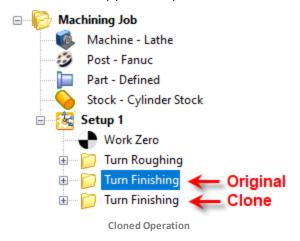
10.4 Clone Operation

You can Clone machining operations in Machining Browser. To Clone an operation, select the operation under the Machining Browser, right-click and select Clone. This performs a Copy/Paste on the selected operation.



Edit or Regenerate the Operation

This creates a copy of the operation located under the currently selected operation.



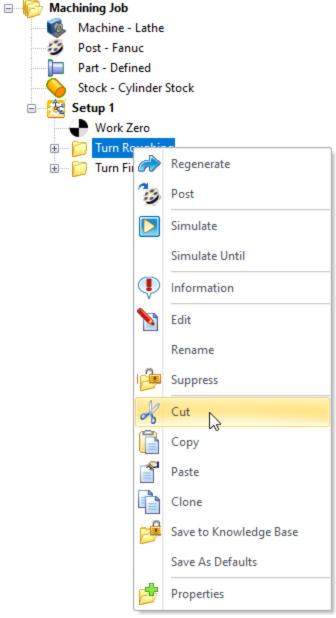
You can then edit the operation and regenerate toolpath.

10.5 Delete Operations

To Delete a machining operation, select the operation from the Machining Browser, right-click and select Cut.

Cut an Operation from the Machining Browser

1. Right-click on the operation folder and select Cut.



Cut an Operation from the Machining Browser

2. The operation is removed and added to the clipboard. If desired, you can right-click and Paste the operation back into the Machining Browser.

Alternate Methods to Delete an Operation

Alternatively you can delete a machining operation by:

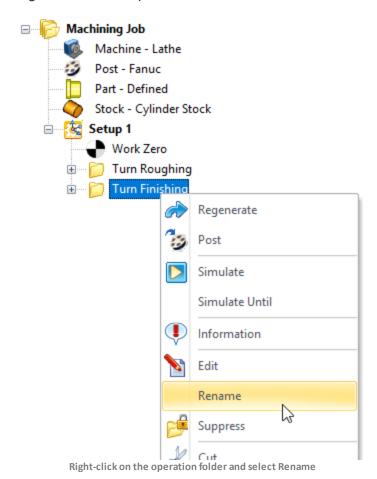
- 1. Selecting the operation and using the Delete key on your keyboard.
- 2. Selecting the operation and dragging the operation out of the mops browser to the viewport area.

10.6 Rename Operations

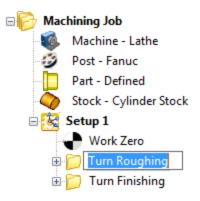
To Rename a machining operation, select the operation from the Machining Browser, right-click and select Rename.

Rename an Operation from the Machining Browser

1. Right-click on the operation folder and select Rename.



2. Enter a new name for the operation.



Enter a new name for the operation

Conventions for Renaming Operations

Do not use any of these common illegal characters/symbols in your Mop Names:

DO NOT USE these Characters when renaming Mops			
#	pound	?	question mark
%	percent	/	forward slash
&	ampersand	\$	dollar sign
{	left bracket	!	exclamation point
}	right bracket	ı	single quotes
\	back slash	11	double quotes
<	left angle bracket	:	colon
>	right angle bracket	@	at sign
*	asterisk		

Also, keep these rules in mind:

- Do not start or end your Mop Names with a space or period
- Keep your file names to a reasonable length and be sure they are under 31 characters.

Alternate Methods to Rename an Operation

Alternatively you can double-left-click on the operation name in the Machining Browser and then enter a new name.

10.7 Suppress Operations

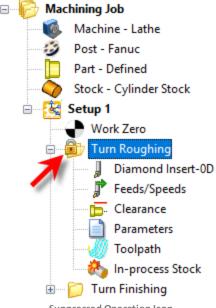
You can Suppress a machining operation or a Setup in the Machining Browser by selecting it, right click and select Suppress from the context menu. Suppressed operations will not be displayed, posted or simulated. You can also right-click and Unsuppress an operation. **Note:** You can customize how suppressed operations are managed using the <u>Machining Preferences</u> dialog.

To Suppress an Operation Machining Job Machine - Lathe Post - Fanuc Part - Defined Stock - Cylinder Stock Setup 1 Work Zero Turn Roughina] Turn Finis 🌈 Regenerate Post Simulate Simulate Until Information Edit Rename Cut

To Suppress an Operation

The Suppressed Operation Icon

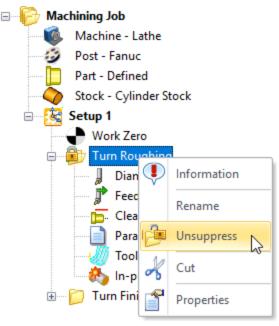
A Suppress operation will display in the Machining Job with the following icon:



Suppressed Operation Icon

To Unsuppress an Operation

To Unsuppress an operation, right-click on it and select Unsuppress.



To Unsuppress an Operation

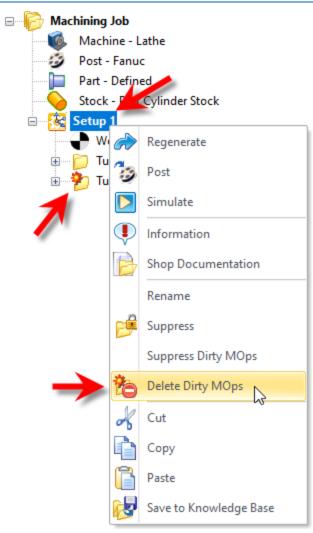
10.8 **Delete Dirty Mops**

You can Delete all machining operations in a Setup that are flagged as dirty 🤔 . This command can also be executed from right-clicking on the Machining Job to delete ALL dirty Mops in all

Setups. Warning This a permanent operation and cannot be undone. Select the Setup, right click and select Delete Dirty Mops from the context menu.

Delete All Dirty Mops (BEFORE)

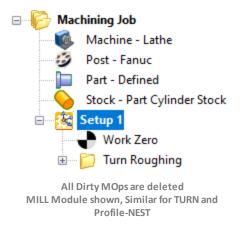
Warning! This operation is permanent and cannot be undone!



To Delete Dirty MOps

Delete All Dirty Mops (AFTER)

A Suppress operation will display in the Machining Job with the following icon:

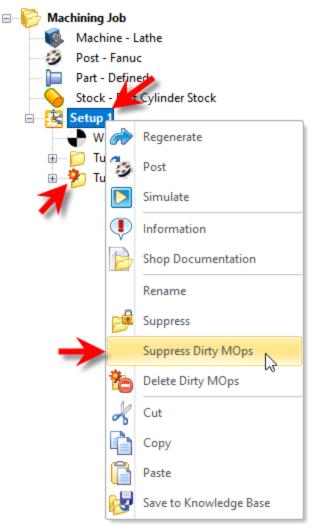


10.9 Suppress Dirty Mops

You can Suppress all machining operations in a Setup that are flagged as dirty . Select the Setup, right click and select Suppress Dirty Mops from the context menu. This command can also be executed from right-clicking on the Machining Job to suppress ALL dirty Mops in all Setups.

Note: You can customize how suppressed operations are managed using the Machining Preferences dialog.

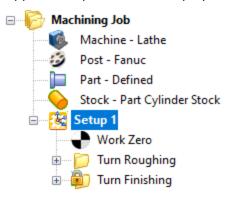
Suppress All Dirty Mops (BEFORE)



To Suppress all Dirty MOps

Suppress All Dirty Mops (AFTER)

Suppressed operation will display in the Machining Job with the following icon:

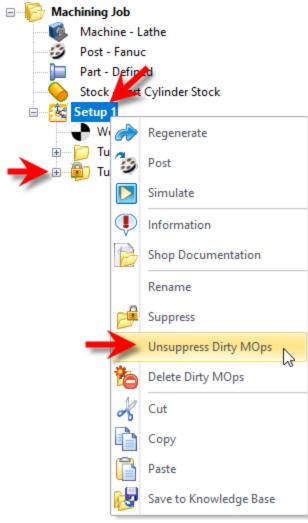


All Dirty MOps are suppressed

10.10 Unsuppress Dirty Mops

You can Unsuppress all machining operations in a Setup that are flagged as dirty . Select the Setup, right click and select Unsuppress Dirty Mops from the context menu. This command can also be executed from right-clicking on the Machining Job to unsuppress ALL dirty Mops in all Setups. **Note:** You can customize how suppressed operations are managed using the Machining Preferences dialog.

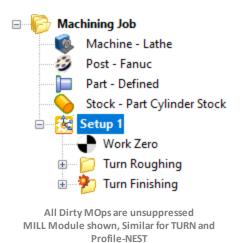
Unsuppress All Dirty Mops (BEFORE)



To Unsuppress all Dirty MOps
MILL Module shown, Similar for TURN and Profile-NEST

Unsuppress All Dirty Mops (AFTER)

Suppressed operation will display in the Machining Job with the following icon:



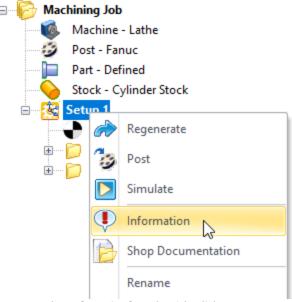
10.11 Machining Information

This displays a dialog box with the following information about the selected Operation, the Setup or the entire Machining Job:

- Operation Name
- Status
- Tool Name & Tool Number
- Cut Feed Rate
- Spindle Speed
- # of GOTOs
- Machine Time

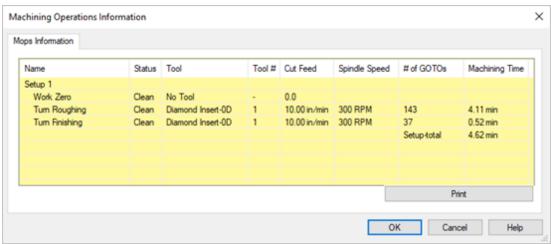
Select Information from the Right-click Menu

Machining Operations Information can be viewed by selecting a Setup, right mouse button click and left click on Information.



Select Information from the Right-click Menu

Dialog Box: Machining Operations Information (TURN Module)



Dialog Box: Machining Operations Information

10.12 Shop Documentation

Shop documentation can be generated for any Setup listed under the Machining Job in the Machining Browser. Right-click on Setup and select Shop Documentation. This will create a setup sheet for the programmed part which includes the following information. It can be printed and handed over to the operator in preparation for the part to be machined on the CNC.

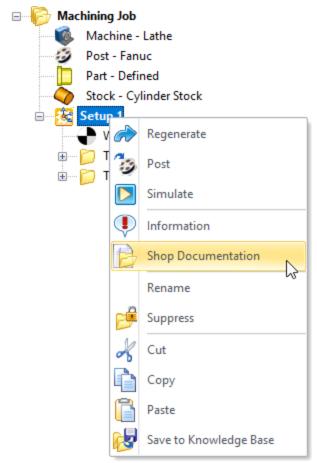
Information in the Shop Documentation Setup Sheet

Screen capture of the part from the active viewport

- Total Machining time
- Tool list
- Machining Operations List

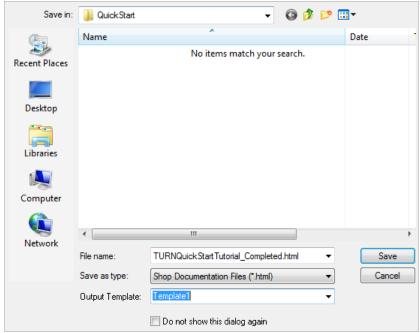
Displaying Shop Documentation for a Setup

1. Right-click on the Setup and select Shop Documentation to display the setup sheet.



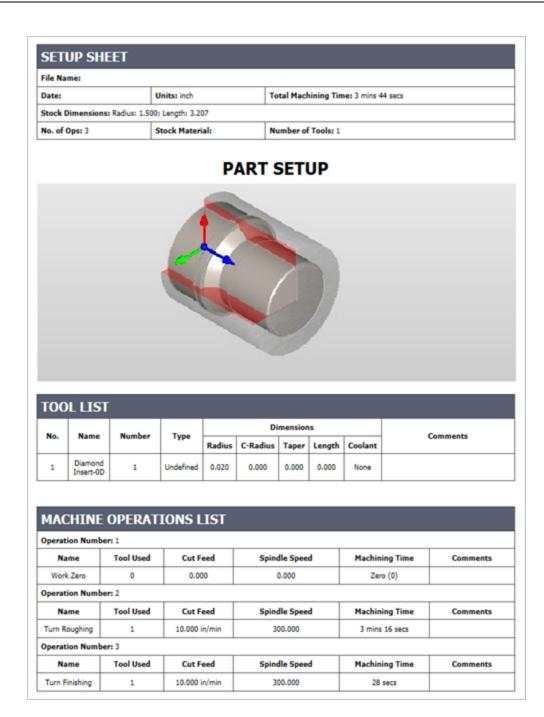
Displaying Shop Documentation for a Setup

2. In the Save Shop Documentation File dialog box, select an Output Template and then pick Save. By default, the HTML file is saved to the folder where the current file is located.



Dialog Box: Save Shop Documentation File

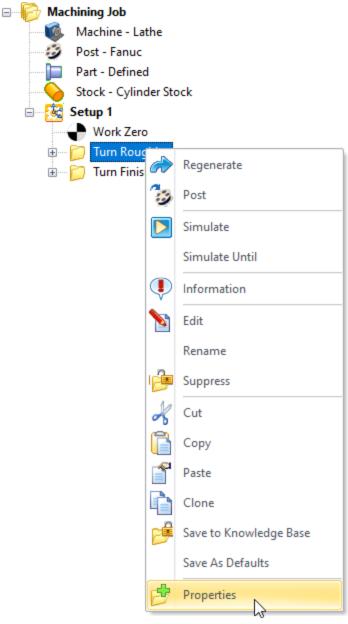
- 3. The Setup Sheet is displayed in your default Internet Browser.
- **Example: Shop Documentation Setup Sheet**



10.13 Machining Operation Properties

You can set the properties of a Operation by selecting it in the Machining Browser window, clicking on the right mouse button and selecting the Properties menu item.

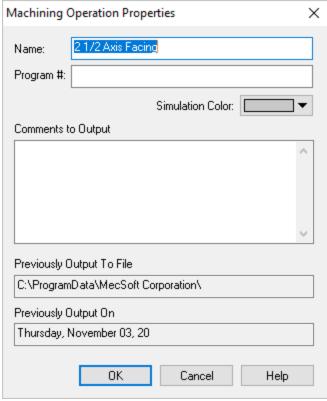
Select Properties from the Right-click Menu



To set Machining Operation Properties
Note: MILL Module shown, Similar for MILL-TURN, TURN and Profile-NEST

Dialog Box: Machining Operation Properties

This will bring up the dialog that is shown below.



Dialog Box: Machining Operation Properties

Name

Change the Name of the Machining Operation.

Program

Specify Program # for the operation. This program number will be output during post processing of the operation.

Simulation Color

This allows you to specify a unique color for this operation during Simulation display. Refer to the Simulate tab Status Bar for setting the simulation to display by Mop (i.e., machining operation type).

Comments to Output

You can also include commands that will be saved with the operation. These comments will also be output during post-processing of the operation. This might be a good place to put in comments or instructions for the machine tool operator.



This can be used to put in add comments or instructions for the machine tool operator!

Previously Output To File

This refers to the name of the external post-processed file that this particular operation was output to.

Previously Output On

This refers to the last time the operation was post-processed and the time the post-processing was performed.

Simulating Machining Operations

TURN Module offers powerful cut material simulation functionality to allow users to simulate actual machining of the generated toolpaths. The output of this simulation is a true 3D cut model. This 3D model can be rotated, zoomed and manipulated.

The 3D cut model can be visually compared with the part model to show areas of uncut material (i.e., undercut) and/or areas of over-cut material (i.e., gouging) using this component. The simulation features allow the early detection and correction of programming errors. The following section describes the material removal simulation functionality available in TURN module.

In the TURN module, rotate the view using the right-mouse button to a suitable orientation that is convenient for viewing the simulation.

Types of Simulations Available

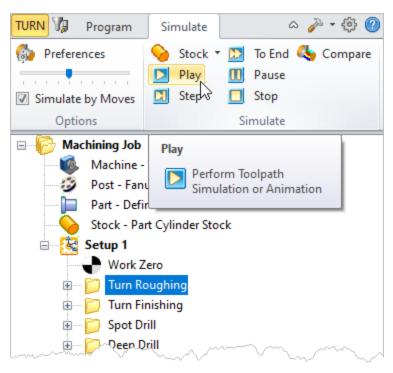
There are three kinds of toolpath simulation available in TURN module. These are:

- Tool Animation
- Cut Material Simulation
- Machine Tool Simulation

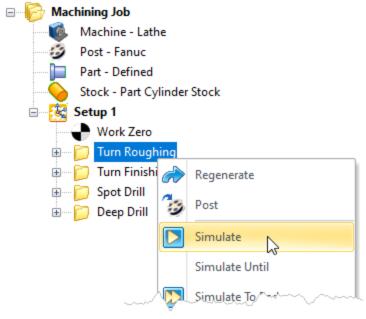
To Simulate an Operation

The simulation can be performed either on the currently active machining operation or on multiple operations. The active operation is the one that is selected and shown highlighted in the Machining Browser. Typically, this would be the last toolpath that was generated.

- 1. To simulate any operation, select it from the Machining Browser.
- 2. Select the Simulate tab.
- 3. Select the Play button or right-click on the operation and pick Simulate.



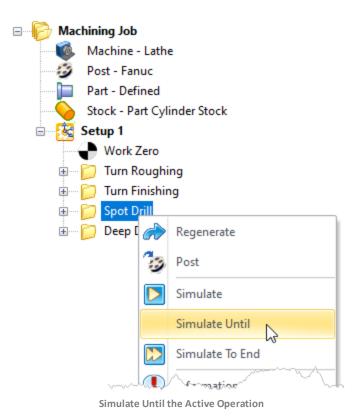
Select an operation and then pick Play from the Simulate tab



Select an operation, right-click and pick Simulate

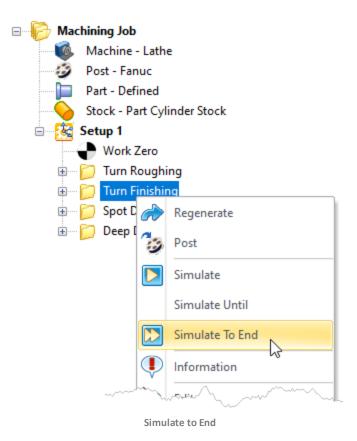
Simulate Until

To perform simulations on multiple operations select the last operation, right click and choose Simulate Until. You can also select multiple operations by holding down the Ctrl key.



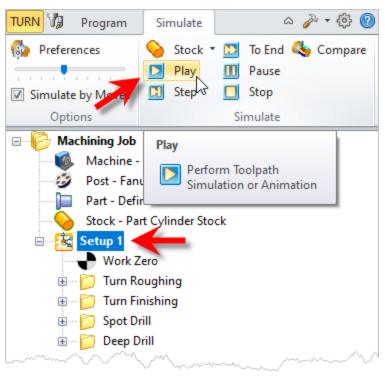
Simulate to End

To simulate directly to the end of the Machining Job, right click on any operation and select Simulate to End.

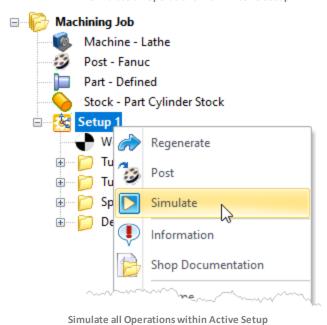


Simulate all Operations within Active Setup

Alternatively you can select a Setup and select Simulate to simulate all the operations within a Setup.



Simulate all Operations within Active Setup



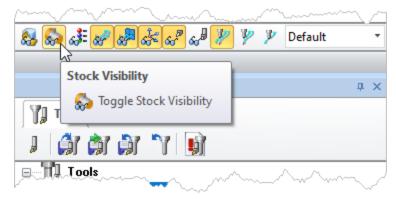
11.1 Tool Animation

Simple tool animation can be carried out in TURN module by using the controls on the Simulate tab.

To Simulate Tool Motions by Move

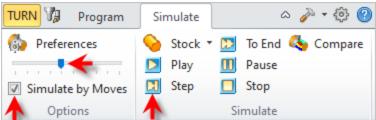
If there is no stock loaded or if the stock is loaded and the Stock Visibility is turned OFF then the tool can be animated to follow the toolpath by setting the step increment to the desired value and clicking on the Simulate button on the Simulate tab of the browser or by selecting an operation and choosing right click to simulate.

- 1. Select the Turn Operation from the Machining Browser.
- 2. If there is stock, turn Stock Visibility OFF.

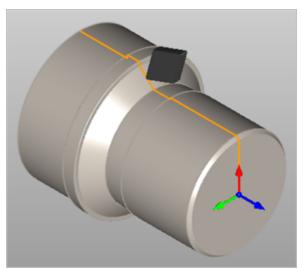


If there is stock, turn Stock Visibility OFF

- 3. Select the Simulate tab.
- 4. Check the box next to Simulate by Moves.
- 5. Adjust the Slider to the far left (i.e., 1 move at a time).
- 6. Pick the Step button to see one tool motion.
- 7. Continue to pick the Step button to "step-through" all tool motions.



Simulate Tool Motions by Move

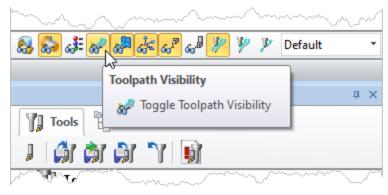


Simulate Tool Motions by Move

To Simulate Tool Motions & Toolpaths by Move

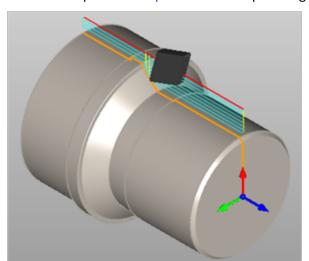
You can also choose to display the toolpath as the tool is being animated. This is a powerful function that allows you to actually watch the toolpath being displayed on the screen incrementally. To do this make sure Toolpath Visibility is turned ON before starting the tool animation along the toolpath.

- 1. Select the Turn Operation from the Machining Browser.
- 2. If there is stock, turn Stock Visibility OFF.
- 3. Turn Toolpath Visibility ON.



Turn Toolpath Visibility ON

- 1. Select the Simulate tab.
- 2. Check the box next to Simulate by Moves.
- 3. Adjust the Slider to the far left (i.e., 1 move at a time).
- 4. Pick the Step button to see one tool motion.



5. Continue to pick the Step button to "step-through" all tool motions.

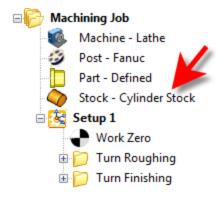
11.2 Cut Material Simulation

TURN Module offers very powerful cut material simulation functionality to allow users to simulate actual machining of the generated toolpaths. To perform cutting simulation, a stock model must be loaded and displayed and a machining operation must be active.

To Simulate Cut Material by Moves

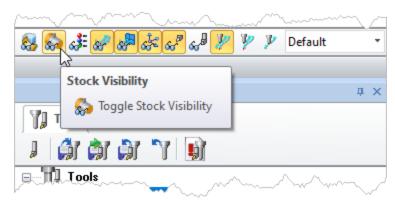
There must be Stock defined and the Stock Visibility turned ON.

1. Make sure Stock is defined for your Machining Job.



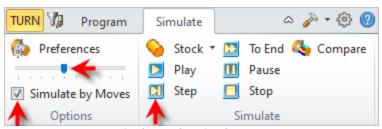
Stock is defined for your Machining Job

- 2. Select the Turn Operation from the Machining Browser.
- 3. Turn Stock Visibility ON.

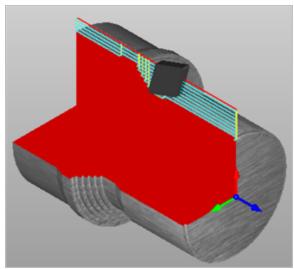


Turn Stock Visibility ON

- 4. Select the Simulate tab.
- 5. Check the box next to Simulate by Moves.
- 6. Adjust the Slider to the far left (i.e., 1 move at a time).
- 7. Pick the Step button to see one tool motion.
- 8. Continue to pick the Step button to "step-through" all tool motions.



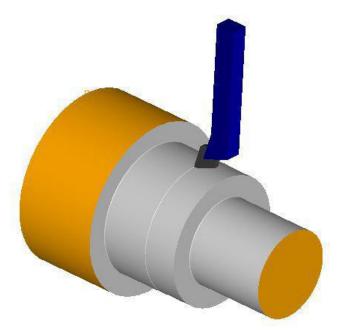
Simulate Tool Motions by Move



Simulating Cut Material Removal

The Simulation is a True 3D Cut Model

The output of the Cut Material Simulation is a true 3D cut model. This 3D model can be rotated, zoomed and manipulated. The cut model can be visually compared with the part model to show areas of uncut material and/or areas of over-cut material using this component. An example of cut material simulation is shown below.



The Simulation is a True 3D Cut Model

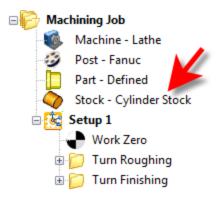
11.3 Material Texture in Simulation

Material texture can be applied to the Cut Material Simulation. This functionality allows users to simulate actual machining of the generated toolpaths with material texture.



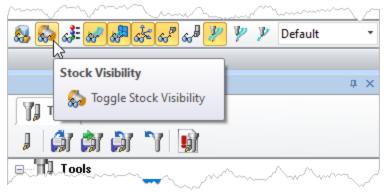
There must be Stock defined and the Stock Visibility turned ON.

1. Make sure Stock is defined for your Machining Job.



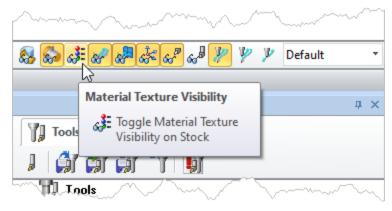
Stock is defined for your Machining Job

- 2. From the Program tab, select Define Stock Material and select a material from the Stock Material dialog box.
- 3. Select the Turn Operation from the Machining Browser.
- 4. Turn Stock Visibility ON.



Turn Stock Visibility ON

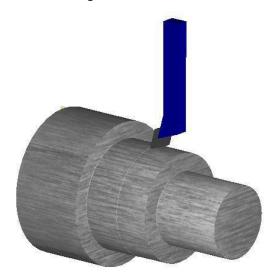
5. Turn Material Texture Visibility ON.



Turn Material Texture Visibility ON

6. Select the Simulate tab.

- 7. Check the box next to Simulate by Moves.
- 8. Adjust the Slider to the far left (i.e., 1 move at a time).
- 9. Pick the Step button to see one tool motion.
- 10. Continue to pick the Step button to "step-through" all tool motions. An example of Cut Material Simulation with Material Texture is shown below. The material is set to Aluminum-6061 under Choose Stock Material of the Stock Material dialog box.



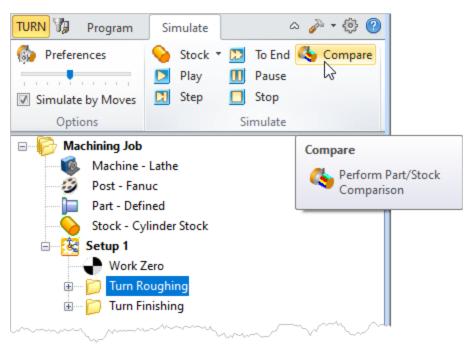
11.4 Part/Stock Compare



This command graphically compares the differences between the part and the stock geometry and displays the results graphically. The part geometry must contain solid/surface/mesh geometry. You can use the Part/Stock Comparison dialog that displays to adjust the tolerance band and continue the comparison.

To Run the Comparison Simulation

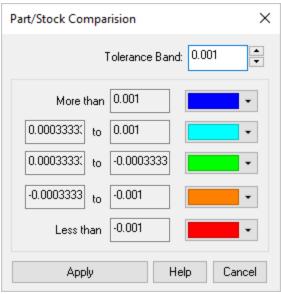
Run the simulation from the Simulate tab and select Perform Part/Stock Comparison.



Location of the Perform Part/Stock Comparison Icon

Dialog Box: Part/Stock Comparison

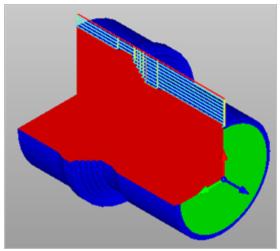
The following dialog is displayed and you can specify the tolerance for part/stock comparison. You can manipulate the part in the graphics window (i.e., pan, zoom, rotate) while this dialog is displayed.



Part/Stock Comparison dialog box

A Visual Stock/Part Model Comparison is Displayed

A visual comparison of the stock model against the part model is displayed. You can color-code areas based on the amount of material remaining or overcut.



Part/Stock Comparison Model TURN Module)

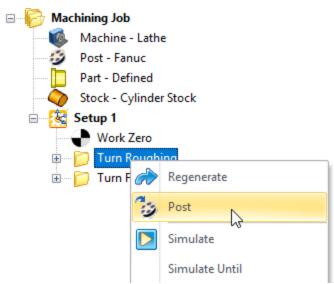
Post Processing Machining Operations

Once machining operations are created they can be post processed to a specific machine controller. To post process a machining operation, select the operation in the Machining Browser, right click and select Post.

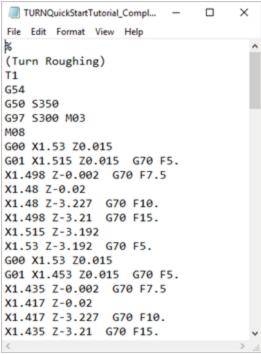
To Post Process from the Machining Browser

There must be a Post defined for the Machining Job.

- 1. If no Post is defined, pick Post and then select a post processor from the Set Post Processor Options dialog box.
- 2. Select the Turn Operation from the Machining Browser.
- 3. Right-click and select Post.



- To Post Process a Turn Operation from the Machining Browser
- 4. Enter a file name for the posted file and pick Post from the Post & Save As dialog box.
- 5. The posted file is displayed in Notepad.



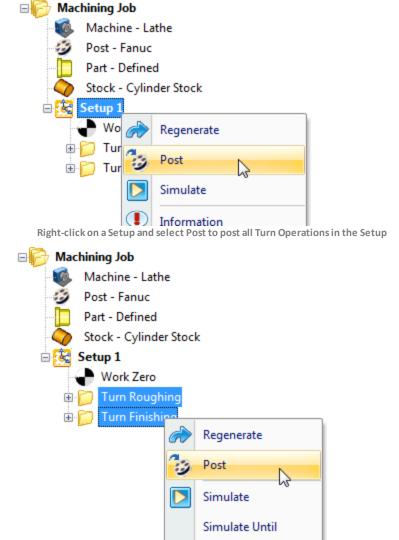
The posted file is displayed in Notepad

To Post Process Multiple Operations

You have the ability to select multiple Turn Operations or the entire set of machining operations and post process all of them with a single button click. To do this:

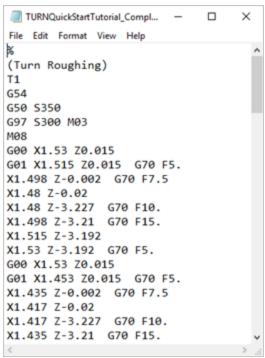
There must be a Post defined for the Machining Job.

- 1. If no Post is defined, pick Post and then select a post processor from the Set Post Processor Options dialog box.
- 2. Select the Setup from the Machining Browser. You can also select multiple operations by holding down the <Ctrl> key.
- 3. Right-click and select Post.



Example shows selecting multiple operations by holding down the <Ctrl> key for posting.

- 7. Enter a file name for the posted file and pick Post from the Post & Save As dialog box.
- 8. The posted file is displayed in Notepad.



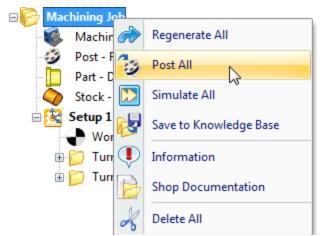
The posted file is displayed in Notepad

To Post Process All Operations

Alternatively you can select the Machining Job at the root level under the Machining Browser, right click and select Post All.

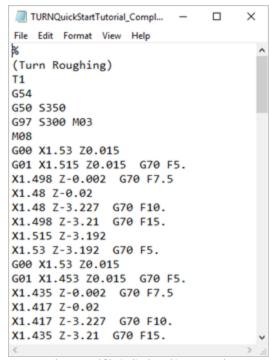
There must be a Post defined for the Machining Job.

- 1. If no Post is defined, pick Post and then select a post processor from the Set Post Processor Options dialog box.
- 2. Select the Machining Job from the Machining Browser.
- 3. Right-click and select Post.



Select the Machining Job from the Machining Browser, right-click and pick Poast All

- 7. Enter a file name for the posted file and pick Post from the Post & Save As dialog box.
- 8. The posted file is displayed in Notepad.



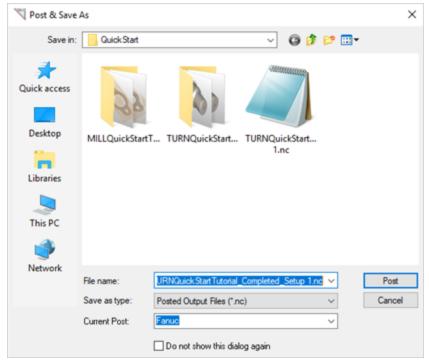
The posted file is displayed in Notepad

About the Post & Save As dialog box

Post-processing can be done from Program and Simulate tabs under the Machining Browser. Selecting Post will display the Post and Save As Dialog. The following are the default settings when the Post and Save As dialog box is displayed:

- Post and Save As dialog points to the folder location where the part geometry is located.
- Save as type refers to post file extension. This information is obtained from the set post options dialog.
- Current Post refers to the controller/post processor to post process the toolpath. This information is also obtained from the set post options dialog.

You can override the default settings under the Post & Save As dialog box. Once you click on the Post button in the dialog, post processing will begin and the posted file is located under the specified folder and then displayed in Notepad by default.



Enter a file name for the posted file and pick Post from the Post & Save As dialog box

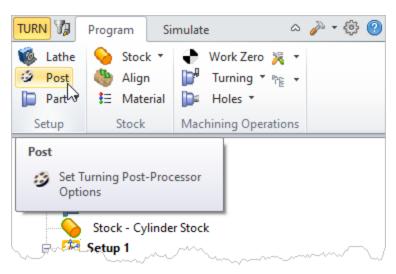
12.1 **Set Post Options**

post You can specify certain post-processor options and rules for post processing. This is done by selecting "Set Post Options" from the Program tab under the Machining

Browser.

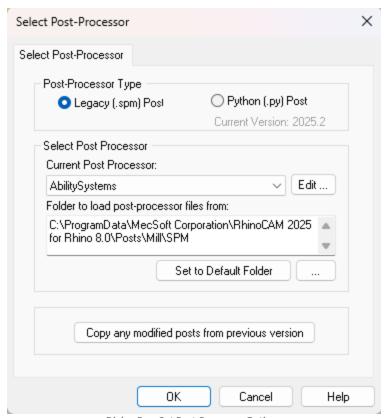
This will bring up the following dialog.

Dialog Box: Set Post-Processor Options



Set Post-Processor Options

See Use Programmable Post to learn more about using the Programmable Post option.



Dialog Box: Set Post-Processor Options

Post Processor Type

Use these options to define the post type to use when posting toolpath operations.

Use Legacy Post

Select this option to use your "Legacy Post" when posting toolpath operations. "Legacy Post" refers to your post definition (*.spm) file you used prior to version 2021.

Use Programmable Post

Select this option to use your "Programmable Post" when posting toolpath operations. "Programmable Post" refers to your programmable post created with our version 2021 and newer CAM plugins. See Use Programmable Post for documentation.

Current Post Processor

User can change the default post processor by selecting a post from the list of available post processors under Current Post Processor.

Folder where post-processor files are located

MILL module uses macro files with a .spm extension to handle post-processing to different controllers. These files are typically located in the "Posts" directory under the RhinoCAM installation folder($C:\ProgramData\MecSoft\ Corporation\RhinoCAM\ 20xx\ for\ Rhino\ x.x\Posts\Mill$).

MILL module by default looks in this directory to build the list of available postprocessors shown under the Current Post. User can change the post processor by selecting a post from the list of available post processors under Current Post.

To change the post processor file location, you can specify the folder to find the Post-Processor macro files by selecting the "Browser for Folder" button in the dialog.

12.1.1 Welcome

PPG Module

RhinoCAM

The control of

2025

Transformational CAM inside Rhino

Prefer Printed Documentation? Check Here!

The RhinoCAM Post-Processor Generator is used to edit post processor files (SPM Files). These files are used by RhinoCAM during toolpath post-processing. RhinoCAM reads in a user specified SPM file, each file corresponding to a single machine tool controller, and generates the post-processed output using the rules resident in these files. Users have the ability to edit these files to modify these rules, thereby controlling the output that RhinoCAM generates.

For purposes of brevity, Rhino refers to both Rhinoceros 7 or Rhino 8.

Using the RhinoCAM Post-Processor Generator, these SPM files can be edited by following these steps:

First choose the required SPM file to edit from the Post Processor File Browser. After selecting the file, it can be edited using the Editor dialog. The format of various output blocks, such as motion, feed rates, spindle etc., can be edited by selecting the appropriate tabs in this dialog.

In addition to predefined block definitions, you can add startup codes as well as termination codes specific to the controller and shop practices. These blocks can be user-defined statements that may contain built in variables.

Related Topics

Good Thinks to Know

Post Processor File Browser

Main Editor

Variable List Dialog

12.1.2 Quick Start

RHINO CAM 2024



Prefer Printed Documentation? Check Here!

Quick Start Guides for each RhinoCAM module are available in both PDF and Video format. Refer to the following information to access these resources:

What's New!

What's New in RhinoCAM 2024

Watch the What's New in 2024 Webinar!

The Complete Quick Start Video Play List

Here is a link to the complete 2024 Video Play List

How to Access the Quick Start Guide Documents

To help you quickly get started in working with each module, select one of the Help buttons located on the RhinoCAM Learning Resources dialog.

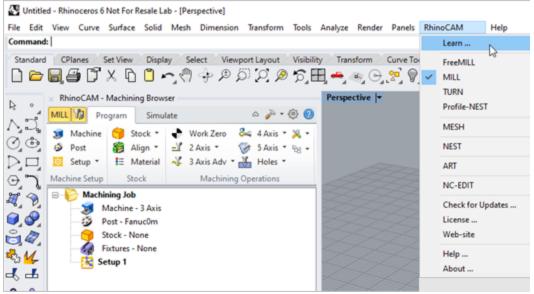
You will find:

• Quick Start Guides

- What's New documents
- Online Help links

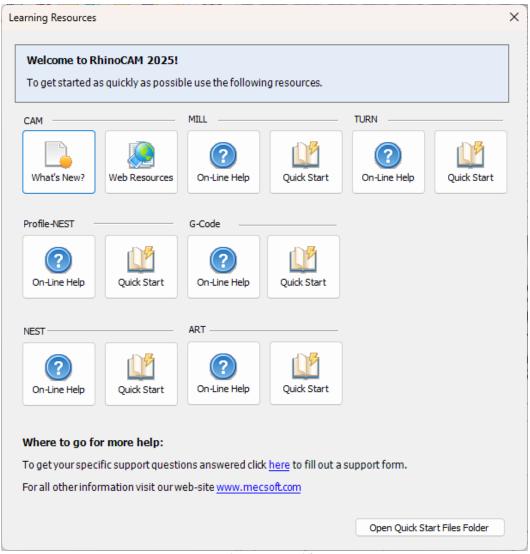
The Quick Start Guides will help you step through an example tutorial which will illustrate how to use the module. To access the Learning Resources dialog:

1. From the Rhino Main Menu, drop down the Main menu and select Learn ...



To access the Learning Resources dilog in RhinoCAM

- 2. Select a document from the Learning Resources dialog to get started using the module of your choice.
 - You can also select the Open Quick Start Files Folder button located at the bottom of the dialog to open the Quick Start folder where the source files (start and completed versions) are located.



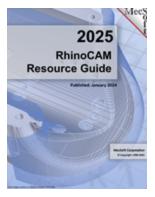
Learning Resources Dialog

Related Topics
Find More Resources

12.1.3 Resource Guide

Download this PDF Guide for a list of the available RhinoCAM Resources.

2024 RhinoCAM Resource Guide



The 2024 RhinoCAM Resource Guide!

18 Pages

Lists PDF downloads and Online resources including Quick Start Guides, Reference Guides, Exercise Guides, Tutorials and More.

Prefer Printed Documentation? Check Here!

12.1.4 Good Things to Know

Here is a list of things you should know when posting G-Code using a customized post created from the Post-Processor Generator in RhinoCAM.

Algebraic Expressions when Posting

The Post Process Generator supports Algebraic Expressions in all input fields.

Here are some guidelines for using expressions:

- 1. Each expression should be placed in 'E{', 'E}' tags.
- 2. In expression can be used next operations: -,+,/,*,^
- 3. Negative values should be placed in parentheses '()'
- 4. Expression parts can be placed in parentheses '()'
- 5. Floating point numbers should be delimited by point symbol, use 0.xx in case of fractional numbers
- 6. Expressions can contain spaces in any place, spaces will be removed while parsing
- 7. Numbers in [-0.9; 0.9] can be written as [-.9; .9]

Examples:

- E{ ([SOME_VAR1]/2 + ([SOME_VAR]*(-3.2)))^3 E}
- E{[SOME_VAR1] + .3 E} SOME_TEXT E{ [SOME_VAR1] *(-1) E}

Posting Drill Cycles & Indexed Machining

Drill cycles will be converted to simulated cycles (i.e., using linear motions) if the setup the drill cycles appear in is not aligned with the machine Z axis. This is done only when the machine has a head configuration defined and Output all coordinates in local Setup Coordinate System is not checked. See Machine Tool Setup for more information.



Posting Cutter Compensation (G40, G41, G42)

All toolpaths except engraving are automatically compensated for the tool geometry. Cutter compensation is used typically to compensate for the difference in the dimensions of the actual cutter used in machining and the cutter used for programming in RhinoCAM. For example, if the cutter used in programming is 0.25 inches and due to tool wear the actual cutter is only 0.24 inches in size, you can compensate for this at the controller rather than having to re-program the operation in RhinoCAM.

Cutter compensation is used extensively in production (high volume) machining where the machine operator can compensate for tool wear before having to stop and replace the tool or insert.

In order to do this the user needs to do the following:

- 1. Turn cutter compensation on in the operation to Auto/ON or CONTROL/ON.
- 2. Specify the cutter compensation value and the compensation register in the controller (the controller needs to be capable of doing this).
- 3. Please make sure the post processor is configured to output cutter compensation. This is defined under the Cutter Compensation section in the post processor generator. Most controllers expect an X & Y motion on the same line as cutter compensation.

Cutter Compensation Left

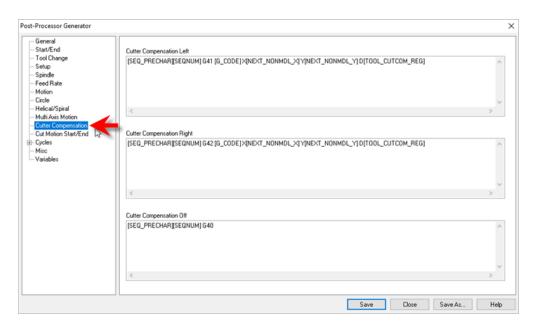
[SEQ_PRECHAR][SEQNUM] G41 [G_CODE] X[NEXT_NONMDL_X] Y[NEXT_NONMDL_Y] D[TOOL_CUTCOM_REG]

Cutter Compensation Right

[SEQ_PRECHAR][SEQNUM] G42 [G_CODE] X[NEXT_NONMDL_X] Y[NEXT_NONMDL_Y] D[TOOL_CUTCOM_REG]

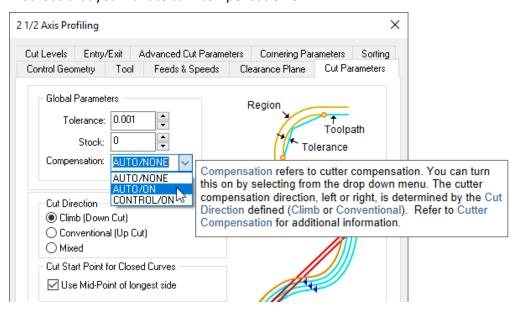
Cutter Compensation Off

[SEQ PRECHAR][SEQNUM] G40



A few things to watch out for:

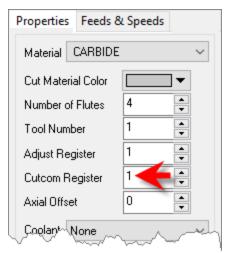
- 1. Cutter compensation makes sense only in 2-1/2 axis operations. If you are using roughing (pocketing & facing) the compensation will be turned on only in the final passes.
- 2. Make sure you are using Climb or Conventional cut traversal in any of the methods that you want to turn compensation on.



3. Make sure you have a linear motion for the controller to turn on the compensation for. If your first motion is an arc the controller will not be able to turn on the compensation. Thus, in 2-1/2 axis profiling, make sure there is a linear entry motion for the controller to be able to turn compensation on & linear exit to turn off compensation.

If you are looking to compensate for the full tool diameter, set Stock = -0.125 under the cut parameters tab. (0.125 being the radius of the tool). This would generate the toolpath ON the curve. This would invalidate the simulation as the tool tip stays on the drive geometry.

Note: The Cutcom Register is set under the Create/Select Tool definition dialog.



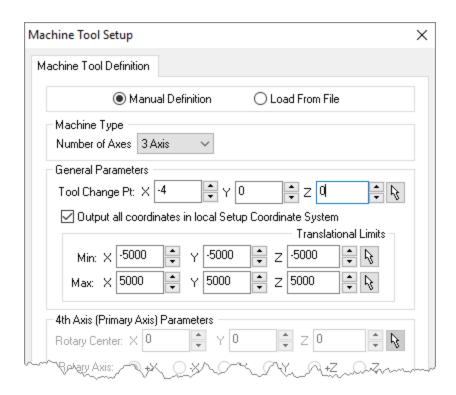
Posting a Tool Change Point

Implementing a Tool Change Point can be useful. For example in 2 and 3 Axis, you may want to change tools manually between operations (i.e., your CNC machine does not have an automatic tool changer). Also in 4 Axis you may want to ensure the tool is moved to a save location prior to a table rotation. To output a Tool Change Point to your posted g-code files, please do the following:

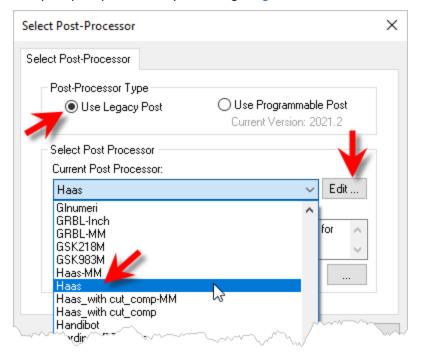
For 2 and 3 Axis Output

- From the Machine Setup dialog (Program tab > Machine > General Parameters > Tool Change Pt), enter your required tool change point coordinates.
- 2. For the sample code (shown at the end of this section) we entered the following values in the Machine Setup dialog:

X: -4, Y: 0 Z: 0



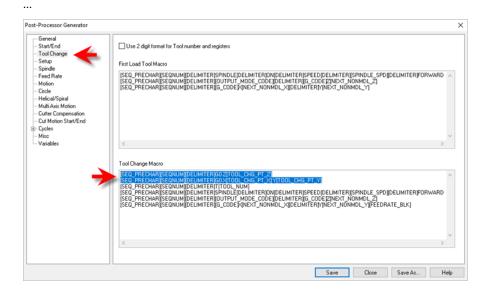
3. Edit your post processor by selecting Program tab > Post > Edit.



4. From the Post Process Generator dialog, select the Tool Change section from the left side of the dialog.

 In the Tool Change Macro block section, replace the first line of text with the following two lines of text at the top of the macro. These two lines of text should precede the line that includes T[TOOL_NUM] as shown in the examples below.

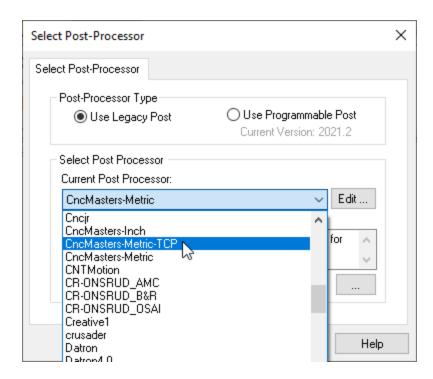
[SEQ_PRECHAR][SEQNUM][DELIMITER]G0 Z[TOOL_CHG_PT_Z]
[SEQ_PRECHAR][SEQNUM][DELIMITER]G0 X[TOOL_CHG_PT_X] Y[TOOL_CHG_PT_Y]
[SEQ_PRECHAR][SEQNUM][DELIMITER]T[TOOL_NUM]



6. If your controller expects to see an optional stop call BEFORE each tool change, you can add another line like below:

```
[SEQ_PRECHAR][SEQNUM][DELIMITER]G0 Z[TOOL_CHG_PT_Z]
[SEQ_PRECHAR][SEQNUM][DELIMITER]G0 X[TOOL_CHG_PT_X] Y[TOOL_CHG_PT_Y]
[SEQ_PRECHAR][SEQNUM][DELIMITER]M01
[SEQ_PRECHAR][SEQNUM][DELIMITER]T[TOOL_NUM]
...
...
```

- 7. From the Post Process Generator dialog, pick Save As.
- 8. Enter a unique name for your post file (*.spm) for testing and pick Save.
- 9. From the Set Post-Processor Options dialog, select the revised post from the Current Post Processor list.



- 10. Note: If you do not see your revised post in the list, select the "..." button to the right of the "Folder where post-processor file are located" and select the folder where you saved your revised post file to (see Step 7 above) and pick OK.
- 11. You should now see your revised post in the list. Select it and pick OK.
- 12. Post a sample toolpath using the revised post.
- 13. Review the g-code test file and locate the first tool change lines of code.
- 14. Your sample test should look something like this depending on your post (based on the tool change point we used in Step 2 above). Note the tool change coordinates in blue:

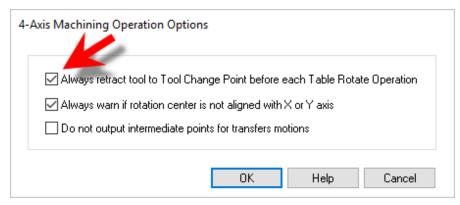
```
...
N66 ;2 1/2 Axis Profiling
N68 G0 Z0.
N70 G0 X-4. Y0.
N72 T1 M06
...
```

15. That's it!

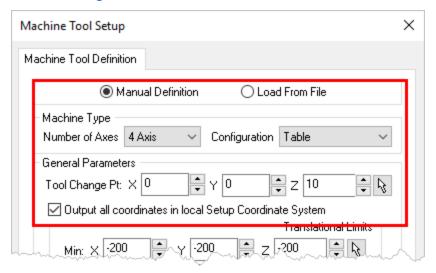
For 4 Axis Output

1. From the Program tab select 4 Axis.

- 2. From the 4 Axis menu select 4 Axis Options.
- 3. From the 4 Axis Operation Options dialog check the box to Always retract tool to Tool Change Point before each Table Rotate Operation.



- 4. Now from the Program tab select Machine and then Manual Definition.
- 5. For the Machine Type select 4 Axis.
- 6. Under General Parameters, enter the X, Y and Z coordinate values for the Tool Change Point.



- 7. Then check the box to Output all coordinates in local Setup Coordinate System and then pick OK to close the dialog.
- 8. Post the 4 Axis toolpath operation and verify that the Tool Change Point is being posted before the table rotation angle similar to this:

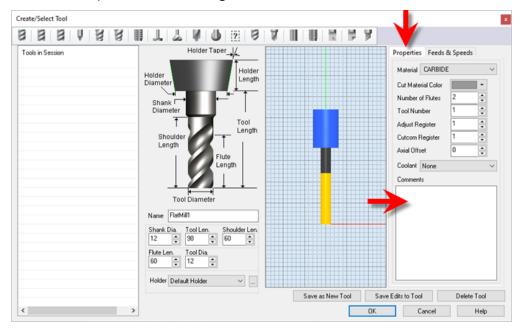
... (Setup 2) N6263 Z10. N6264 X0.Y0. (Horizontal Roughing) N6265 A180.F300.

Posting Tool Comments

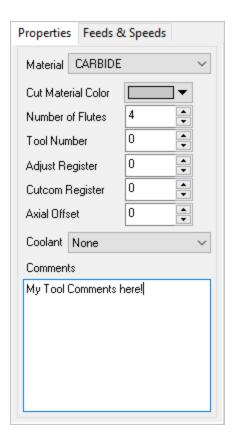
You can add comments associated with a Tool. These Comments are saved with the Tool in your Tool Library. They are also posted to your g-code when the tool is used.

Here are the steps to add Comments to a Tool:

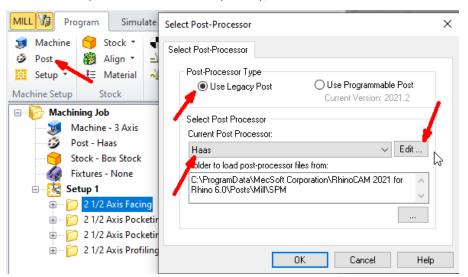
- 1. Edit the Tool using the Create/Select Tool dialog.
- 2. Select the Properties tab on the right.



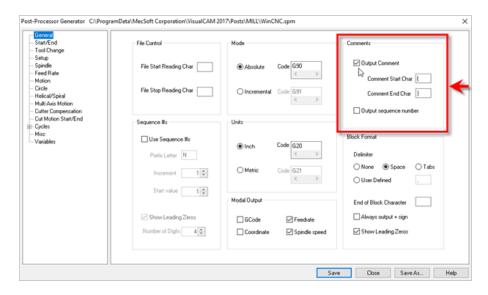
3. Add text to the Comments window.



- 4. Make sure Comments are enabled in your post.
 - A. Click on Post (Set Post-Processor Options), then click Edit.



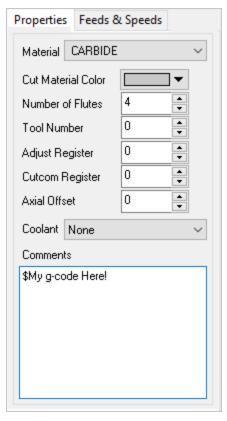
- B. From the Post Processor Generator dialog, select the General tab from the left.
- C. Check the box to Output Comments. You can also change the start and end characters to use.



- D. Then pick Save or Save As.
- 5. Now post your operations and see your comments:

```
...
G1 X0.5301 Y-0.7171 Z0.7480
G3 X0.7801 Y-0.4671 I0.0000 J0.2500 F2.6
G1 X0.7801 Y-0.2171 Z0.7480 F6.9
G0 Z0.9843
G0 X0.7801 Y-0.2171
(2 1/2 Axis Profiling)
(My Tool Comments Here!)
S18000
G0 Z0.9843
G0 X0.5301 Y-0.7097
G1 X0.5301 Y-0.7097
G1 X0.5873 Y-0.7097 Z0.7480 F6.9
G1 X0.5873 Y-0.6345 Z0.7480
G1 X0.4729 Y-0.6345 Z0.7480
...
```

6. If you want to post g-codes instead of comments, just place a \$ character prior to the comment in the Create/Select Tools dialog. Adding \$ as prefix will skip the comment start & end characters in the posted code.



...
G1 X0.4655 Y-0.7171 Z0.7480
G1 X0.5301 Y-0.7171 Z0.7480
G3 X0.7801 Y-0.4671 I0.0000 J0.2500 F2.6
G1 X0.7801 Y-0.2171 Z0.7480 F6.9
G0 Z0.9843
G0 X0.7801 Y-0.2171
(2 1/2 Axis Profiling)
My g-code Here!
S18000
G0 Z0.9843
G0 X0.5301 Y-0.7097
G1 X0.5301 Y-0.7097
G1 X0.5373 Y-0.7097 Z0.7480 F6.9
G1 X0.5873 Y-0.6345 Z0.7480
...

Related Topics

Post Processor File Browser

Main Editor

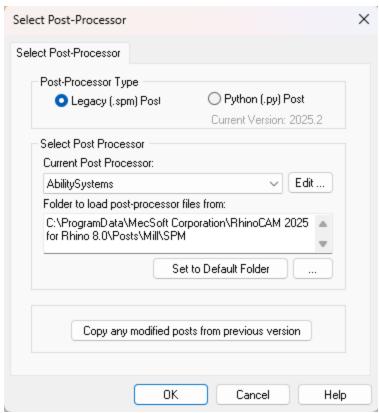
Variable List Dialog

...

12.1.5 Use Legacy Post

Select this option from the Post-Processor Options dialog to use your "Legacy Post" when posting toolpath operations. "Legacy Post" refers to your post definition (*.spm) file you used prior to version 2021. This option also lists the over 300 existing post-processors. See Current Post Processor below.

Dialog Box: Set Post-Processor Options



Dialog Box: Set Post-Processor Options

Post Processor Type

Use these options to define the post type to use when posting toolpath operations. Each option is documented further in the Post-processor Generator On-Line Help.

Use Legacy Post

Select this option to use your "Legacy Post" when posting toolpath operations. "Legacy Post" refers to your post definition (*.spm) file you used prior to version 2021. This option also lists the over 300 existing post-processors. See Current Post Processor below.

Use Programmable Post

Select this option to use your "Programmable Post" when posting toolpath operations. "Programmable Post" refers to your programmable post created with our version 2021

and newer CAM plugins. This option will list only one post processor selection called PostModifier. This post definition is defined using the Programmable Post API.

Current Post Processor

You can change the default post processor by selecting a post from the list of available post processors under Current Post Processor. If Use Legacy Post is selected, the Current Post Processor list will contain MecSoft's standard list of over 300 post processors. If Use Programmable Post is selected, this will list only one post processor selection called PostModifier. This post definition is defined using the Programmable Post API. Refer to the Programmable Post API documentation for more about the API.

Folder where post-processor files are located

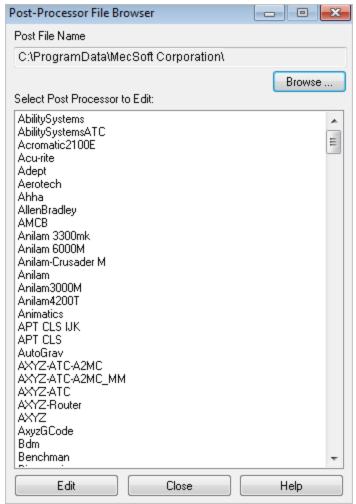
MILL module uses macro files with a .spm extension to handle post-processing to different controllers. These files are typically located in the "Posts" directory under the RhinoCAM installation folder(C:\ProgramData\MecSoft Corporation\RhinoCAM 2024 for Rhino x.x\Posts\Mill).

12.1.5.1 Dialogs

12.1.5.1.1 Post Processor File Browser

The dialog shown below is used to select the post processor file to be edited. (SPM File). The name and location of the post processor file can be either entered in the edit box provided, or can be selected using the browse button. You can double click on the required SPM File to invoke the <u>Editor</u>.

Dialog Box: Post Processor File Browser



Dialog Box: Post Processor File Browser

Related Topics

Introduction

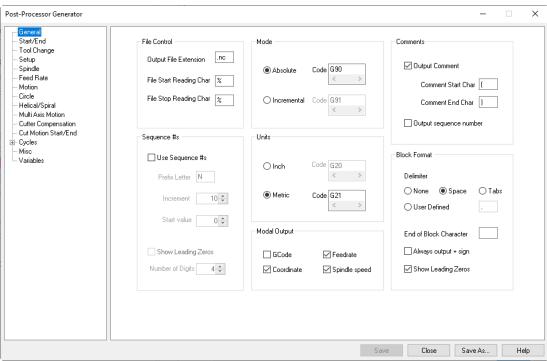
Post Processor Editor

Variable List Dialog

12.1.5.1.2 PPG Editor

The RhinoCAM Post-Processor Generator (PPG) Editor is shown below. This Editor is divided into sections (listed on the left) allowing you to define each block type. Refer to the list of sections below.

Dialog Box: Post Processor Generator: Editor



Dialog Box: Post Processor Generator: Editor

PPG Editor Sections

General

This folder helps you set up file information, G-Code format, mode and the units of operation.

- Start End Start and End code specifier.
- <u>Tool Change</u>
 Load and Tool Change Macro specifier.
- <u>Setup</u>
 Setup change and Rotate Table Setup specifier.
- Spindle Spindle code specifier.
- <u>Feed Rate</u>
 Feed Rate specifier.
- Motion Motion block specifier
- <u>Circle</u>
 <u>Circle</u> block specifier.
- Helical/Spiral
 Helical and Spiral motion block specifier.

- <u>Multi Axis Motion</u>
 Multi Axis Motion specifier.
- <u>Cutter Compensation</u>
 Motion blocks for Cutter Compensation Right, Left and Off.
- <u>Cut Motion Start/End</u>
 <u>Cut Motion Start and End macro blocks.</u>
- <u>Cycles</u>
 <u>Cycle G-Code</u> and format specifier.
- <u>Miscellaneous</u>
 Coolant and Compensation code specifier
- <u>Variables</u>
 Lists variables and their values used in post-processing
- Related Topics

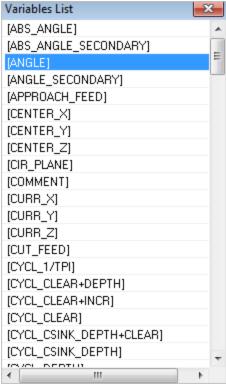
 Introduction

<u>Post Processor File Browser</u> <u>Variable List Dialog</u>

12.1.5.1.3 Variable List Dialog

The Variable List dialog shown below can be invoked by pressing the right mouse button from within edit boxes that are used in setting up startup and termination code for a post-processor. This dialog can be used to add <u>variables</u> to the active edit box for <u>macros</u>.

Dialog Box: Variable List



Dialog Box: Variable List

Related Topics

Post Processor File Browser

Post Processor Editor

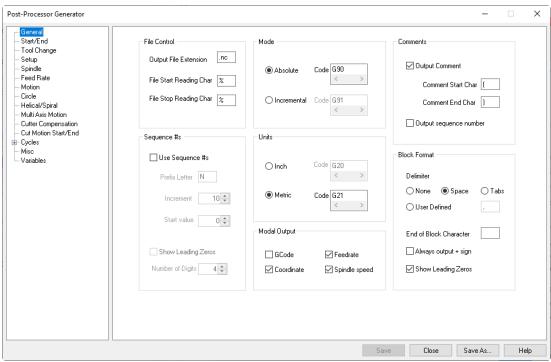
Variables List

12.1.5.2 PPG Editor

12.1.5.2.1 General

The General section allows you to define the general behavior of the post-processor output. Each editable parameter is described below.

PPG Editor: General



PPG Editor: General

File Control

This section allows you to set the default extension of the output file.

Output File Extension

This allows you to set the posted file extension here in the PPG. Once set, go to the Post Preferences dialog (CAM Preferences > Post) and check the box "File Extension from Post Processor". The file extension will also be shown in that dialog.

• File Start Reading Char

The user can also set up an optional File Start character. This file start character will be the first character written to the output file.

• File Stop Reading Char

Similarly the file end character will be the last character written to the output file. Most standard controllers look for a percent sign (%) as this last character.

Mode

Coordinate values can be set to be either Absolute or Incremental. In the Absolute mode, coordinate values (X, Y, Z, I, J, K) are output as absolute values. In the Incremental mode, coordinate values are output as incremental values.

Comments

This section defines the general format of commentary blocks.

- Output Comment: Set parameter to output comments
- Comment Start Char: Comment start character
- Comment End Char: Comment end character
- Output Sequence Number: Toggle sequence number for comments

If you want the comments to be output just as it is without the Start Character and the End Character, then in RhinoCAM, when you are inserting a comment, type in a \$ sign in front of it, like:

\$ Comment



Sequence #s

This section allows you to control the format of sequence numbers to the output file. This option is available for all G-code lines except Tool change Macro and Start and End Code.

- Use Sequence #s Sequence number output can be turned on or off.
- Prefix Letter

When on, a prefix letter can optionally be added at the beginning of every sequence number.

Increment

Sequence numbers can also be output in increments rather than sequentially. This increment value can be specified here.

• Start Value

This specifies the starting value for the sequence numbers.

Show Leading Zeros

In addition the number of digits output as well as presence/absence of leading zeros in the sequence numbers can be controlled.



This tells the post-processor the units of the output file by outputting a units code that can be defined here. Output units can either be in the English system (inches) or in the Metric system (mm).

Inch

Sets the units to Inches and post the code G20 by default. This code can be changed if desired.

Metric

Sets the units to Millimeters and post the code G21 by default. This code can be changed if desired.

Block Format

This section defines the general format of all output blocks. Each of the options is described below.

Delimiter:

This is the delimiter used between G-codes. Example where delimiter is set to [D]: G01[D]X1.0[D]Y2.0[D]Z3.0[D] S3000M03[D]F20

None: No delimiter is posted in the output.

Space: A space character is output as the delimiter

Tab: A tab character is output as the delimiter

User Defined: Select this option and then enter the delimiter character to use.

- End of Block Character: End of block character to output
- Always output +sign: Outputs a '+' (no quote marks included) for positive values.
- Show Leading Zeros: Check this box to include leading zeros in the posted code. Example (G01 X+1.0 Y+1.0 Z+1.0)

Modal Output

The Post processor generator allows the following parameters to be set as modal or non-modal. The modal output setting will output the value of a variable only if it is different from the value that was last output.

- Gcode: G-Code modal option sample
- Coordinate: Coordinates modal option sample
- Feedrate: Feed Rate modal option sample
- Spindle speed: Spindle Speed modal option sample

An example of non-modal data is shown below. The repeated values are shown in colored text.

\$1000M03 G00 X1.0 Y2.0 Z0.0 F10 \$2000M03 G01 X1.0 Y2.0 Z3.0 F20 G01 X1.0 Y3.0 Z3.0 F20 \$2000M03

Related Topics

Other PPG Editor Sections:

Start/End

Tool Change

<u>Setup</u>

Spindle

Feed Rate

Motion

Circle

Helical/Spiral Cycles

Multi Axis Motion

Cutter Compensation

Cut Motion Start/End

Cycles

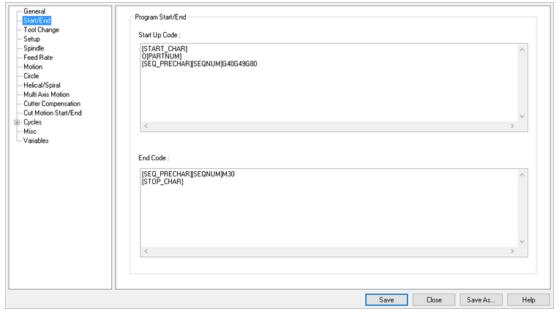
Miscellaneous

Variables

12.1.5.2.2 StartEnd

This tab is used to set the Start and End G-Codes.

PPG Editor: Start/End



PPG Editor: Start/End

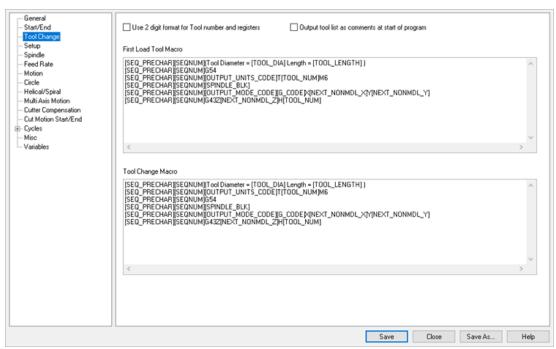
Startup Code

First macro output in the generated NC file. Example: [START_CHAR] O[PART NUM] [SEQ_PRECHAR][SEQNUM]G40G49G80 **End Code** Last macro output in the generated NC file. Example: [SEQ_PRECHAR][SEQNUM]M30 [STOP_CHAR] Related Topics How to edit macros Other PPG Editor Sections: General **Tool Change Setup Spindle Feed Rate Motion** Circle Helical/Spiral Cycles Multi Axis Motion **Cutter Compensation Cut Motion Start/End Cycles Miscellaneous Variables**

12.1.5.2.3 Tool Change

This tab is used to set the Load Tool and Tool Change macros.

PPG Editor: Tool Change



PPG Editor: Tool Change

Use 2 digit format for Tool number and registers

Check this box to use 2-digit format for Tool Numbers and Tool Registers (i.e., T01)

Output tool list as comments at start of program

Check this box to include the tool list as a comment at the start of the program.

Example:

```
%
Ob
N1G40G49G80
(BEGIN TOOL LIST)
(TOOL 1 - FLAT MILL- 1/2 INCH - DESC: 0.5000 DIA, 2 FLUTE, CARBIDE MAT)
(TOOL 2 - BALLMILL- 1/4 INCH - DESC: 0.2500 DIA, 2 FLUTE, CARBIDE MAT)
(ENDOF TOOL LIST)
(Setup 1)
(Horizontal Roughing)
N2(Tool Diameter = 0.5 Length = 4.0)
N3G54
...
```

First Load Tool Marco

Macro for the first load tool command. Example: [SEQ_PRECHAR][SEQNUM](Tool Diameter = [TOOL_DIA] Length = [TOOL_LENGTH]) [SEQ PRECHAR][SEQNUM]G54 ISEQ PRECHARIJSEQNUMIJOUTPUT UNITS CODEJTITOOL NUMIM6 [SEQ PRECHAR][SEQNUM][SPINDLE BLK] [SEQ_PRECHAR][SEQNUM][OUTPUT_MODE_CODE][G_CODE]X[NEXT_NONMDL_X] YNEXT NONMDL Y [SEQ_PRECHAR][SEQNUM]G43Z[NEXT_NONMDL_Z]H[TOOL_NUM] ☐ Tool Change Macro Macro for tool change command. (Not including the first load tool.) Example: [SEQ_PRECHAR][SEQNUM](Tool Diameter = [TOOL_DIA] Length = [TOOL_LENGTH]) [SEQ PRECHAR][SEQNUM][OUTPUT UNITS CODE]T[TOOL NUM]M6 [SEQ PRECHAR][SEQNUM]G54 [SEQ_PRECHAR][SEQNUM][SPINDLE_BLK] ISEQ PRECHARIJSEQNUMIJOUTPUT MODE CODEJIG CODEJXINEXT NONMDL XI YNEXT NONMDL Y [SEQ_PRECHAR][SEQNUM]G43Z[NEXT_NONMDL_Z]H[TOOL_NUM] **Related Topics** How to edit macros Other PPG Editor Sections: General Start/End

Setup

Spindle

Feed Rate

Motion

Circle

Helical/Spiral Cycles

Multi Axis Motion

Cutter Compensation

Cut Motion Start/End

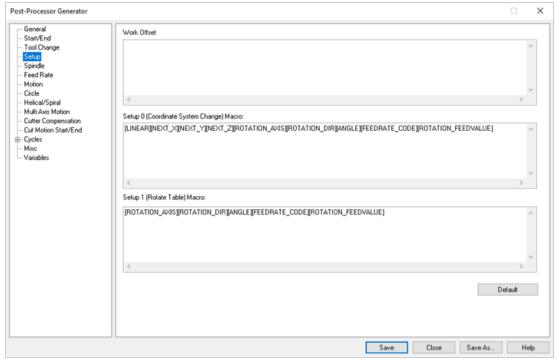
Cycles

Miscellaneous

Variables

12.1.5.2.4 Setup

PPG Editor: Setup



PPG Editor: Setup

Work Offset

You can define macros here that will control the format of each Work Offset in the posted g-code file.

Setup 0 (Coordinate System Change) Macro

Macro to execute before every Setup change.

Example:

[LINEAR][NEXT_X][NEXT_Y][NEXT_Z][ROTATION_AXIS][ROTATION_DIR][ANGLE] [FEEDRATE_CODE][ROTATION_FEEDVALUE]

Setup 1 (Rotate Table) Macro

Macro to execute before every Rotate Table Setup change.

Example:

[ROTATION_AXIS][ROTATION_DIR][ANGLE][FEEDRATE_CODE][ROTATION_FEEDVALUE]

Related Topics

Other PPG Editor Sections:

General

Start/End

Tool Change

Spindle

Feed Rate

Motion

<u>Circle</u>

Helical/Spiral Cycles

Multi Axis Motion

Cutter Compensation

Cut Motion Start/End

Cycles

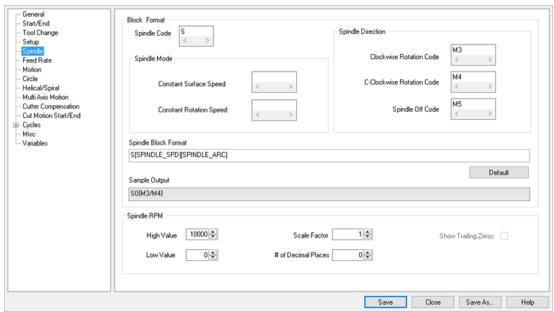
Miscellaneous

Variables

12.1.5.2.5 Spindle

This tab is used to set parameters for controlling the spindle.

PPG Editor: Spindle



PPG Editor: Spindle

Block Format

Sets the spindle block format.

- Spindle Code: Register used for the feed rate value.
- Spindle Direction: Specify the direction code for the spindle

Clockwise Rotation Code: Clockwise spindle code

C-Clockwise Rotation Code: Counter clockwise spindle code

Spindle Off Code: Spindle off code

Spindle Mode:

Constant Surface Speed:

Constant Rotation Speed:

- Spindle Block Format: Defines the block format for the spindle. Example: S[SPINDLE_SPD][SPINDLE_ARC]
- Default: Reset all values in this section to their system defaults.
- Sample output: This field displays sample output of the spindle block. It is a non-editable field.

Spindle RPM

 High Value: Maximum spindle value. The spindle RPM is capped to this high value.

- Low Value: Minimum spindle value. The spindle RPM is capped to this low value.
- Scale Factor: Scale factor of Spindle value.
- # of Decimal Places: Number of digits output after the decimal point
- Show Trailing Zeros: Show trailing zeros when # of Decimal Places is set to a value greater than zero.

Related Topics

Other PPG Editor Sections:

General

Start/End

Tool Change

Setup

Feed Rate

Motion

Circle

Helical/Spiral Cycles

Multi Axis Motion

Cutter Compensation

Cut Motion Start/End

Cycles

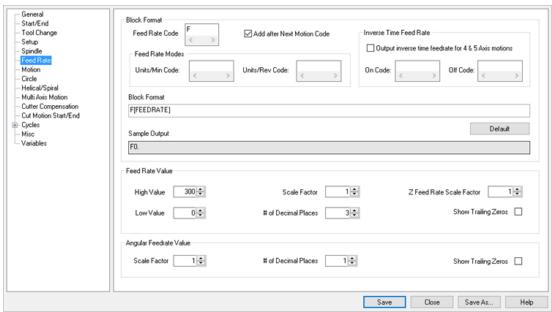
Miscellaneous

Variables

12.1.5.2.6 Feed Rate

This tab sets the feeds and speeds parameters

PPG Editor: Feed Rate



PPG Editor: Feed Rate

Block Format

Characters for the feed rate block:

- Feed Rate Code: Register used for the feed rate value
- Add after Next Motion Code:
- Feed Rate Modes

Units/Min Code: Typically a G94
Unites/Rev Code: Typically a G95

• Inverse Time Feed Rate

When Output inverse time feedrate for 4 & 5 Axis motions is selected the On Code is output at the start of the operation and Off Code at the end.

You turn on the Inverse Time Feedrate using a checkbox in the Post/Feedrate tab. You can set up the code for On and Off in the same tab. Once this is set, then all 4 and 5 axis motions will be processed with this feedrate being output.

The way the feedrate is computed is as follows:

First the distance traveled by the tool is computed for each move = dist

Then the time taken for traversing the move is computed thus: timeForTravel = dist / cutFeedRate;

Then the inverse time feedrate is = 1.0/timeForTravel;

And it is output for each move if different from previous move.

On Code: G93 Off Code: G94

- Block Format: Format for the feed rate block
- Default: Reset all values in this section to their system defaults.
- Sample Output: Sample output displays sample code of the feed rate. It is a non-editable field.

Feed Rate values

Parameters for the adjustment of feed rate value:

- High Value: Maximum Feed rate value.
- Low Value: Minimum Feed rate value.
- Scale Factor: Scale factor of Feed rate value.
- # of Decimal Places: Number of digits output after the decimal point.
- Z Feed Rate Scale Factor: Feed rate scale factor for Z Feed Rate (use [ZFEEDRATE] variable to get the Z feed rate)
- Show Trailing Zeros: Show trailing zeros when # of Decimal Places is set to a value greater than zero.

Angular Rate values

- Scale Factor: Enter the scale factor for angular feed rate values.
- # of Decimal Places: Number of digits output after the decimal point
- Show Trailing Zeros: Show trailing zeros when # of Decimal Places is set to a value greater than zero.

Related Topics

Other PPG Editor Sections:

<u>General</u>

Start/End

Tool Change

Setup

Spindle

Motion

Circle

Helical/Spiral Cycles

Multi Axis Motion

Cutter Compensation

Cut Motion Start/End

Cycles

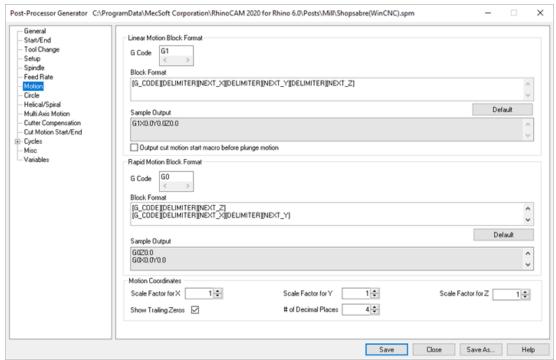
Miscellaneous

Variables

12.1.5.2.7 Motion

This tab is used to define the linear motion outputs of a post-processor. You can use multiple lines to define the Block Format in both the Linear Motion Block and the Rapid Motion Block.

PPG Editor: Motion



PPG Editor: Motion

Linear Motion Block

Used to define the output format for the cut motions (e.g.: G1). The sample output can be seen in the non-editable Sample Output field. Multiple lines of code are supported.

G Code: Typically a G1

- Block Format: Example: [G_CODE][NEXT_X][NEXT_Y][NEXT_Z]
- Default: Reset all values in this section to their system defaults.
- Sample Output: This displays how the posted output will look.
- Output cut motion start macro before plunge motion: Checking this box will output the cut motion start macro defined under <u>Cut Motion Start/End</u> section before the plunge motion in the posted code.

Rapid Motion Block Format

Used to define the output format for the rapid motions (e.g.: G0). The sample output can be seen in the non-editable Sample Output field. Multiple lines of code are supported.

- G Code: Typically G0
- Block Format: Example: [G_CODE][NEXT_Z] [NEXT_X][NEXT_Y]
- Default: Reset all values in this section to their system defaults.
- Sample Output: This displays how the posted output will look.

Motion Coordinates

- Scale Factor for X, Y, Z: Scale factor of the coordinate values. (Includes circles and cycles)
- Show Trailing Zeros: Show the trailing zeros (e.g. 5.4 is output as 5.4000)
- # of Decimal Places: Number of digits output after the decimal point

Related Topics

Other PPG Editor Sections:

General

Start/End

Tool Change

Setup

Spindle

Feed Rate

<u>Circle</u>

Helical/Spiral Cycles

Multi Axis Motion

Cutter Compensation

Cut Motion Start/End

Cycles

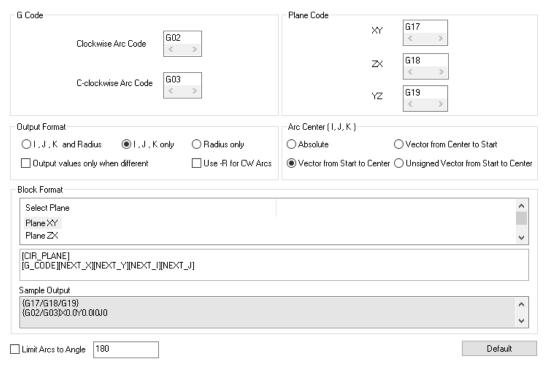
Miscellaneous

Variables

12.1.5.2.8 Circle

This tab is used to define the circle block output.

PPG Editor: Circle



PPG Editor: Circle

☐ G Code

Arc Direction Code:

Clockwise Arc Code: Typically G02

• C-clockwise Arc Code: Typically G03

Plane Code

The G Code for the principal planes in which the Arc motion is output.

- XY: Typically G17
- ZX: Typically G18
- YZ: Typically G19

Output Format

These options help define the output format for the circle command.

- I,J,K and Radius: Output I,J,K and Radius
- I,J,K only: Output only I,J,K.
- Radius only: Output only Radius.
- Output values only when different: Output <u>I,J,K,R</u> values only when different from the previous values.
- Use -R for CW Arcs: Prefixes -R before clockwise arc motions.

Arc Center (I,J,K)

Defines the calculation of the arc center coordinates.

- Absolute: is the absolute center
- Vector from Center to Start: is (Center Start)
- Vector from Start to Center: is (Start Center)
- Unsigned vector: is the unsigned distance between center and start.

Block Format

Used to specify the block format for three different planes. Use the default button to see the default values and edit them if needed.

Sample Output

This field displays sample output of the arc motion block. This field is non-editable. It indicates the parameters selected from the available options.

Limit Arcs to Angle

This is used to limit arcs to a certain angle. This is helpful for certain types of controllers which cannot output arcs greater than a certain angle

Default

Reset all values in this section to their system defaults.

Related Topics

Other PPG Editor Sections:

General

Start/End

Tool Change

<u>Setup</u>

Spindle

Feed Rate

Motion

Helical/Spiral Cycles

Multi Axis Motion

Cutter Compensation

Cut Motion Start/End

Cycles

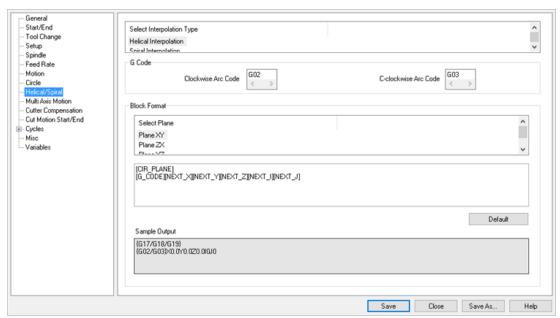
Miscellaneous

Variables

12.1.5.2.9 Helical/Spiral

This tab is used to define the Helix and Spiral block output. For both these cycles, the Arc Center and the Plane Code are the same as those defined in the Circle Section. Please define those first before defining these cycles.





PPG Editor: Helical/Spiral Cycles

Select Interpolation Type

Used to select the Interpolation type to define the parameters for the Helical Cycles or the Spiral Cycles.

G Code

Used to define the Clockwise and the Counter Clockwise Codes for the Helical or Spiral Cycles

Block Format

Used to specify the block format for three different planes. Use the default button to see the default values and edit them if needed.

Default

Reset all values in this section to their system defaults.

Sample Output

This field displays sample output of the Helical/Spiral motion block. This field is non-editable. It indicates the parameters selected from the available options.

Related Topics

Other PPG Editor Sections:

<u>General</u>

Start/End

Tool Change

Setup

Spindle

Feed Rate

Motion

Circle

Multi Axis Motion

Cutter Compensation

Cut Motion Start/End

Cycles

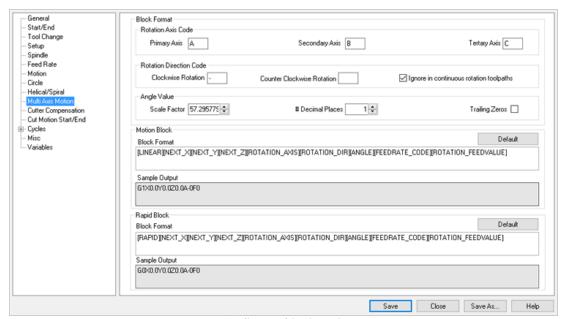
Miscellaneous

Variables

12.1.5.2.10 Multi Axis Motion

This tab is used to set 4th Axis Motion Section parameters.

PPG Editor: Multi Axis Motion



PPG Editor: Multi Axis Motion

Block Format

Rotation Axis Code

Characters for Rotation Axis Code.

- Primary Axis: Sets the primary axis code. Typically A
- Secondary Axis: Sets the secondary axis code. Typically B
- Tertary Axis: Sets the Tertary axis code. Typically C

Rotation Direction Code (Only for Rotate Table)

Characters for Rotation Direction Code

- Clockwise Rotation: Clockwise rotation code
- Counter Clockwise Rotation: Counter Clockwise rotation code
- Ignore in continuous rotation toolpaths: Check this box to ignore rotation direction in 4 Axis continuous rotation toolpaths.

Angle Values

Angle Value for 4th Axis Motion

- Scale Factor: Scale Factor for Angle Value (the angle is in radians, to convert to degrees use a scale factor of 57.295779513082
- # Decimal Places: No of Decimal Places
- Trailing Zeros: Number of Trailing Zeros after Decimal places

Motion Block

Motion Code for 4th Axis Motion

- Block Format: Helps to define the output format for the 4th Axis motion code.
- Sample Output: Sample output displays sample code of the 4th Axis motion. It is a non-editable field.
- Default: Reset all values in this section to their system defaults.

Rapid Block

Rapid Code for 4th Axis Motion

- Block Format: Helps to define the output format for the 4th Axis rapid code
- Sample Output: Sample output displays sample code of the 4th Axis rapids. It is a non-editable field.
- Default: Reset all values in this section to their system defaults.

Related Topics

Other PPG Editor Sections:

General

Start/End

Tool Change

<u>Setup</u>

Spindle

Feed Rate

Motion

Circle

Helical/Spiral Cycles

Cutter Compensation

Cut Motion Start/End

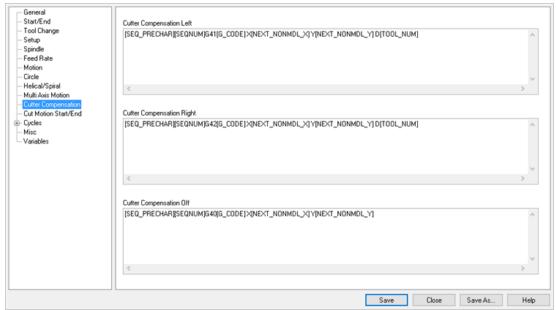
Cycles

Miscellaneous

Variables

12.1.5.2.11 Cutter Compensation

PPG Editor: Cutter Compensation



PPG Editor: Cutter Compensation

Cutter Compensation Left

Macro used to define the output when the cutter compensation left is detected in the output

Cutter Compensation Right

Macro used to define the output when the cutter compensation right is detected in the output

Cutter Compensation Off

Macro used to define the output when the cutter compensation cancel (off) is detected in the output

Related Topics

Other PPG Editor Sections:

<u>General</u>

Start/End

Tool Change

Setup

Spindle

Feed Rate

Motion

<u>Circle</u>

Helical/Spiral Cycles

Multi Axis Motion

Cut Motion Start/End

Cycles

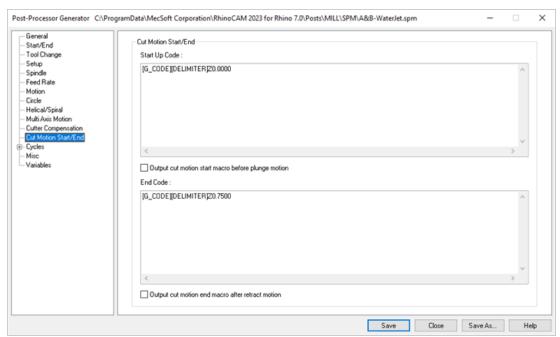
Miscellaneous

Variables

12.1.5.2.12 Cut Motion Start/End

The Cut Motion Start/End dialog allows you to define Start and End cut motion codes.

PPG Editor: Cut Motion Start/End



PPG Editor: Cut Motion Start/End

Output cut motion start macro before plunge motion

You can have the Cut Motion Start Up Code posted before plunge motions by checking the box.

Output cut motion end macro after retract motion

You can have the Cut Motion End Macro posted after the retract motions by checking this box.

Related Topics

Other PPG Editor Sections:

General

Start/End

Tool Change

Setup

Spindle

Feed Rate

Motion

Circle

Helical/Spiral Cycles

Multi Axis Motion

Cutter Compensation

Cycles

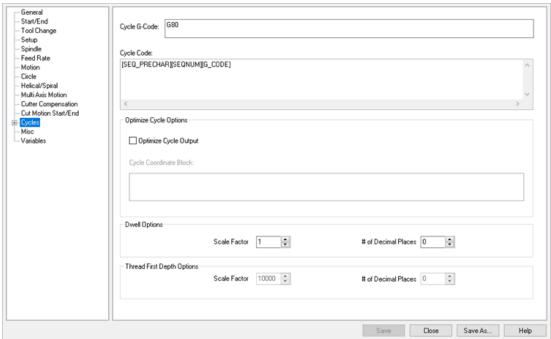
Miscellaneous

Variables

12.1.5.2.13 Cycles

This tab is to set the cycle parameters in the RhinoCAM Post-Processor.

PPG Editor: Cycles



PPG Editor: Cycles

Cycle G-Code

Macros for the cycle commands. It represents the selected G-code value that defines each specific cycle. This value is displayed in the edit box below all the available options. It can be changed if required.

Cycle Code

The following Cycles are supported:

- Cycle Off (G80)
- Standard Drill (G81)
- Standard Drill with Dwell On (G82)
- Deep (G83)

- Break Chip (G87)
- Counter Sink (G82)
- Tap (Clockwise) (G84)
- Tap (C-Clockwise) (G84)
- Peck Tapping (Clockwise) (G84)
- Peck Tapping (C-Clockwise) (G84)
- Rigid Tap (Clockwise) (T00)
- Rigid Tap (C-Clockwise) (T01)
- Bore (Drag) Dwell Off (G85)
- Bore (Drag) Dwell On (G89)
- Bore (No Drag) Dwell Off Orient On (G76)
- Bore (No Drag) Dwell On Orient On (G76)
- Bore (No Drag) Dwell Off Orient Off (G86)
- Bore (No Drag) Dwell On Orient Off (G86)
- Bore (Reverse) Dwell Off (G87)
- Bore (Manual) Dwell On (G88)
- Bore (Reverse) Dwell Off (G77)
- Bore (Reverse) Dwell On (G77)
- User Defined Drill Cycle 1
- User Defined Drill Cycle 2
- User Defined Drill Cycle 3
- User Defined Drill Cycle 4
- User Defined Tap Cycle 1
- User Defined Tap Cycle 2
- User Defined Tap Cycle 3
- User Defined Tap Cycle 4
- User Defined Bore Cycle 1
- User Defined Bore Cycle 2
- User Defined Reverse Bore Cycle 1
- User Defined Reverse Bore Cycle 2
- Turn Thread Cycle Automatic
- Turn Thread Cycle Box Cycle
- Turn Thread Cycle Single Block
- Machine Control Cycle 1
- Machine Control Cycle 2
- Machine Control Cycle 3
- Machine Control Cycle 4

Optimize Cycle Options

Optimize Cycle output will define the cycle format only once and will output the X,Y values for all the other holes. This will result in significant reduction in the file size for output.

• Optimize Cycle Output: Enables the optimized cycle options.

• Cycle Coordinate Block: Specific cycle block variables to use.

Dwell Options

- Scale Factor for Dwell: Sets the scale factor for dwell output.
- # of Decimal Places: Sets the number of decimal places for output.

Thread First Depth Options

- Scale Factor: Sets the scale factor for the first thread depth.
- # of Decimal Places: Sets the number of decimal places for output.

Related Topics

How to edit macros

Other PPG Editor Sections:

General

Start/End

Tool Change

Setup

Spindle

Feed Rate

Motion

Circle

Helical/Spiral Cycles

Multi Axis Motion

Cutter Compensation

Cut Motion Start/End

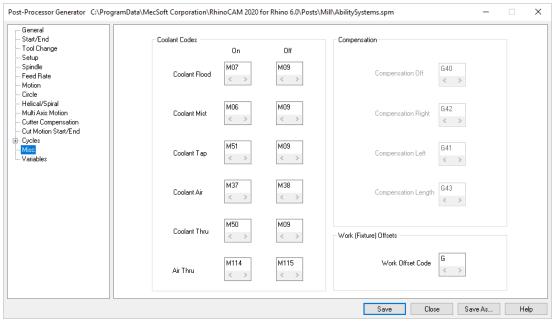
Miscellaneous

<u>Variables</u>

12.1.5.2.14 Miscellaneous

This tabbed dialog is used to set miscellaneous parameters. The various miscellaneous parameters are shown in the dialog.

PPG Editor: Miscellaneous



PPG Editor: Miscellaneous

Coolant Codes

Coolant Flood: Coolant Flood On/Off code

Coolant Mist: Coolant Mist On/Off code

Coolant Tap: Coolant Tap On/Off code

Coolant Air: Coolant Air On/Off code

• Coolant Thru: Coolant Thru On/Off code

• Air Through: Coolant Air Thru On/Off code

Compensation

- Compensation Off: (This is not editable reserved for future releases)
- Compensation Left: (This is not editable reserved for future releases)
- Compensation Right: (This is not editable reserved for future releases)
- Compensation Length: (This is not editable reserved for future releases)

Work (Fixture) Offsets

Work (Fixture) Offsets: Sets the work offset prefix code. Typically G. You can enable the output of the work offset code by selecting Output Work Offset from the Work Zero dialog and entering the offset code. For example, enabling and entering 54 in the Work Zero dialog activates this portion of the post and prefixes the code with this value. Example: G54.

Related Topics

Other PPG Editor Sections:

General

Start/End

Tool Change

Setup

Spindle

Feed Rate

Motion

Circle

Helical/Spiral Cycles

Multi Axis Motion

Cutter Compensation

Cut Motion Start/End

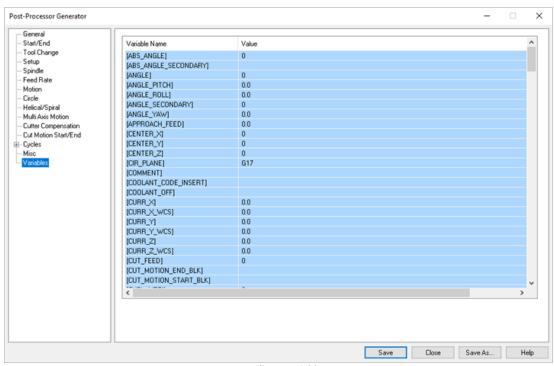
Cycles

<u>Variables</u>

12.1.5.2.15 Variables

This tab lists all the variables used in the macros in the RhinoCAM Post Processor.

PPG Editor: Variables



PPG Editor: Variables

Variables

The variables that can be used are listed in the table below.

The variables that start with "CYCL_" are used only for the cycles commands.

Variable	Comments
[ABS_ANGLE]	
[ABS_ANGLE_SECONDARY]	
[ANGLE]	
[ANGLE_PITCH]	
[ANGLE_ROLL]	
[ANGLE_SECONDARY]	
[ANGLE_YAW]	
[APPROACH_FEED]	
[CENTER_X]	
[CENTER_Y]	

[CENTER_Z]	
[CIR_PLANE]	
[COMMENT]	Output comments.
[COOLANT_CODE_INSERT]	
[COOLANT_OFF]	
[CURR_X]	The X coordinate of current point.
[CURR_X_WCS]	The X coordinate of current point in World Coordinates
[CURR_Y]	The Y coordinate of current point.
[CURR_Y_WCS]	The Y coordinate of current point in World Coordinates
[CURR_Z]	The Z coordinate of current point.
[CURR_Z_WCS]	The Z coordinate of current point in World Coordinates
[CUT_FEED]	
[CUT_MOTION_END_BLK]	
[CUT_MOTION_START_BLK]	
[CYCL_1/TPI]	1/TPI (only for TAP cycle)
[CYCL_CLEAR+DEPTH]	Drill Depth + Clear. (only for cycles except C-SINK)
[CYCL_CLEAR+INCR]	
[CYCL_CLEAR]	Clearance. (only for cycles)
[CYCL_CSINK_DEPTH+CLEAR]	Drill Depth + Clear. (only for C-SINK cycle)
[CYCL_CSINK_DEPTH]	Drill Depth. (only for C-Sink cycle)
[CYCL_DEPTH]	Drill Depth. (only for cycles except C-SINK)
[CYCL_DWELL]	Dwell. (only for cycles)
[CYCL_INCR]	Step Increment. (only for cycles)
[CYCL_IPM]	IPM. (only for cycles except TAP)
[CYCL_IPR]	IPR. (only for TAP cycle)
[CYCL_NEG_CLEAR+DEPTH]	-(Drill Depth + Clear). (only for cycles except C-SINK)
[CYCLE_NUM_STEPS]	
	I .

[CYCL_ORIENT]	Orient. (only for cycles)
[CYCL_SCALED_DWELL]	Dwell * Scale Factor (only for cycles)
[CYCL_TPI]	
[CYCLE_Z]	This variable stores the Z value of drill points.
[CYCL_Z+CLEAR]	Next Z + Clearance. (only for cycles)
[CYCL_Z+DEPTH+CLEAR]	Next Z + Depth + Clearance. (only for cycles)
[CYCL_Z+DEPTH]	Next Z + Depth. (only for cycles)
[CYCL_Z-DEPTH]	Next Z - Depth. (only for cycles)
[DELIMITER]	<u>Delimiter</u> definition.
[DEPART_FEED]	Outputs the Departure feedrate value for the currently operation.
[ENGAGE_FEED]	Outputs the Engage feedrate value for the currently operation.
[EOB]	The end of block character.
[EXTRUSION]	
[EXTRUSION_BLK]	
[EXTRUSION_CODE]	
[FEEDRATE]	FeedRate Value.
[FEEDRATE_BLK]	FeedRate Block.
[FEEDRATE_CODE]	Outputs the <u>Feedrate code</u>
[FEEDRATE_UNITS_CODE]	Outputs the <u>Feedrate Units code</u>
[FIRST_TOOL_NUM]	
[G_CODE]	The next G-Code. This is translated to linear, rapid, arc or cycle G-Code.
[HELIX_ANGLE]	
[HELIX_CCW_ARC]	
[HELIX_CW_ARC]	
[HELIX_LEAD]	
[HELIX_NUM_REV]	

[HELIX_RADIUS] [HELIX_TOTAL_DEPTH] [INPUTFILE_NAME] [INPUTFILE_NAME_LONG]	
[INPUTFILE_NAME]	
[INPUTFILE_NAME_LONG]	
[INV_TIME_FEEDRATE_OFF]	
[INV_TIME_FEEDRATE_ON]	
[LINEAR] The line	ar motion code.
[MOP_NAME]	
	absolute X coordinate point I Coordinates.
	absolute Y coordinate point I Coordinates.
	absolute Z coordinate point I Coordinates.
[NEXT_I]	
[NEXT_J]	
[NEXT_K]	
[NEXT_NONMDL_E]	
[NEXT_NONMDL_I]	
[NEXT_NONMDL_J]	
[NEXT_NONMDL_K]	
[NEXT_NONMDL_L]	
[NEXT_NONMDL_R]	
1	non-modal X coordinate local Machine Coordinates.
	non-modal X coordinate World Coordinates.
1. – – 1	non-modal Y coordinate local Machine Coordinates.
	non-modal Y coordinate World Coordinates.

[NEXT_NONMDL_Z]	The next non-modal Z coordinate point in local Machine Coordinates.
[NEXT_NONMDL_Z_WCS]	The next non-modal Z coordinate point in World Coordinates.
[NEXT_R]	
[NEXT_TOOL_NAME]	
[NEXT_TOOL_NUM]	
[NEXT_X]	The next X coordinate point in Machine Coordinates.
[NEXT_X_WCS]	The next X coordinate point in World Coordinates.
[NEXT_Y]	The next Y coordinate point in Machine Coordinates.
[NEXT_Y_WCS]	The next Y coordinate point in World Coordinates.
[NEXT_Z]	The next Z coordinate point in Machine Coordinates.
[NEXT_Z_WCS]	The next Z coordinate point in World Coordinates.
[OUTPUTE_MODE_CODE]	
[OUTPUT_UNITS_CODE]	English or Metric outputs code.
[OUTPUTFILE_NAME]	
[OUTPUT_FILENAME_LONG]	
[PARTNAME]	
[PARTNUM]	
[PLUNGE_FEED]	
[POST_NAME]	
[POST_NAME_LONG]	
[PREV_TOOL_ADJST_REG]	
[PREV_TOOL_CUTCOM_REG]	
[PREV_TOOL_NUM]	
[PREV_TOOL_NUM_FLUTES]	

[PREV_TOOL_ZOFFSET]	
[PROGRAM_END_BLK]	
[PROGRAM_START_BLK]	
[RAPID]	The <u>rapid motion code</u> .
[RAPID_FEED]	
[RETRACT_FEED]	
[ROTATION_AXIS]	
[ROTATION_AXIS_SECONDARY]	
[ROTATION_DIR]	
[ROTATION_DIR_SECONDARY]	
[ROTATION_FEEDVALUE]	
[ROTATION_MODE]	
[SEQ_PRECHAR]	Letter that is <u>prefixed</u> before the sequence number
[SEQNUM]	The actual sequence number.
[SEQNUM] [SETUP_NAME]	The actual sequence number.
	The actual sequence number.
[SETUP_NAME]	The actual sequence number.
[SETUP_NAME] [SETUP_X]	The actual sequence number.
[SETUP_NAME] [SETUP_X] [SETUP_XAXIS_X]	The actual sequence number.
[SETUP_NAME] [SETUP_X] [SETUP_XAXIS_X] [SETUP_XAXIS_Y]	The actual sequence number.
[SETUP_NAME] [SETUP_X] [SETUP_XAXIS_X] [SETUP_XAXIS_Y] [SETUP_XAXIS_Z]	The actual sequence number.
[SETUP_NAME] [SETUP_X] [SETUP_XAXIS_X] [SETUP_XAXIS_Y] [SETUP_XAXIS_Z] [SETUP_Y]	The actual sequence number.
[SETUP_NAME] [SETUP_X] [SETUP_XAXIS_X] [SETUP_XAXIS_Y] [SETUP_XAXIS_Z] [SETUP_Y] [SETUP_YAXIS_X]	The actual sequence number.
[SETUP_NAME] [SETUP_X] [SETUP_XAXIS_X] [SETUP_XAXIS_Y] [SETUP_XAXIS_Z] [SETUP_Y] [SETUP_YAXIS_X] [SETUP_YAXIS_Y]	The actual sequence number.
[SETUP_NAME] [SETUP_X] [SETUP_XAXIS_X] [SETUP_XAXIS_Y] [SETUP_XAXIS_Z] [SETUP_YAXIS_Z] [SETUP_YAXIS_X] [SETUP_YAXIS_Y] [SETUP_YAXIS_Y]	The actual sequence number.
[SETUP_NAME] [SETUP_X] [SETUP_XAXIS_X] [SETUP_XAXIS_Y] [SETUP_XAXIS_Z] [SETUP_YAXIS_Z] [SETUP_YAXIS_X] [SETUP_YAXIS_Y] [SETUP_YAXIS_Y] [SETUP_YAXIS_Z]	The actual sequence number.

[SETUP_ZAXIS_Z]	
[SPINDLE_ARC]	Spindle direction.
[SPINDLE_BLK]	Spindle Block.
[SPINDLE_CODE]	
[SPINDLE_SPD]	Spindle speed.
[SPINDLE_SPD_MAX]	
[SPINDLE_SPD_TYPE]	
[SPIRAL_ANGLE]	
[SPIRAL_CCW_ARC]	
[SPIRAL_CW_ARC]	
[SPIRAL_END_RADIUS]	
[SPIRAL_LEAD]	
[SPIRAL_NUM_REV]	
[SPIRAL_START_RADIUS]	
[SPIRAL_TOTAL_LENGTH]	
[START_CHAR]	The program start character.
[START_POSITION_X]	
[START_POSITION_Y]	
[START_POSITION_Z]	
[START_X]	The X coordinate of start point.
[START_X_WCS]	The X coordinate of start point in World Coordinates.
[START_Y]	The Y coordinate of start point.
[START_Y_WCS]	The Y coordinate of start point in World Coordinates.
[START_Z]	The Z coordinate of start point.
[START_Z_WCS]	The Z coordinate of start point in World Coordinates.
[STEP_NEXT_X]	

[STEP_NEXT_Y]	
[STEP_NEXT_Z]	
[STEP_START_DEPTH]	
[STOCK_LENGTH_X]	
[STOCK_LENGTH_Y]	
[STOCK_LENGTH_Z]	
[STOCK_MAX_X]	UNDEFINED is output if there is
[STOCK_MAX_Y]	no stock defined when posting
[STOCK_MAX_Z]	occurs.
[STOCK_MIN_X]	
[STOCK_MIN_Y]	
[STOCK_MIN_Z]	
[STOP_CHAR]	The program end character.
[TEMPERATURE]	
[TEMPERATURE_BED_SET_CODE]	
[TEMPERATURE_BED_WAIT_CODE]	
[TEMPERATURE_EXTRUDER_SET_CODE]	
[TEMPERATURE_EXTRUDER_WAIT_CODE]	
[TEMPERATURE_SET_BLK]	
[TEMPERATURE_SET_CODE]	
[TEMPERATURE_WAIT_BLK]	
[TEMPERATURE_BED_WAIT_CODE]	
[THREAD_ANGLE]	
[THREAD_DEPTH]	
[THREAD_DIR]	
[THREAD_FINISH_NUMCUTS]	
[THREAD_FINISH_STOCK]	
[THREAD_FINISH_Z]	
[THREAD_FIRST_DEPTH]	
[THREAD_INFEED_TYPE]	

[THREAD_LENGTH]	
[THREAD_MAJOR_DIR]	
[THREAD_MIN_DEPTH]	
[THREAD_MINOR_DIA]	
[THREAD_PITCH]	
[THREAD_PULL_OUT_DIST]	The pull out value is specified under G76 parameters in threading mop in turning.
[THREAD_TAPER]	
[TIME_STAMP]	
[TOOL_ADJ_REG]	Tool Adjust Register number.
[TOOL_CHG_PT_X]	
[TOOL_CHG_PT_Y]	
[TOOL_CHG_PT_Z]	
[TOOL_CUTCOM_REG]	
[TOOL_DIA]	Tool Diameter.
[TOOL_LENGTH]	Tool length.
[TOOL_NAME]	
[TOOL_NUM]	Tool number.
[TOOL_NUM_FLUTES]	
[TOOL_RAD]	Tool Radius.
[TOOL_ZOFFSET]	
[TOOLPATH_MAX_X]	
[TOOLPATH_MAX_Y]	
[TOOLPATH_MAX_Z]	
[TOOLPATH_MIN_X]	
[TOOLPATH_MIN_Y]	
[TOOLPATH_MIN_Z]	

[VMPFILE_NAME]	
[WMPFILE_NAME_LONG]	
[WORK_OFFSET_CODE]	
[WORK_OFFSET_NUM]	
[WORK_OFFSET_PREFIX]	
[ZFEEDRATE]	
INV_TIME_FEEDRATE_FLAG	

Variables

The variables that can be used are listed in the table below.

The variables that start with "CYCL_" are used only for the cycles commands.

Variable	Comments
[ABS_ANGLE]	
[ABS_ANGLE_SECONDARY]	
[ANGLE]	
[ANGLE_PITCH]	
[ANGLE_ROLL]	
[ANGLE_SECONDARY]	
[ANGLE_YAW]	
[APPROACH_FEED]	
[CENTER_X]	
[CENTER_Y]	
[CENTER_Z]	
[CIR_PLANE]	
[COMMENT]	Output comments.
[COOLANT_CODE_INSERT]	
[COOLANT_OFF]	
[CURR_X]	The X coordinate of current point.

[CURR_X_WCS]	The X coordinate of current point in
[cont_x_wes]	World Coordinates
[CURR_Y]	The Y coordinate of current point.
[CURR_Y_WCS]	The Y coordinate of current point in World Coordinates
[CURR_Z]	The Z coordinate of current point.
[CURR_Z_WCS]	The Z coordinate of current point in World Coordinates
[CUT_FEED]	
[CUT_MOTION_END_BLK]	
[CUT_MOTION_START_BLK]	
[CYCL_1/TPI]	1/TPI (only for TAP cycle)
[CYCL_CLEAR+DEPTH]	Drill Depth + Clear. (only for cycles except C-SINK)
[CYCL_CLEAR+INCR]	
[CYCL_CLEAR]	Clearance. (only for cycles)
[CYCL_CSINK_DEPTH+CLEAR]	Drill Depth + Clear. (only for C-SINK cycle)
[CYCL_CSINK_DEPTH]	Drill Depth. (only for C-Sink cycle)
[CYCL_DEPTH]	Drill Depth. (only for cycles except C-SINK)
[CYCL_DWELL]	Dwell. (only for cycles)
[CYCL_INCR]	Step Increment. (only for cycles)
[CYCL_IPM]	IPM. (only for cycles except TAP)
[CYCL_IPR]	IPR. (only for TAP cycle)
[CYCL_NEG_CLEAR+DEPTH]	-(Drill Depth + Clear). (only for cycles except C-SINK)
[CYCLE_NUM_STEPS]	
[CYCL_ORIENT]	Orient. (only for cycles)
[CYCL_SCALED_DWELL]	Dwell * Scale Factor (only for cycles)
[CYCL_TPI]	
[CYCLE_Z]	This variable stores the Z value of drill points.

[CYCL_Z+CLEAR]	Next Z + Clearance. (only for cycles)	
[CYCL_Z+DEPTH+CLEAR]	Next Z + Depth + Clearance. (only for cycles)	
[CYCL_Z+DEPTH]	Next Z + Depth. (only for cycles)	
[CYCL_Z-DEPTH]	Next Z - Depth. (only for cycles)	
[DELIMITER]	<u>Delimiter</u> definition.	
[DEPART_FEED]	Outputs the Departure feedrate value for the currently operation.	
[ENGAGE_FEED]	Outputs the Engage feedrate value for the currently operation.	
[EOB]	The end of block character.	
[EXTRUSION]		
[EXTRUSION_BLK]		
[EXTRUSION_CODE]		
[FEEDRATE]	FeedRate Value.	
[FEEDRATE_BLK]	FeedRate Block.	
[FEEDRATE_CODE]	Outputs the Feedrate code	
[FEEDRATE_UNITS_CODE]	Outputs the Feedrate Units code	
[FIRST_TOOL_NUM]		
[G_CODE]	The next G-Code. This is translated to linear, rapid, arc or cycle G-Code.	
[HELIX_ANGLE]		
[HELIX_CCW_ARC]		
[HELIX_CW_ARC]		
[HELIX_LEAD]		
[HELIX_NUM_REV]		
[HELIX_RADIUS]		
[HELIX_TOTAL_DEPTH]		
[INPUTFILE_NAME]		
[INPUTFILE_NAME_LONG]		
[INV_TIME_FEEDRATE_OFF]		

[INV_TIME_FEEDRATE_ON]	
[LINEAR]	The <u>linear motion code</u> .
[MOP_NAME]	
[NEXT_ABS_X_WCS]	The next absolute X coordinate point in World Coordinates.
[NEXT_ABS_Y_WCS]	The next absolute Y coordinate point in World Coordinates.
[NEXT_ABS_Z_WCS]	The next absolute Z coordinate point in World Coordinates.
[NEXT_I]	
[NEXT_J]	
[NEXT_K]	
[NEXT_NONMDL_E]	
[NEXT_NONMDL_I]	
[NEXT_NONMDL_J]	
[NEXT_NONMDL_K]	
[NEXT_NONMDL_L]	
[NEXT_NONMDL_R]	
[NEXT_NONMDL_X]	The next non-modal X coordinate point in local Machine Coordinates.
[NEXT_NONMDL_X_WCS]	The next non-modal X coordinate point in World Coordinates.
[NEXT_NONMDL_Y]	The next non-modal Y coordinate point in local Machine Coordinates.
[NEXT_NONMDL_Y_WCS]	The next non-modal Y coordinate point in World Coordinates.
[NEXT_NONMDL_Z]	The next non-modal Z coordinate point in local Machine Coordinates.
[NEXT_NONMDL_Z_WCS]	The next non-modal Z coordinate point in World Coordinates.
[NEXT_R]	
[NEXT_TOOL_NAME]	
[NEXT_TOOL_NUM]	

[NEXT_X]	The next X coordinate point in Machine Coordinates.
[NEXT_X_WCS]	The next X coordinate point in World Coordinates.
[NEXT_Y]	The next Y coordinate point in Machine Coordinates.
[NEXT_Y_WCS]	The next Y coordinate point in World Coordinates.
[NEXT_Z]	The next Z coordinate point in Machine Coordinates.
[NEXT_Z_WCS]	The next Z coordinate point in World Coordinates.
[OUTPUTE_MODE_CODE]	
[OUTPUT_UNITS_CODE]	English or Metric outputs code.
[OUTPUTFILE_NAME]	
[OUTPUT_FILENAME_LONG]	
[PARTNAME]	
[PARTNUM]	
[PLUNGE_FEED]	
[POST_NAME]	
[POST_NAME_LONG]	
[PREV_TOOL_ADJST_REG]	
[PREV_TOOL_CUTCOM_REG]	
[PREV_TOOL_NUM]	
[PREV_TOOL_NUM_FLUTES]	
[PREV_TOOL_ZOFFSET]	
[RAPID]	The <u>rapid motion code</u> .
[RAPID_FEED]	
[RETRACT_FEED]	
[ROTATION_AXIS]	
[ROTATION_AXIS_SECONDARY]	

[
[ROTATION_DIR]	
[ROTATION_DIR_SECONDARY]	
[ROTATION_FEEDVALUE]	
[ROTATION_MODE]	
[SEQ_PRECHAR]	Letter that is <u>prefixed</u> before the sequence number
[RT_NXT_X]	The next X coordinate. (Modal)
[RT_NXT_Y]	The next Y coordinate. (Modal)
[RT_NXT_Z]	The next Z coordinate. (Modal)
[RT_NXT_NONMDL_X]	The next X coordinate. (NonModal)
[RT_NXT_NONMDL_Y]	The next Y coordinate. (NonModal)
[RT_NXT_NONMDL_Z]	The next Z coordinate. (NonModal)
[SEQNUM]	The actual sequence number.
[SPINDLE_ARC]	Spindle direction.
[SPINDLE_BLK]	Spindle Block.
[SPINDLE_CODE]	
[SPINDLE_SPD]	Spindle speed.
[SPINDLE_SPD_MAX]	
[SPINDLE_SPD_TYPE]	
[SPIRAL_ANGLE]	
[SPIRAL_CCW_ARC]	
[SPIRAL_CW_ARC]	
[SPIRAL_END_RADIUS]	
[SPIRAL_LEAD]	
[SPIRAL_NUM_REV]	
[SPIRAL_START_RADIUS]	
[SPIRAL_TOTAL_LENGTH]	
[START_CHAR]	The program start character.
[START_POSITION_X]	
	I .

[START_POSITION_Y]	
[START_POSITION_Z]	
[START_X]	The X coordinate of start point.
[START_X_WCS]	The X coordinate of start point in World Coordinates.
[START_Y]	The Y coordinate of start point.
[START_Y_WCS]	The Y coordinate of start point in World Coordinates.
[START_Z]	The Z coordinate of start point.
[START_Z_WCS]	The Z coordinate of start point in World Coordinates.
[STEP_NEXT_X]	
[STEP_NEXT_Y]	
[STEP_NEXT_Z]	
[STEP_START_DEPTH]	
[STOCK_LENGTH_X]	
[STOCK_LENGTH_Y]	
[STOCK_LENGTH_Z]	
[STOCK_MAX_X]	UNDEFINED is output if there is
[STOCK_MAX_Y]	no stock defined when posting
[STOCK_MAX_Z]	occurs.
[STOCK_MIN_X]	
[STOCK_MIN_Y]	
[STOCK_MIN_Z]	
[STOP_CHAR]	The program end character.
[TEMPERATURE]	
[TEMPERATURE_BED_SET_CODE]	
[TEMPERATURE_BED_WAIT_CODE]	
[TEMPERATURE_EXTRUDER_SET_CODE]	
[TEMPERATURE_EXTRUDER_WAIT_CODE]	
[TEMPERATURE_SET_BLK]	
[TEMPERATURE_SET_CODE]	
[TEMPERATURE_WAIT_BLK]	

[TEMPERATURE_BED_WAIT_CODE]	
[THREAD_ANGLE]	
[THREAD_DEPTH]	
[THREAD_DIR]	
[THREAD_FINISH_NUMCUTS]	
[THREAD_FINISH_STOCK]	
[THREAD_FINISH_Z]	
[THREAD_FIRST_DEPTH]	
[THREAD_INFEED_TYPE]	
[THREAD_LENGTH]	
[THREAD_MAJOR_DIR]	
[THREAD_MIN_DEPTH]	
[THREAD_MINOR_DIA]	
[THREAD_PITCH]	
[THREAD_PULL_OUT_DIST]	The pull out value is specified under G76 parameters in threading mop in turning.
[THREAD_TAPER]	
[TIME_STAMP]	
[TOOL_ADJ_REG]	Tool Adjust Register number.
[TOOL_CHG_PT_X]	
[TOOL_CHG_PT_Y]	
[TOOL_CHG_PT_Z]	
[TOOL_CUTCOM_REG]	
[TOOL_DIA]	Tool Diameter.
[TOOL_LENGTH]	Tool length.
[TOOL_NAME]	
[TOOL_NUM]	Tool number.

[TOOL_NUM_FLUTES]	
[TOOL_RAD]	Tool Radius.
[TOOL_ZOFFSET]	
[VMPFILE_NAME]	
[WMPFILE_NAME_LONG]	
[WORK_OFFSET_NUM]	
[WORK_OFFSET_PREFIX]	
[ZFEEDRATE]	
INV_TIME_FEEDRATE_FLAG	

Related Topics

Other PPG Editor Sections:

General

Start/End

Tool Change

Setup

Spindle

Feed Rate

Motion

<u>Circle</u>

Helical/Spiral Cycles

Multi Axis Motion

Cutter Compensation

Cut Motion Start/End

Cycles

Miscellaneous

12.1.5.3 Macros

12.1.5.3.1 Macros

The following is a list of the available macros in the RhinoCAM Post-Processor generator.

StartEnd Tab

These macros are output before and after a tool path and therefore Runtime variables cannot be used.

Program Start up Code Program End Code

Tool Change Tab

These macros are output only when a tool is loaded or changed.

First Load Tool Macro Tool Change Macro

Cycles Tab

These macros are output only when the motion command is a cycle command.

Drill Code Deep Code Break Chip Code
Counter Sink Code Tap Code Bore [No Drag[Code Bore [Manual] Code Bore [Reverse] Code

12.1.5.3.2 How to edit Macros

This section describes the procedure for editing macros.

You can directly type the macro. With the exception of '[' and ']' characters as variables.

Usage of Variable List Dialog

You can also add variables directly in the following manner.

	Operation	Dialog to operate
1	Click the right mouse button on the required edit box	Main Editor
2	Variable List Dialog is displayed.	Variable List Dialog
3	Select the position.	Main Editor
4	Select the variable to add. (This procedure is for adding) Double click the left mouse button on the variable list and	Variable List Dialog
	the highlighted variable is added.	
5	Use the [Add] or [Undo] or [Undo All] buttons to perform the standard add and undo operations.	Variable List Dialog

Note: Multiple operations would require you to repeat steps 3 to 5.

12.1.6 Use Programmable Post

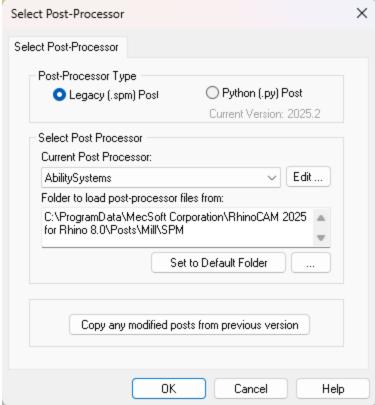
This documentation describes Programmable Post Processor and details on how create post scripts for it.

The Programmable Post Processor allows you to use Python script files for G-Code generation during toolpath processing by each MecSoft CAM plugin. You can create new post scripts or modify existing ones. Using the Python language for post scripts allows you to more efficiently generate the needed G-Code output allowing the use of programming elements, such as condition processing, loops, logical operations, and more.

12.1.6.1 Selecting a Programmable Post

Perform the following steps to use a programmable post-processor.

1. Select Use Programmable Post from Set Post-Processor Options dialog. When Use Programmable Post is selected the Python post scripts will be used for G-Code generation.



Dialog Box: Set Post-Processor Options

- 2. Select an available post script file or create a new one.
- 3. Press OK to save the options.

12.1.6.2 Writing Scrips

Script used in Programmable Post Processor uses Python programming language. That's why to execute it correctly, the script should have an appropriate code structure and format. As scripts written using Python programming language users can use its language features like loops, conditions, functions, etc. Also, all language restrictions applied to post scripts.

All post scripts should be placed in Post/[module_name]/PY folder, along with default.spm files. (The default.spm is only used for general post initialization).

The beginning of the file must contain the following line. It imports data types for event handling:

from post_ext import *

If you want to use the option Extension from Post-Processor then the variable GENERAL_OutputFileExt should be specified as follows:

GENERAL_OutputFileExt = ".nc"

12.1.6.3 Post Events

Programmable Post Processor has event driven architecture. Before outputting a specific block of G-code event is called. List of available events can be found at "Post event list" section.

User can specify output g-code block format on each event and Set/Get Global Post variables using objects from event parameters:

def OnEndProcessing(blockData: PostBlockData, globalData: PostGlobalData):
return

PostBlockData object used to get or set G-Code block format for called event. Some block formats can contain multiple lines. For these cases each line should be separated by '\n' symbol (user can use .splitlines() and .join functions from python to process them).

PostBlockData	
Methods	Description
Set(string)	Set block format string
Get()	Get block format string

Example of modification block output format:

```
def OnRapidMotion(blockData: PostBlockData, globalData: PostGlobalData):
    data = blockData.Get()
    data = data + " - Modified by OnRapidMotion"
    blockData.Set(data)
    return
```

To access global(system) post variables user can use PostGlobalData object, list of variables can be found at "Post variable list" section

PostGlobalData Object Methods	
Methods	Description
GetIntVar(string)	Get variable value as Int
GetFloatVar(string)	Get variable value as float
GetStrVar(string)	Get variable value as string
SetIntVar(string, value)	Set int value for variable
SetFloatVar(string, value)	Set float value for variable
SetStrVar(string, value)	Set string value for variable

Example of modification of variable from variable list:

```
def OnRapidMotion(blockData: PostBlockData, globalData: PostGlobalData):
    nextX = float(globalData.GetStrVar("[NEXT_NONMDL_X]")) # e.g. converting to float by using
Python
    nextX = nextX + 1.3
    globalData.SetFloatVar("[NEXT_NONMDL_X]", nextX)
    return
```

12.1.6.4 Post Event List

Post Event List	
Event	Description
OnStartProcessing(blockData: PostBlockData, globalData: PostGlobalData)	Starting post processing event
OnEndProcessing(blockData: PostBlockData, globalData: PostGlobalData)	End post processing event
OnMOpStart(globalData: PostGlobalData)	Starting processing Mop
OnMOpEnd(globalData: PostGlobalData)	Finished generating G-Code for Mop
OnComment(blockData: PostBlockData, globalData: PostGlobalData)	Processing comment output
OnSetup(blockData: PostBlockData, globalData: PostGlobalData)	Processing Mop Setup output

OnWorkZero(blockData: PostBlockData, globalData: PostGlobalData)	Processing Work Zero Mop output
OnToolChange(blockData: PostBlockData, globalData: PostGlobalData)	Changing tool output
OnSpindleSpeed(blockData: PostBlockData, globalData: PostGlobalData)	Processing Spindle Speed output
OnFeedRate(blockData: PostBlockData, globalData: PostGlobalData)	Processing Feed Rate output
OnToolCompensation(blockData: PostBlockData, globalData: PostGlobalData)	Processing Tool Compensation output
OnCoolant(blockData: PostBlockData, globalData: PostGlobalData)	Processing coolant output
OnRapidMotion(blockData: PostBlockData, globalData: PostGlobalData)	Processing Rapid Motion output
OnLinearMotion(blockData: PostBlockData, globalData: PostGlobalData)	Processing Linear Motion output
OnCirclularMotion(blockData: PostBlockData, globalData: PostGlobalData)	Processing Circular Motion output
OnSpiralMotion(blockData: PostBlockData, globalData: PostGlobalData)	Processing Spiral Motion output
OnHelicalMotion(blockData: PostBlockData, globalData: PostGlobalData)	Processing Helical Motion output
On4AxisRapidMotion(blockData: PostBlockData, globalData: PostGlobalData)	Processing Rapid Motion output for 4Axis machine
On4AxLinearMotion(blockData: PostBlockData, globalData: PostGlobalData)	Processing Linear Motion output for 4Axis machine
On5AxRapidMotion(blockData: PostBlockData, globalData: PostGlobalData)	Processing Rapid Motion output for 5Axis machine
On5AxLinearMotion(blockData: PostBlockData, globalData: PostGlobalData)	Processing Linear Motion output for 5Axis machine
OnCycleStart(blockData: PostBlockData, globalData: PostGlobalData)	Starting processing cycles
OnCyclePoint(blockData: PostBlockData, globalData: PostGlobalData)	Processing cycle point output
OnCycleEnd(globalData: PostGlobalData)	Ending processing cycles
OnDwell(blockData: PostBlockData, globalData: PostGlobalData)	Processing Dwell output

OnRotateHead(blockData: PostBlockData, globalData: PostGlobalData)	Processing Rotate head output
OnRotateTable(blockData: PostBlockData, globalData: PostGlobalData)	Processing Rotate table output
OnMachineRewind(blockData: PostBlockData, globalData: PostGlobalData)	

12.1.6.5 Post Variables List

Post Variables List		
Variable	Description	
[ABS_ANGLE]		
[ABS_ANGLE_SECONDARY]		
[ANGLE]		
[ANGLE_SECONDARY]		
[APPROACH_FEED]		
[CENTER_X]		
[CENTER_Y]		
[CENTER_Z]		
[CIR_PLANE]		
[COMMENT]	Output comments.	
[CURR_X]	The X coordinate of current point.	
[CURR_X_WCS]	The X coordinate of current point in World Coordinates	
[CURR_Y]	The Y coordinate of current point.	
[CURR_Y_WCS]	The Y coordinate of current point in World Coordinates	
[CURR_Z]	The Z coordinate of current point.	
[CURR_Z_WCS]	The Z coordinate of current point in World Coordinates	
[CUT_FEED]		
[CYCL_1/TPI]	1/TPI (only for TAP cycle)	

[CYCL_CLEAR+DEPTH]	Drill Depth + Clear. (only for cycles except C-SINK)
[CYCL_CLEAR+INCR]	
[CYCL_CLEAR]	Clearance. (only for cycles)
[CYCL_CSINK_DEPTH+CLEAR]	Drill Depth + Clear. (only for C-SINK cycle)
[CYCL_CSINK_DEPTH]	Drill Depth. (only for C-Sink cycle)
[CYCL_DEPTH]	Drill Depth. (only for cycles except C-SINK)
[CYCL_DWELL]	Dwell. (only for cycles)
[CYCL_INCR]	Step Increment. (only for cycles)
[CYCL_IPM]	IPM. (only for cycles except TAP)
[CYCL_IPR]	IPR. (only for TAP cycle)
[CYCL_NEG_CLEAR+DEPTH]	-(Drill Depth + Clear). (only for cycles except C-SINK)
[CYCLE_NUM_STEPS]	
[CYCL_ORIENT]	Orient. (only for cycles)
[CYCL_SCALED_DWELL]	Dwell * Scale Factor (only for cycles)
[CYCL_TPI]	
[CYCL_Z+CLEAR]	Next Z + Clearance. (only for cycles)
[CYCL_Z+DEPTH+CLEAR]	Next Z + Depth + Clearance. (only for cycles)
[CYCL_Z+DEPTH]	Next Z + Depth. (only for cycles)
[CYCL_Z-DEPTH]	Next Z - Depth. (only for cycles)
[DELIMITER]	Delimiter definition.
[DEPART_FEED]	Outputs the Departure feedrate value for the currently operation.
[ENGAGE_FEED]	Outputs the Engage feedrate value for the currently operation.
[EOB]	The end of block character.
[EXTRUSION]	
[EXTRUSION_BLK]	
[EXTRUSION_CODE]	
[FEEDRATE]	FeedRate Value.
[FEEDRATE_BLK]	FeedRate Block.
	The state of the s

[FEEDRATE_CODE]	Outputs the Feedrate code
[FEEDRATE_UNITS_CODE]	Outputs the Feedrate Units code
[FIRST_TOOL_NUM]	
[G_CODE]	The next G-Code. This is translated to linear, rapid, arc or cycle G-Code.
[HELIX_ANGLE]	
[HELIX_CCW_ARC]	
[HELIX_CW_ARC]	
[HELIX_LEAD]	
[HELIX_NUM_REV]	
[HELIX_RADIUS]	
[HELIX_TOTAL_DEPTH]	
[INPUTFILE_NAME]	
[INPUTFILE_NAME_LONG]	
[INV_TIME_FEEDRATE_OFF]	
[INV_TIME_FEEDRATE_ON]	
[LINEAR]	The linear motion code.
[MAXZ]	
[MINZ]	
[MOP_NAME]	
[NEXT_ABS_X_WCS]	The next absolute X coordinate point in World Coordinates.
[NEXT_ABS_Y_WCS]	The next absolute Y coordinate point in World Coordinates.
[NEXT_ABS_Z_WCS]	The next absolute Z coordinate point in World Coordinates.
[NEXT_I]	
[NEXT_J]	
[NEXT_K]	
[NEXT_NONMDL_E]	
[NEXT_NONMDL_I]	
[NEXT_NONMDL_J]	
	1

[NEXT_NONMDL_K]	
[NEXT_NONMDL_L]	
[NEXT_NONMDL_R]	
[NEXT_NONMDL_X]	The next non-modal X coordinate point in local Machine Coordinates.
[NEXT_NONMDL_X_WCS]	The next non-modal X coordinate point in World Coordinates.
[NEXT_NONMDL_Y]	The next non-modal Y coordinate point in local Machine Coordinates.
[NEXT_NONMDL_Y_WCS]	The next non-modal Y coordinate point in World Coordinates.
[NEXT_NONMDL_Z]	The next non-modal Z coordinate point in local Machine Coordinates.
[NEXT_NONMDL_Z_WCS]	The next non-modal Z coordinate point in World Coordinates.
[NEXT_R]	
[NEXT_TOOL_NAME]	
[NEXT_TOOL_NUM]	
[NEXT_X]	The next X coordinate point in Machine Coordinates.
[NEXT_X_WCS]	The next X coordinate point in World Coordinates.
[NEXT_Y]	The next Y coordinate point in Machine Coordinates.
[NEXT_Y_WCS]	The next Y coordinate point in World Coordinates.
[NEXT_Z]	The next Z coordinate point in Machine Coordinates.
[NEXT_Z_WCS]	The next Z coordinate point in World Coordinates.
[OUTPUTE_MODE_CODE]	
[OUTPUT_UNITS_CODE]	English or Metric outputs code.
[OUTPUTFILE_NAME]	
[OUTPUT_FILENAME_LONG]	
[PARTNAME]	

[PARTNUM]	
[PLUNGE_FEED]	
[POST_NAME]	
[POST_NAME_LONG]	
[PREV_TOOL_ADJST_REG]	
[PREV_TOOL_CUTCOM_REG]	
[PREV_TOOL_NUM]	
[PREV_TOOL_NUM_FLUTES]	
[PREV_TOOL_ZOFFSET]	
[RAPID]	The rapid motion code.
[RAPID_FEED]	
[RETRACT_FEED]	
[ROTATION_AXIS]	
[ROTATION_AXIS_SECONDARY]	
[ROTATION_DIR]	
[ROTATION_DIR_SECONDARY]	
[ROTATION_FEEDVALUE]	
[ROTATION_MODE]	
[RT_NXT_X]	The next X coordinate. (Modal)
[RT_NXT_Y]	The next Y coordinate. (Modal)
[RT_NXT_Z]	The next Z coordinate. (Modal)
[RT_NXT_NONMDL_X]	The next X coordinate. (NonModal)
[RT_NXT_NONMDL_Y]	The next Y coordinate. (NonModal)
[RT_NXT_NONMDL_Z]	The next Z coordinate. (NonModal)
[SEQ_PRECHAR]	Letter that is prefixed before the sequence number
[SEQNUM]	The actual sequence number.
[SPINDLE_ARC]	Spindle direction.
[SPINDLE_BLK]	Spindle Block.
[SPINDLE_CODE]	
[SPINDLE_SPD]	Spindle speed.

[SPINDLE_SPD_MAX]	
[SPINDLE_SPD_TYPE]	
[SPIRAL_ANGLE]	
[SPIRAL_CCW_ARC]	
[SPIRAL_CW_ARC]	
[SPIRAL_END_RADIUS]	
[SPIRAL_LEAD]	
[SPIRAL_NUM_REV]	
[SPIRAL_START_RADIUS]	
[SPIRAL_TOTAL_LENGTH]	
[START_CHAR]	The program start character.
[START_POSITION_X]	
[START_POSITION_Y]	
[START_POSITION_Z]	
[START_X]	The X coordinate of start point.
[START_X_WCS]	The X coordinate of start point in World Coordinates.
[START_Y]	The Y coordinate of start point.
[START_Y_WCS]	The Y coordinate of start point in World Coordinates.
[START_Z]	The Z coordinate of start point.
[START_Z_WCS]	The Z coordinate of start point in World Coordinates.
[STEP_NEXT_X]	
[STEP_NEXT_Y]	
[STEP_NEXT_Z]	
[STEP_START_DEPTH]	
[STOCK_LENGTH_X]	UNDEFINED is output if there is no stock defined when posting occurs.
[STOCK_LENGTH_Y]	
[STOCK_LENGTH_Z]	
[STOCK_MAX_X]	

[STOCK_MAX_Y]	
[STOCK_MAX_Z]	
[STOCK_MIN_X]	
[STOCK_MIN_Y]	
[STOCK_MIN_Z]	
[STOP_CHAR]	The program end character.
[TEMPERATURE]	
[TEMPERATURE_BED_SET_CODE]	
[TEMPERATURE_BED_WAIT_CODE]	
[TEMPERATURE_EXTRUDER_SET_CODE]	
[TEMPERATURE_EXTRUDER_WAIT_CODE]	
[TEMPERATURE_SET_BLK]	
[TEMPERATURE_SET_CODE]	
[TEMPERATURE_WAIT_BLK]	
[TEMPERATURE_BED_WAIT_CODE]	
[THREAD_ANGLE]	
[THREAD_DEPTH]	
[THREAD_DIR]	
[THREAD_FINISH_NUMCUTS]	
[THREAD_FINISH_STOCK]	
[THREAD_FINISH_Z]	
[THREAD_FIRST_DEPTH]	
[THREAD_INFEED_TYPE]	
[THREAD_LENGTH]	
[THREAD_MAJOR_DIR]	
[THREAD_MIN_DEPTH]	
[THREAD_MINOR_DIA]	
[THREAD_PITCH]	
[THREAD_PULL_OUT_DIST]	The pull out value is specified under G76 parameters in threading mop in turning.
[THREAD_TAPER]	
	I .

Tool Adjust Register number.	
Tool Diameter.	
Tool length.	
Tool number.	
Tool Radius.	

12.1.6.6 Example Script

Here is an example Python post script, (PostScriptExample.py), for a programmable post-processor which sets following data:

- Linear/Rapid motion format
- Start/End block format
- Setting "[SEQ_PRECHAR]" variable
- Tool Change block format (different for fist tool change)
- File extension for "File Extension from Post Processor" option

from post_ext import *

Set output file extension

```
GENERAL OutputFileExt = ".nc"
# Define block format for outputten code
LinearMotionCodeBlock = "[G CODE][DELIMITER][NEXT X][DELIMITER][NEXT Y][DELIMITER]
[NEXT_Z]"
RapidMotionCodeBlock = "[G_CODE][DELIMITER][NEXT_Z]\n[NEXT_X][DELIMITER][NEXT_Y]"
StartProcessingBlock = "[START_CHAR]\n[SEQ_PRECHAR][SEQNUM][DELIMITER]G40[DELIMITER]
G49[DELIMITER]G80[DELIMITER]G98 - Start processing"
EndProcessingBlock = "[SEQ_PRECHAR][SEQNUM][DELIMITER]M30\n[STOP_CHAR] - End
processing"
FirstToolChangeCodeBlock = ("; First Tool Change\n"
"[SEQ_PRECHAR][SEQNUM][DELIMITER][OUTPUT_UNITS_CODE][DELIMITER]T[TOOL_NUM]
[DELIMITER]M06",
"[SEQ_PRECHAR][SEQNUM][SPINDLE_BLK]",
"[SEQ_PRECHAR][SEQNUM][DELIMITER][OUTPUT_MODE_CODE][DELIMITER][G_CODE][DELIMITER]
X[NEXT_NONMDL_X][DELIMITER]Y[NEXT_NONMDL_Y]",
"[SEQ_PRECHAR][SEQNUM][DELIMITER]G43[DELIMITER]Z[NEXT_NONMDL_Z][DELIMITER]
H[TOOL ADJST REG]")
ToolChangeCodeBlock = ("[SEQ_PRECHAR][SEQNUM][DELIMITER][OUTPUT_UNITS_CODE]
[DELIMITER]T[TOOL_NUM][DELIMITER]M06",
"[SEQ_PRECHAR][SEQNUM][SPINDLE_BLK]",
"[SEQ PRECHAR][SEQNUM][DELIMITER][OUTPUT MODE CODE][DELIMITER][G CODE][DELIMITER]
X[NEXT_NONMDL_X][DELIMITER]Y[NEXT_NONMDL_Y]",
"[SEQ_PRECHAR][SEQNUM][DELIMITER]G43[DELIMITER]Z[NEXT_NONMDL_Z][DELIMITER]
H[TOOL ADJST REG]")
# Global vars for processing
ToolChangeNum = 0
# Helper functions
def SetBlockData(blockData: PostBlockData, value):
 block = '\n'
```

```
if type(value) == tuple:
   block = block.join(value)
 else:
   value = value.splitlines()
   block = block.join(value)
 blockData.Set(block)
# Set post vars
def InitializeVars(globalData: PostGlobalData):
 globalData.SetStrVar("[SEQ_PRECHAR]", "#")
def OnStartProcessing(blockData: PostBlockData, globalData: PostGlobalData):
 InitializeVars(globalData)
 SetBlockData(blockData, StartProcessingBlock)
 return
def OnEndProcessing(blockData: PostBlockData, globalData: PostGlobalData):
 SetBlockData(blockData, EndProcessingBlock)
 return
def OnMOpStart(globalData: PostGlobalData):
 return
def OnMOpEnd(globalData: PostGlobalData):
 return
def OnComment(blockData: PostBlockData, globalData: PostGlobalData):
 return
def OnSetup(blockData: PostBlockData, globalData: PostGlobalData):
 return
```

```
def OnWorkZero(blockData: PostBlockData, globalData: PostGlobalData):
 return
def OnToolChange(blockData: PostBlockData, globalData: PostGlobalData):
 global ToolChangeNum
 if ToolChangeNum == 0:
  SetBlockData(blockData, FirstToolChangeCodeBlock) # 1st tool change
 else:
  SetBlockData(blockData, ToolChangeCodeBlock)
 ToolChangeNum = ToolChangeNum + 1
 return
def OnSpindleSpeed(blockData: PostBlockData, globalData: PostGlobalData):
 return
def OnFeedRate(blockData: PostBlockData, globalData: PostGlobalData):
 return
def OnToolCompensation(blockData: PostBlockData, globalData: PostGlobalData):
 return
def OnCoolant(blockData: PostBlockData, globalData: PostGlobalData):
 return
def OnRapidMotion(blockData: PostBlockData, globalData: PostGlobalData):
 SetBlockData(blockData, RapidMotionCodeBlock)
 return
def OnLinearMotion(blockData: PostBlockData, globalData: PostGlobalData):
 SetBlockData(blockData, LinearMotionCodeBlock)
 return
```

```
def OnCirclularMotion(blockData: PostBlockData, globalData: PostGlobalData):
 return
def OnSpiralMotion(blockData: PostBlockData, globalData: PostGlobalData):
 return
def OnHelicalMotion(blockData: PostBlockData, globalData: PostGlobalData):
 return
def On4AxisRapidMotion(blockData: PostBlockData, globalData: PostGlobalData):
 SetBlockData(blockData, RapidMotionCodeBlock)
 return
def On4AxLinearMotion(blockData: PostBlockData, globalData: PostGlobalData):
 SetBlockData(blockData, LinearMotionCodeBlock)
 return
def On5AxRapidMotion(blockData: PostBlockData, globalData: PostGlobalData):
 return
def On5AxLinearMotion(blockData: PostBlockData, globalData: PostGlobalData):
 return
def OnCycleStart(blockData: PostBlockData, globalData: PostGlobalData):
 return
def OnCyclePoint(blockData: PostBlockData, globalData: PostGlobalData):
 return
def OnCycleEnd(globalData: PostGlobalData):
 return
```

```
def OnDwell(blockData: PostBlockData, globalData: PostGlobalData):
    return

def OnRotateHead(blockData: PostBlockData, globalData: PostGlobalData):
    return

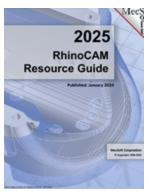
def OnRotateTable(blockData: PostBlockData, globalData: PostGlobalData):
    return

def OnMachineRewind(blockData: PostBlockData, globalData: PostGlobalData):
    return
```

12.1.7 Find More Resources

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The 2024 RhinoCAM Resource Guide!

18 Pages

Lists PDF downloads and Online resources including Quick Start Guides, Reference Guides, Exercise Guides, Tutorials and More.

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Archiving Machining Operations

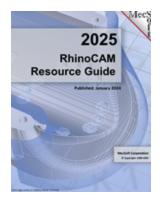
Once machining operations are created they can be archived along with the Rhino part (.3dm) file. This can be accomplished by simply saving the part file. When the part file is retrieved, all archived operations will be loaded along with the part file.

Another powerful way of using archived machining operations is to create operations and save them in a Knowledge Base. You then can load this Knowledge Base file to any part geometry. These machining operations can then be utilized to generate toolpaths to machine the newly loaded geometry. This is a powerful feature that allows you to use existing machining operations without having to recreate these operations in every new session of TURN module.

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Index

- A -

Algebraic Expressions 393

Align
Part Geometry 106
Stock Geometry 106
arc center [i,j,k] 426
arc motion block 426

Archiving Machining Operations 476

Avoid Sections 116, 175, 194, 211, 228, 244

- B -

block format 410 **Boring** Clearance Tab 322 Cut Parameters Tab 324 Feeds & Speeds Tab 318 Overview 314 Tool Tab 317 **Browsers** 44 Docking Machining (MOps) 29 Machining Objects (MObs) 36 Overview 29

- C -

CAM Preferences 45 **Cutting Tools** Feeds & Speeds 50 Geometry 46 Post 62 Stock 47 Toolpath 55 Circle 426 Clearance Plane Overview 150 Clone 349 Toolpaths Colors **Cutting Tool** 49 **Fixtures** 46

Regions 46 Stock 47 Surfaces 46 Toolpath 55 comments (o/p, start, end, seq) 410 comments on output 410 Compare Part/Stock 379 437 compensation 437 coolant code Copy & Paste Operations 347 **Cut Material Simulation** 375 **Cutter Compensation** 140, 393 **Cutting Tool Default Library** 49 Display 49 Cycles 435

- D -

Delete Dirty Operations (MOps) 355 **Delete Operations** 350 delimiter 410 Dirty Operations (MOps) Delete 355 357 Suppress Unsuppress 359 Drill Cycles & Indexed Machining 393 Drilling Clearance Tab 296 Cut Parameters Tab 298 Feeds & Speeds Tab 292 Tool Tab 291 Drilling (Hole Making) Operations Overview 76 **Drillings** Overview 288

- E -

Editing Machining Operations
Clone 349
Copy & Paste Operations 347
Delete Operations 350
Dirty Operations (MOps) 355
Editing Associatively 340
Information 360

Editing Machining Operations	Feeds & Speeds Tab 237
Overview 340	Finishing Parameters Tab 233
Properties 364	Global Parameters Tab 228
Rename Operations 352	Overview 227
Shop Documentation 361	Tool Tab 235
Suppress 354	Groove Roughing
Suppress Dirty Operations (MOps) 357	Clearance Geometry Tab 225
Toolpath Viewer 345	Entry/Exit Tab 217
•	Feeds & Speeds Tab 220
	Global Parameters Tab 211
Export Part to VCP 171	Overview 209
Stock to STL 102	Roughing Tab 215
<u></u>	Tool Tab 218
- F -	
•	- H -
Feed Rate 421	• •
feed rate value 421	Help
feedrate block 421	Find more Resources 477
Feeds & Speeds	Hole Making
Calculator (Load from File) 148, 185	Boring 314
Defaults 50	Drilling 288
Overview 141	Reverse Boring 327
Tracking Options 50	Tapping 301
file control 410	How to edit 458
file select dialog 406	How to care 400
Follow Curve	•
Clearance Geometry Tab 257	- -
Entry/Exit Tab 250	
Feeds & Speeds Tab 253	Information
Follow Curve Parameters Tab 249	About Operations 360
Global Parameters Tab 244	Introduction 389
Overview 243	
	_ K _
Tool Tab 251	- 17 -
format 426	K-Bases
	Tab 40
- G -	Knowledge Base
	Overview 155
Geometry 17, 85	Overview 133
How to Define 25	-
Orient 19	- L -
Overview 85	_
Part Geometry Types 17, 85	Legacy Post 405
Preferences 46	Library
Types Supported 17, 85	Default Tool 49
Groove Finishing	Licensing
Clearance Geometry Tab 241	Network 65
Entry/Exit Tab 234	linear motion block 424
LINIY/LAN LOI	

	in Simulations 377
RΛ	Toggle On/Off 29
- IVI -	Miscellaneous 437
Machine Control	Miscellaneous Operations
Dialog Box 163	Machine Control 163
Menu Item 163	MOp Set 162
Selext Machine Control Cycle 163	Overview 161
•	modal output 410
Machine Coordinate System (WCS) Toggle On/Off 29	mode 410
	MOp Set 162
Machine Setup Manual Definition 83	More Help 475
Tool Coordinate System 80	Motion 424
,	motion coordinates 424
Machining Align Part and Stock Models 106	motion order 424
3	
Archiving Operations 476 Clearance Plane 150	NI
	- 14 -
Creating 80, 85	Naturals Authorities Cettings CF
Creating Operations 80	Network Authentication Settings 65
Drilling (Hole Making) Operations 76	Network Licensing
Editing Operations 340	Network Authentication Settings 65
Feeds & Speeds 141	Proxy Server Settings 65
Knowledge Base 155	Settings 65
Machining Features 116	use LAN Daemon Settings 65
Miscellaneous Operations 161	
Operation Properties 364	- 0 -
Overview 68	•
Part Geometry 85	Orient Part 87
Preferences 52	Orient Part Geometry 19
Setup 105	
Stock Geometry 93	D
Tools 118	• P •
Tools and Utilities 166	Porting Off
Turning Operations 68	Parting Off Clearance Geometry Tab 285
Machining Browser (MOps)	Entry/Exit Tab 278
Overview 29	Feeds & Speeds Tab 281
Program tab 31	Overview 274
Simulate tab 33	Part Off Tab 276
Toggle Tabs 30	
Machining Features	
Avoid Sections 116, 175, 194, 211, 228, 244	plane 426
Overview 116	Post
Machining Objects (MObs) Browser	Default File Extension 62
K-Bases tab 40	File Naming Conventions 62
Overview 36	New File Extensions 62
Tools tab 36	Options Dialog 387
Macros 457	Preferences 62
main editor 407	Program to send posted files to 62
Material 108	Select 387

Post		sample output (spindle) 419
Send posted files to 387		Save As Defaults 167
Set File Extension 387		sequence number 410
Set Naming Conventions 387		Setup 105
Show Output Dialog when Post-Processing	62	Orient Part 87
Stock Transparency 62		Work Zero 110
Use Legacy 405		Shop Documentation 361
Post Process Generator		Simulate
Dialog 170		Cut Material 375
Post Processing		Machining Operations 368, 372
Overview 382		Material Texture 377
Preferences		Tab 33
Machining 52		Simulation
Simulation 57		Part/Stock Compare 379
User Interface 60		Preferences 57
Print Media Archive 15		Spindle 419
Program tab 31		spindle block 419
Programmable Post		spindle direction 419
About 458		spindle RPM 419
Event List 461		StartEnd 414
Example Script 470		STL
How to select 459		Export Stock to 102
Post Events 460		Stock
Variables List 463		Edge Display 47
Writing Scrips 459		Preferences 47
Proxy Server		Transparency 47
Enable 65		Stock Geometry
Password 65		Cylinder 93
Port Number 65		Delete 103
Proxy IP 65		Export as STL 102
Username 65		from Selection 101
Proxy Server Settings 65		Offset 97
, ,		Overview 93
D		Part Cylinder 96
- K -		Remove Simulations 104
Danama Oramatiana 250		Revolve 100
Rename Operations 352		Toggle On/Off 29
Reverse Boring		Suppress
Clearance Tab 335		Dirty Operations (MOps) 357
Cut Parameters Tab 336		Toolpaths (MOps) 354
Feeds & Speeds Tab 331		. , ,
Overview 327		T
Tool Tab 329		-T-
C		Tapping
- S -		Clearance Tab 309
		Cut Parameters Tab 311
sample output (feedrate) 421		Feeds & Speeds Tab 304
sample output (motion) 424		Overview 301

	FI- 8 CI- T-I- 000
Tapping	Feeds & Speeds Tab 202
Tool Tab 303	Finishing Parameters Tab 198
Threading	Global Parameters Tab 194
Clearance Geometry Tab 272	Overview 192
Feeds & Speeds Tab 268	Tool Tab 200
Overview 259	Turn Roughing
Thread Cut Parameters Tab 263	Clearance Geometry Tab 190
Thread Parameters Tab 261	Entry/Exit Tab 182
Tool Tab 266	Feeds & Speeds Tab 185
Tool Change Point 393	Global Parameters Tab 175
Tool Comments 393	Overview 173
ToolAxis 430	Roughing Options Tab 180
ToolChange 415	Tool Tab 183
Toolpath 55	Turning Operations
Colors 55	Follow Curve 243
Display 55	Groove Finishing 227
Preferences 55	Groove Roughing 209
Toggle On/Off 29	Overview 68
Viewer 345	Parting Off 274
Tools	Threading 259
Add Tool to Library 136	Turn Finishing 192
Animation 372	Turn Roughing 173
Create/Edit 118	rum Roughing 175
Cutter Compensation 140	- U -
List Tools 139	
Load Tool Library 135	units 410
Overview 118	Unsuppress
Save Tool Library 138	Dirty Operations (MOps) 359
Select Tools from Library 137	Toolpaths (MOps) 354
Tab 36	User Interface
Tools and Utilities	CAM Preferences 45
Export to VCP 171	Docking Browsers 44
Overview 166	K-Bases tab 40
Tools tab 36	Machining Browser (MOps) 29
TURN	Machining Objects (MObs) Browser 36
Coordinate System 16	Menu Item 28
Default View 16	Overview 28
Features 7	Preferences 60
How to Define Part Geometry 25	Program tab 31
Key Concepts 16	Simulate tab 33
Part Geometry Types 17, 85	
Post-Processing 12	Toggle Tabs 30 Tools tab 36
Understanding 8	
Welcome 7	TURN Browsers 29
Work-flow 10	Utilities
Turn Finishing	Post Process Generator 170
Clearance Geometry Tab 207	
Entry/Exit Tab 199	

- V -

variable list dialog 409 Variables 439 Videos & Guides 13

- W -

Welcome 7
Work Zero 110
World Coordinate System (WCS)
Toggle On/Off 29